

# Introduction to Infinite-Dimensional Lie Groups

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26.06.2023

Today: calculus in locally convex spaces

Wednesday and Thursday: Examples and theory of  
infinite-dimensional Lie groups

## §1 Locally convex spaces, weak integrals

It's not sufficient for our purposes to consider normed spaces  $(E, \|\cdot\|)$  or Banach spaces. Rather, consider locally convex topological vector spaces  $E$  whose topology comes from a set  $\Gamma$  of seminorms

$$q: E \rightarrow [0, \infty[, \quad x \mapsto q(x).$$

Thus  $q(tx) = |t|q(x)$  for all  $t \in \mathbb{R}$  and  $x \in E$ ; and

$$q(x + y) \leq q(x) + q(y) \quad \text{for all } x, y \in E.$$

For each  $x \in E \setminus \{0\}$ , we have  $q(x) > 0$  for some  $q \in \Gamma$ . We can assume that for all  $p, q \in \Gamma$ , the seminorm

$$x \mapsto \max\{p(x), q(x)\}$$

is in  $\Gamma$ .

A subset  $U \subseteq E$  is open if, for each  $x \in U$ , it contains the ball

$$B_\varepsilon^q(x) := \{y \in E : q(y - x) < \varepsilon\}$$

for some  $q \in \Gamma$  and some  $\varepsilon > 0$ .

**Example.** Every normed space is a locally convex space, notably

- (a) The set  $C(K, \mathbb{R})$  of continuous real-valued functions with the supremum norm  $\|\cdot\|_\infty$ ;
- (b) For  $k \in \mathbb{N}_0$  the space  $C^k([0, 1], \mathbb{R})$  of  $C^k$ -functions  $f: [0, 1] \rightarrow \mathbb{R}$ ,

$$\|f\|_{C^k} := \max_{j=0, \dots, k} \|f^{(j)}\|_\infty.$$

**Example.** The space  $C^\infty([0, 1], \mathbb{R})$  of smooth functions becomes a locally convex space if we use the seminorms  $\|\cdot\|_{C^k}$  for  $k \in \mathbb{N}_0$ .

### Definition

A sequence  $(x_n)_{n \in \mathbb{N}}$  in a locally convex space is called a **Cauchy sequence** if, for each 0-neighbourhood  $U \subseteq E$ , there exists  $N \in \mathbb{N}$  such that

$$x_m - x_n \in U \quad \text{for all } n, m \geq N.$$

If every Cauchy sequence in  $E$  is convergent, then  $E$  is called **sequentially complete**.

For example,  $C^k([0, 1], \mathbb{R})$  is sequentially complete for all  $k \in \mathbb{N}_0$  and also for  $k = \infty$ .

Consider  $a < b$  and a continuous function  $\gamma: [a, b] \rightarrow E$ .

### Definition

An element  $x \in E$  is called a *weak integral* for  $\gamma$  if

$$\lambda(x) = \int_a^b \lambda(\gamma(t)) dt$$

for each continuous linear functional  $\lambda: E \rightarrow \mathbb{R}$ .

If it exists, the weak integral is unique, as  $E'$  separates points on  $E$  by the Hahn-Banach Theorem. Write  $\int_a^b \gamma(t) dt := x$ ; thus

$$\lambda \left( \int_a^b \gamma(t) dt \right) = \int_a^b \lambda(\gamma(t)) dt$$

for all  $\lambda \in E'$ .

## Fact

If  $E$  is sequentially complete, then the weak integral  $\int_a^b \gamma(t) dt$  exists in  $E$  for each continuous function  $\gamma: [a, b] \rightarrow E$ .

For the proof, consider the Riemann sum

$$S(\gamma, Z) := \sum_{j=1}^k (t_j - t_{j-1}) \gamma(t_j)$$

for a subdivision  $Z = \{a = t_0 < t_1 < \dots < t_k = b\}$  of  $[a, b]$ , and

$$\Delta(Z) := \max_{j=1, \dots, k} (t_j - t_{j-1}).$$

Pick a sequence  $(Z_n)_{n \in \mathbb{N}}$  of subdivisions with  $\Delta(Z_n) \rightarrow 0$ . Since  $\gamma$  is uniformly continuous, see that  $(S(\gamma, Z_n))_{n \in \mathbb{N}}$  is a Cauchy sequence, hence convergent to some  $x \in E$ . Applying  $\lambda \in E'$ , get

$$\lambda(S(\gamma, Z_n)) = \sum_{j=1}^k (t_j - t_{j-1}) \lambda(\gamma(t_j)) = S(\lambda \circ \gamma, Z_n) \rightarrow \int_a^b (\lambda(\gamma(t))) dt$$

and thus  $\lambda(x) = \lim_{n \rightarrow \infty} \lambda(S(\gamma, Z_n)) = \int_a^b \lambda(\gamma(t)) dt$ .

## §2 $C^1$ -curves and the Fundamental Theorem of Calculus

Let  $E$  be a locally convex space.

### Definition

A continuous map  $\gamma: [a, b] \rightarrow E$  is called a  **$C^1$ -curve** if

$$\gamma'(t) := \lim_{s \rightarrow t} \frac{\gamma(s) - \gamma(t)}{s - t}$$

exists in  $E$  for each  $t \in [a, b]$  and  $\gamma': [a, b] \rightarrow E$  is continuous.

### Fundamental Theorem

If  $\gamma: [a, b] \rightarrow E$  is a  $C^1$ -curve, then

$$\gamma(b) - \gamma(a) = \int_a^b \gamma'(t) dt.$$

Notably, the weak integral exists.

**Proof.** For each continuous linear functional  $\lambda: E \rightarrow \mathbb{R}$ ,

the composition  $\lambda \circ \gamma: [a, b] \rightarrow \mathbb{R}$  is continuous and for  $t \in [a, b]$ , we have

$$\frac{\lambda(\gamma(s)) - \lambda(\gamma(t))}{s - t} = \lambda \left( \frac{\gamma(s) - \gamma(t)}{s - t} \right) \rightarrow \lambda(\gamma'(t)) \quad (*)$$

as  $s \rightarrow t$ , whence  $\lambda \circ \gamma: [a, b] \rightarrow \mathbb{R}$  is a  $C^1$ -function. Thus

$$\lambda(\gamma(b) - \gamma(a)) = \lambda(\gamma(b)) - \lambda(\gamma(a)) = \int_a^b (\lambda \circ \gamma)'(t) dt = \int_a^b \lambda(\gamma'(t)) dt,$$

using the Fundamental Theorem for the real-valued function  $\lambda \circ \gamma$  and then (\*). Hence  $\gamma(b) - \gamma(a)$  is the weak integral of  $\gamma'$ .



## §3 $C^1$ -maps between locally convex spaces

$E, F$             locally convex topological vector spaces

$U \subseteq E$             open

**Definition (Andrée Bastiani, 1964)**

A map  $f: U \rightarrow F$  is called **continuously differentiable** (or  $C^1$ ) if it is continuous, the directional derivatives

$$df(x, y) := (D_y f)(x) := \left. \frac{d}{dt} \right|_{t=0} f(x + ty) = \lim_{t \rightarrow 0} \frac{f(x + ty) - f(x)}{t}$$

exist for all  $x \in U$  and  $y \in E$ , and  $df: U \times E \rightarrow F$ ,  
 $(x, y) \mapsto df(x, y)$  is continuous.

**Example.** Every constant map  $f: E \rightarrow F$  is  $C^1$  with  $df(x, y) = 0$ .

**Example.** Every continuous linear map  $\alpha: E \rightarrow F$  is  $C^1$ , with  $d\alpha(x, y) = \alpha(y)$  for all  $x, y \in E$ .

In fact,  $\alpha(x + ty) = \alpha(x) + t\alpha(y)$  implies that

$$\frac{\alpha(x + ty) - \alpha(x)}{t} = \alpha(y) \rightarrow \alpha(y)$$

as  $t \rightarrow 0$ .

**Example.** Every continuous bilinear map  $\beta: E_1 \times E_2 \rightarrow F$  is  $C^1$ , with

$$d\beta((x_1, x_2), (y_1, y_2)) = \beta(y_1, x_2) + \beta(x_1, y_2)$$

for all  $x_1, y_1 \in E_1$  and  $x_2, y_2 \in E_2$ . In fact,

$$\beta(x_1 + ty_1, x_2 + ty_2) = \beta(x_1, x_2) + t\beta(y_1, x_2) + t\beta(x_1, y_2) + t^2\beta(y_1, y_2)$$

implies that

$$\frac{\beta(x_1 + ty_1, x_2 + ty_2) - \beta(x_1, x_2)}{t} = \beta(y_1, x_2) + \beta(x_1, y_2) + t\beta(y_1, y_2)$$

converges to  $\beta(y_1, x_2) + \beta(x_1, y_2)$  as  $t \rightarrow 0$ .

Consider a  $C^1$ -map  $f: E \supseteq U \rightarrow E$  as before.

### Mean Value Theorem

Let  $x, y \in U$ . If  $x + t(y - x) \in U$  for all  $t \in [0, 1]$ , then

$$f(y) - f(x) = \int_0^1 df(x + t(y - x), y - x) dt.$$

**Proof.** Apply the Fundamental Theorem to  $\gamma: [0, 1] \rightarrow F$ ,  $\gamma(t) := f(x + t(y - x))$  with  $\gamma'(t) = df(x + t(y - x), y - x)$ .  $\square$

Define  $U^{[1]} := \{(x, y, t) \in U \times E \times \mathbb{R} : x + ty \in U\}$

### Lemma

If  $f: U \rightarrow F$  is  $C^1$ , then the map

$$f^{[1]}: U^{[1]} \rightarrow F, \quad (x, y, t) \mapsto \begin{cases} \frac{f(x+ty)-f(x)}{t} & \text{if } t \neq 0; \\ df(x, y) & \text{if } t = 0 \end{cases}$$

is continuous.

On the open set  $t \neq 0$ , this follows from the continuity of  $f$ . For  $(x, y, t)$  close to  $(x_0, y_0, 0)$ ,

$$f^{[1]}(x, y, t) = \int_0^1 df(x + sty, y) ds$$

by the Mean Value Theorem; integrals depend continuously on parameters  $(x, y, t)$ .

Consider a  $C^1$ -map  $f: E \supseteq U \rightarrow F$  as before and a  $C^1$ -map  $g: V \rightarrow Y$  to a locally convex space  $Y$ , defined on an open subset  $V \subseteq F$  such that  $f(U) \subseteq V$ .

## Chain Rule

The composition  $g \circ f: U \rightarrow Y$ ,  $x \mapsto g(f(x))$  is  $C^1$  with

$$d(g \circ f)(x, y) = dg(f(x), df(x, y)) \quad \text{for all } (x, y) \in U \times E.$$

**Proof.** We have

$$\begin{aligned} \frac{g(f(x + ty)) - g(f(x))}{t} &= \frac{g\left(f(x) + t \frac{f(x+ty) - f(x)}{t}\right) - g(f(x))}{t} \\ &= g^{[1]}(f(x), f^{[1]}(x, y, t), t) \end{aligned}$$

for  $t \neq 0$ , which converges to

$$g^{[1]}(f(x), f^{[1]}(x, y, 0), 0) = dg(f(x), df(x, y))$$

as  $t \rightarrow 0$ .

## Remark

If  $f: E \supseteq U \rightarrow F$  is  $C^1$ , then the continuous map  $f'(x) := df(x, \cdot): E \rightarrow F$  is linear for each  $x \in U$ .

We have  $df(x, 0y) = df(x, 0) = 0 = 0df(x, y)$  and for  $t \neq 0$

$$df(x, ty) = \lim_{s \rightarrow 0} \frac{f(x + sty) - f(x)}{s} = t \lim_{s \rightarrow 0} \frac{f(x + sty) - f(x)}{st} = tdf(x, y).$$

For  $x \in U$  and  $y_1, y_2 \in E$ ,

$$\begin{aligned} \frac{f(x + ty_1 + ty_2) - f(x)}{t} &= \frac{f(x + ty_1 + ty_2) - f(x + ty_1)}{t} \\ &\quad + \frac{f(x + ty_1) - f(x)}{t} \\ &= f^{[1]}(x + ty_1, y_2, t) + f^{[1]}(x, y_1, t) \end{aligned}$$

converges both to  $df(x, y_1 + y_2)$  and

$f^{[1]}(x, y_2, 0) + f^{[1]}(x, y_1, 0) = df(x, y_1) + df(x, y_2)$  as  $t \rightarrow 0$ . The limits must coincide.

## Fact

A map  $f: E \supseteq U \rightarrow \prod_{j \in J} F_j =: F$  to a product of locally convex spaces with components  $f_j: U \rightarrow F_j$  is  $C^1$  if and only if each  $f_j$  is  $C^1$ . In this case,

$$df(x, y) = (df_j(x, y))_{j \in J} \quad \text{for all } x \in U \text{ and } y \in E. \quad (1)$$

**Proof.** The projection  $\text{pr}_j: F \rightarrow F_j$ ,  $(y_i)_{i \in J} \mapsto y_j$  onto the  $j$ th component is continuous and linear. Hence, if  $f$  is  $C^1$ , then also  $f_j = \text{pr}_j \circ f$  is  $C^1$  and  $d(f_j)(x, y) = d(\text{pr}_j)(f(x), df(x, y)) = \text{pr}_j(df(x, y))$ , whence (1) holds.

If all components are  $C^1$ , then

$$\frac{f(x + ty) - f(x)}{t} = \left( \frac{f_j(x + ty) - f_j(x)}{t} \right)_{j \in J}$$

converges to  $(df_j(x, y))_{j \in J}$  as  $t \rightarrow 0$  since this holds componen-wise.

## Fact

Let  $f: E \supseteq U \rightarrow F$  be a map and  $F_0 \subseteq F$  be a closed vector subspace such that  $f(U) \subseteq F_0$ . Then  $f$  is  $C^1$  if and only if  $f|^{F_0}: U \rightarrow F_0$  is so, and  $df(x, y) = d(f|^{F_0})(x, y)$  for all  $(x, y) \in U \times E$  in this case.

**Proof.** The inclusion map  $j: F_0 \rightarrow F$  is continuous and linear. Hence, if  $f|^{F_0}$  is  $C^1$ , then also  $f = j \circ f|^{F_0}$ , with

$$df(x, y) = dj(f|^{F_0}(x), d(f|^{F_0})(x, y)) = j(d(f|^{F_0})(x, y)) = d(f|^{F_0})(x, y).$$

If  $f$  is  $C^1$ , then  $f|^{F_0}$  is continuous and

$$\frac{f(x + ty) - f(x)}{t} \rightarrow df(x, y)$$

in  $F$  as  $t \rightarrow 0$ . Note that the difference quotients are in  $F_0$ ; since  $F_0$  is closed, the limit  $df(x, y)$  is in  $F_0$  as well and the difference quotients, which coincide with those of  $f|^{F_0}$ , converge to  $df(x, y)$  also in  $F_0$  using the induced topology.



The preceding two facts concerning mappings into products and mappings into closed vector subspaces hold just as well with  $C^k$ -maps in place of  $C^1$ -maps, and we shall not restate them. Likewise the Chain Rule (compositions of composable  $C^k$ -maps are  $C^k$ ). Higher order differentiability is defined as follows.

## §4 Higher order differentiability

Let  $E$  and  $F$  be locally convex spaces and  $U \subseteq E$  be an open subset. Let  $k \in \mathbb{N}$ .

### Definition

A map  $f: U \rightarrow F$  is called  $C^{k+1}$  if it is  $C^1$  and  $df: U \times E \rightarrow F$  is  $C^k$ .

### Remark

One can show that  $f$  is  $C^k$  if and only if  $f$  is continuous, the iterated directional derivatives

$$d^j f(x, y_1, \dots, y_j) := (D_{y_j} \cdots D_{y_1} f)(x)$$

exist at  $x \in U$  for all  $j \in \mathbb{N}$  with  $j \leq k$  and  $y_1, \dots, y_j \in E$ , and  $d^j f: U \times E^j \rightarrow F$  is continuous.

**Example.** Every continuous linear map  $\alpha: E \rightarrow F$  is  $C^k$  for all  $k \in \mathbb{N}$  and hence smooth.

We already know that  $\alpha$  is  $C^1$  and that  $d\alpha: E \times E \rightarrow F$  is the map

$$(x, y) \mapsto \alpha(y).$$

Thus  $d\alpha$  is a continuous linear map and hence  $C^k$  by induction. By definition,  $\alpha$  is  $C^{k+1}$ .

**Example.** Every continuous bilinear map  $\beta: E_1 \times E_2 \rightarrow F$  is  $C^k$  for all  $k \in \mathbb{N}$  and hence smooth.

We already know that  $\beta$  is  $C^1$  and that  $d\beta: (E_1 \times E_2) \times (E_1 \times E_2) \rightarrow F$  is the map

$$((x_1, x_2), (y_1, y_2)) \mapsto \beta(y_1, x_2) + \beta(x_1, y_2).$$

Thus  $d\beta = \beta \circ \alpha_1 + \beta \circ \alpha_2$  with continuous linear maps  $\alpha_1, \alpha_2: (E_1 \times E_2)^2 \rightarrow E_1 \times E_2$ . The latter being  $C^k$ , also  $d\beta$  is  $C^k$ , by the Chain Rule. Hence  $\beta$  is  $C^{k+1}$ .

Consider a locally convex algebra  $A$  (a locally convex space  $A$ , endowed with a continuous bilinear multiplication  $A \times A \rightarrow A$  such that the associative law  $x(yz) = (xy)z$  holds and there exists a neutral element  $1$  for the multiplication,  $1x = x1 = x$  for all  $x \in A$ ).

### Definition

If the unit group  $A^\times := \{x \in A : (\exists y \in A) xy = yx = 1\}$  is open in  $A$  and the inversion map  $\iota: A^\times \rightarrow A, x \mapsto x^{-1}$  is continuous, then  $A$  is called a **continuous inverse algebra** or **cia**.

### Fact

If  $A$  is a **cia**, then the inversion map  $\iota: A^\times \rightarrow A$  is smooth. Thus  $A^\times$  is a Lie group.

**Proof.** For all  $a, b \in A^\times$ , we have

$$b^{-1} - a^{-1} = b^{-1}(a - b)a^{-1}.$$

Applying this to  $a = x$  and  $y = x + ty$  for  $x \in A^\times$  and  $y \in A$ , we get

$$\frac{(x + ty)^{-1} - x^{-1}}{t} = (x + ty)^{-1}(-y)x^{-1} \rightarrow -x^{-1}yx^{-1}$$

as  $t \rightarrow 0$ . Thus  $d\iota$  exists and

$$d\iota(x, y) = -x^{-1}yx^{-1} = -\iota(x)y\iota(x)$$

is continuous in  $(x, y)$ , whence  $\iota$  is  $C^1$ . If  $\iota$  is  $C^k$  by induction, we deduce using the Chain Rule and smoothness of the bilinear algebra multiplication that  $d\iota$  is  $C^k$ , whence  $\iota$  is  $C^{k+1}$ . We also used that a map to a product is  $C^k$  if all of its components are so.

**Example.** Every Banach algebra  $A$  (e.g.,  $C^k([0, 1], \mathbb{R})$ ) is a cia and hence  $A^\times$  a Lie group.

**Example.**  $C^\infty([0, 1], \mathbb{R})$  is a cia.

## §5 Comparison with calculus in normed spaces

Let  $(E, \|\cdot\|_E)$  and  $(F, \|\cdot\|_F)$  be Banach spaces,  $U \subseteq E$  be an open subset and  $f: U \rightarrow F$  be a map. Say that  $f$  is differentiable at  $x \in U$  if there exists a continuous linear map  $f'(x): E \rightarrow F$  such that the remainder term in the affine-linear approximation

$$f(y) = f(x) + f'(x)(y - x) + R(y)$$

satisfies

$$\lim_{y \rightarrow x} \frac{\|R(y)\|_F}{\|y - x\|_E} = 0.$$

The  $f$  is continuous at  $x$  and  $f'(x)$  is unique as

$$f'(x)(y) = (D_y f)(x) \quad \text{for all } y \in E.$$

Call  $f$  **continuously Fréchet differentiable** (or  $FC^1$ ) if  $f$  is differentiable at each  $x \in U$  and  $f': U \rightarrow (\mathcal{L}(E, F), \|\cdot\|_{\text{op}})$  is continuous. If  $f$  is  $FC^1$  and  $f'$  is  $FC^k$ , say that  $f$  is  $FC^{k+1}$ .

### Fact

If  $f$  is  $FC^k$ , then  $f$  is  $C^k$ . If  $f$  is  $C^{k+1}$ , then  $f$  is  $FC^k$ .

Notably, same notion of smoothness!

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