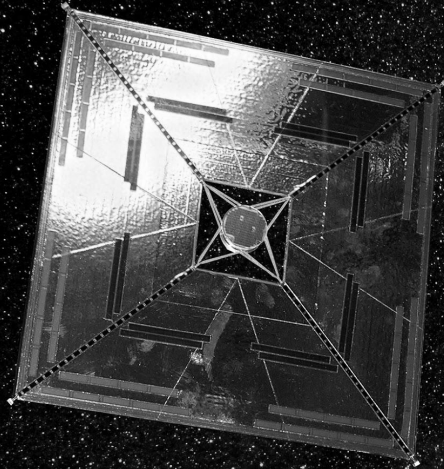
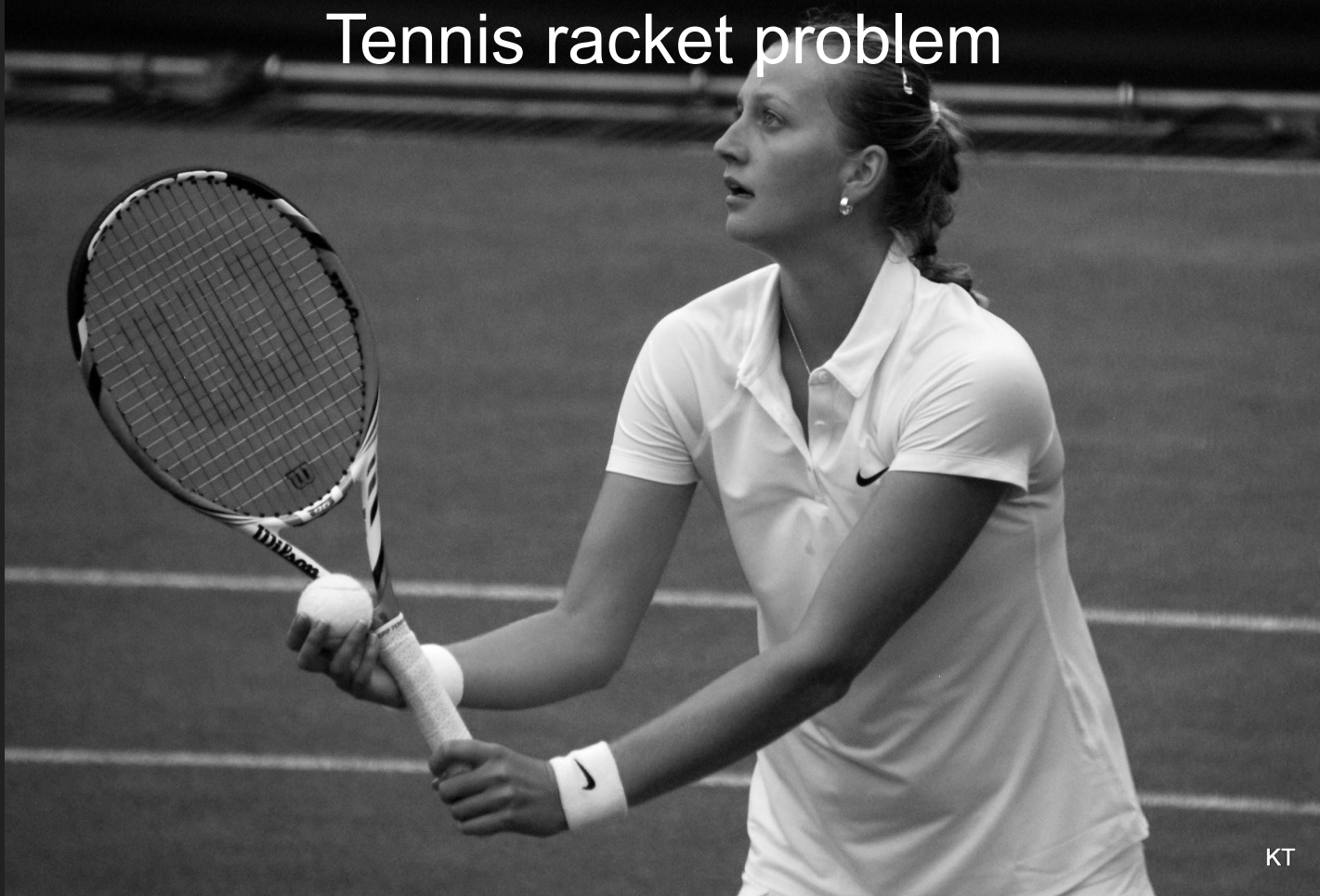


Pedal coordinates, Dipole drive orbits and other force problems



Białystok 24. 6. 2022
Petr Blaschke

Tennis racket problem



Tennis racket problem

Find a curve of a given length fixed on both ends that sweeps maximal volume when rotated around the x -axis.



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$$L[y] := \int_{-1}^1 \pi y^2 dx,$$

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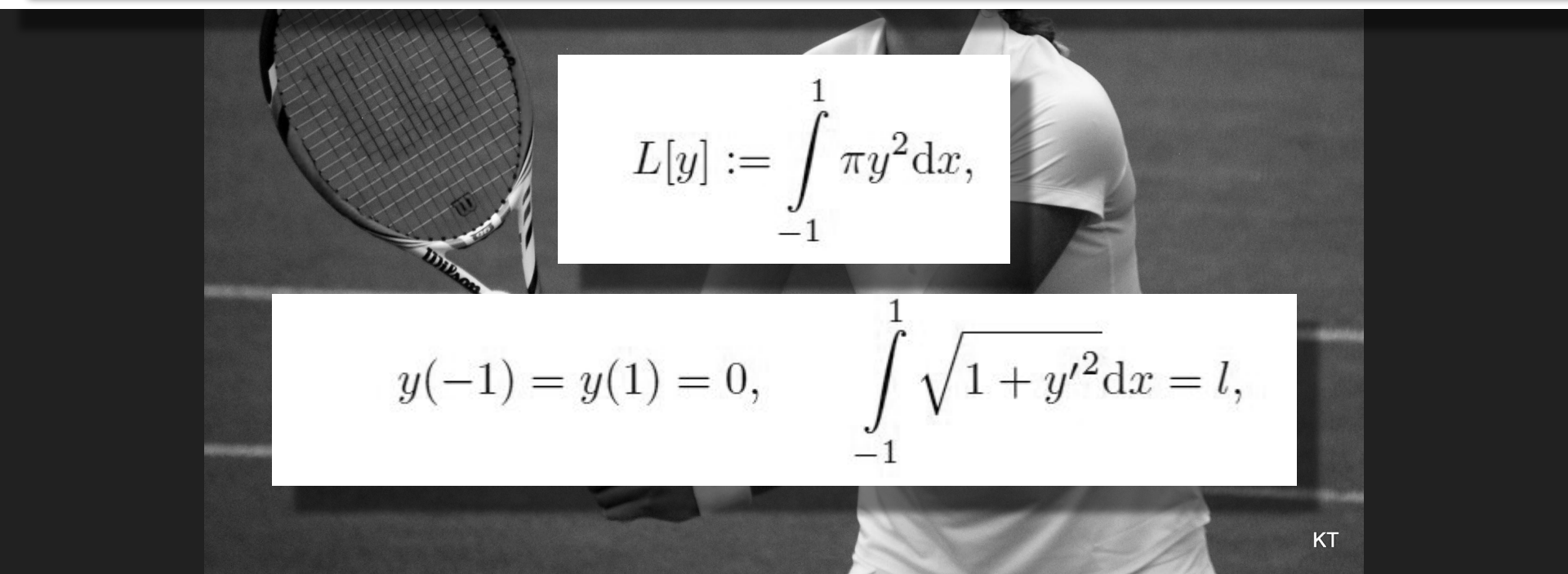
Find a curve of a given length fixed on both ends that sweeps maximal volume when rotated around the x -axis.

$$L[y] := \int_{-1}^1 \pi y^2 dx,$$

$$y(-1) = y(1) = 0, \quad \int_{-1}^1 \sqrt{1 + y'^2} dx = l,$$

Beltrami identity:

$$\pi y^2 + \lambda \sqrt{1 + y'^2} - \lambda \frac{y'^2}{\sqrt{1 + y'^2}} = C$$


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$$\sqrt{\frac{\lambda - C}{\pi}} F\left(y \sqrt{\frac{\pi}{C + \lambda}}, k\right) - \sqrt{\frac{\lambda - C}{\pi}} E\left(y \sqrt{\frac{\pi}{C + \lambda}}, k\right) + Cy = x - d.$$

$$-1$$

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Euler-Lagrange equation:

$$\frac{y''}{(1 + y'^2)^{\frac{3}{2}}} = \frac{2\pi}{\lambda} y.$$

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Euler-Lagrange equation:

$$\kappa \propto y.$$

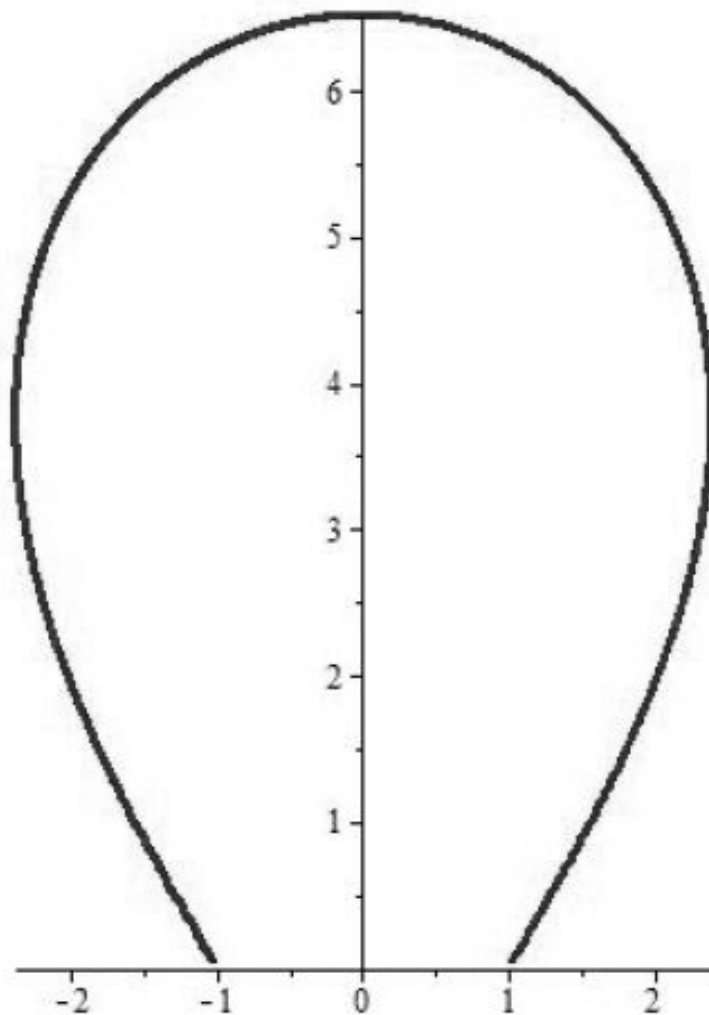
$$\frac{y''}{(1 + y'^2)^{\frac{3}{2}}} = \frac{2\pi}{\lambda} y.$$

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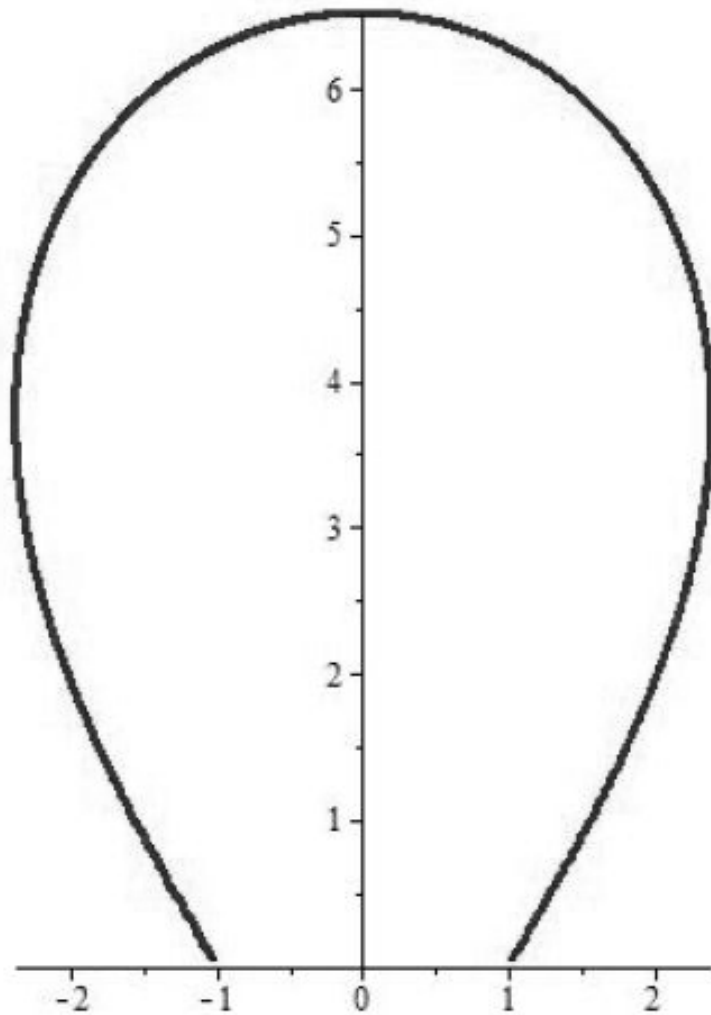
$$\sqrt{\frac{\lambda - C}{\pi}} F\left(y\sqrt{\frac{\pi}{C + \lambda}}, k\right) - V$$

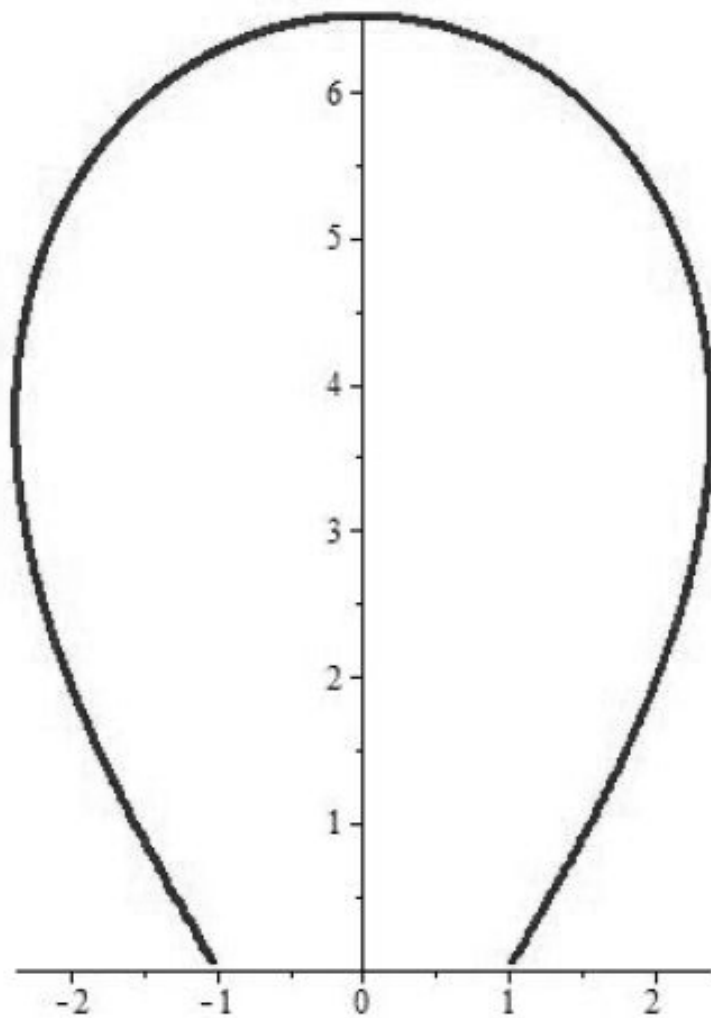
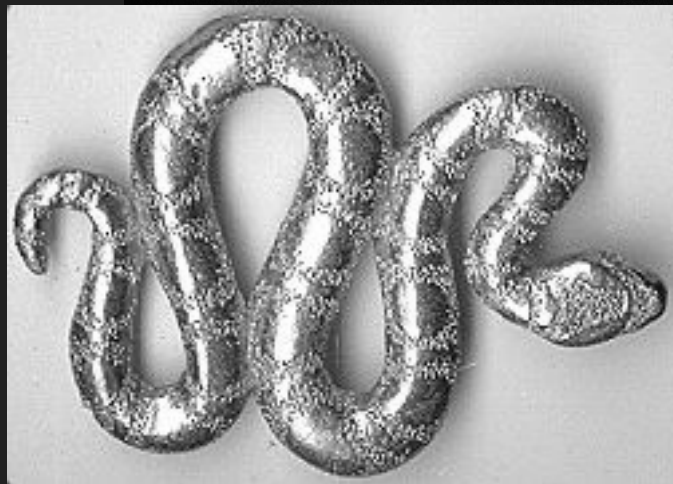
Euler-Lagrange equation:

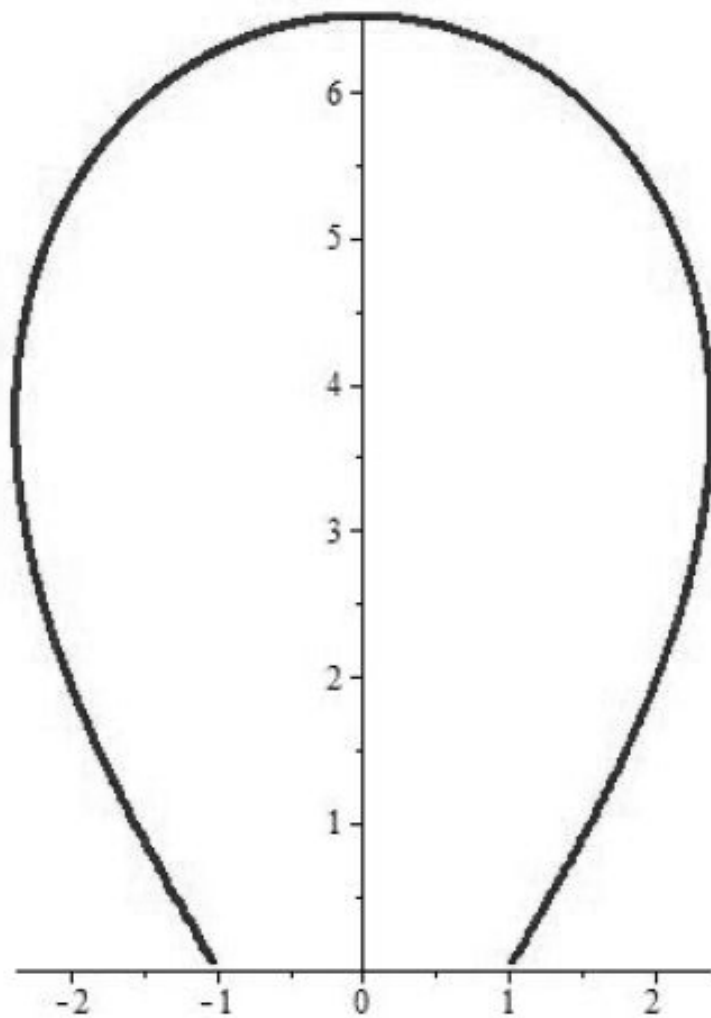
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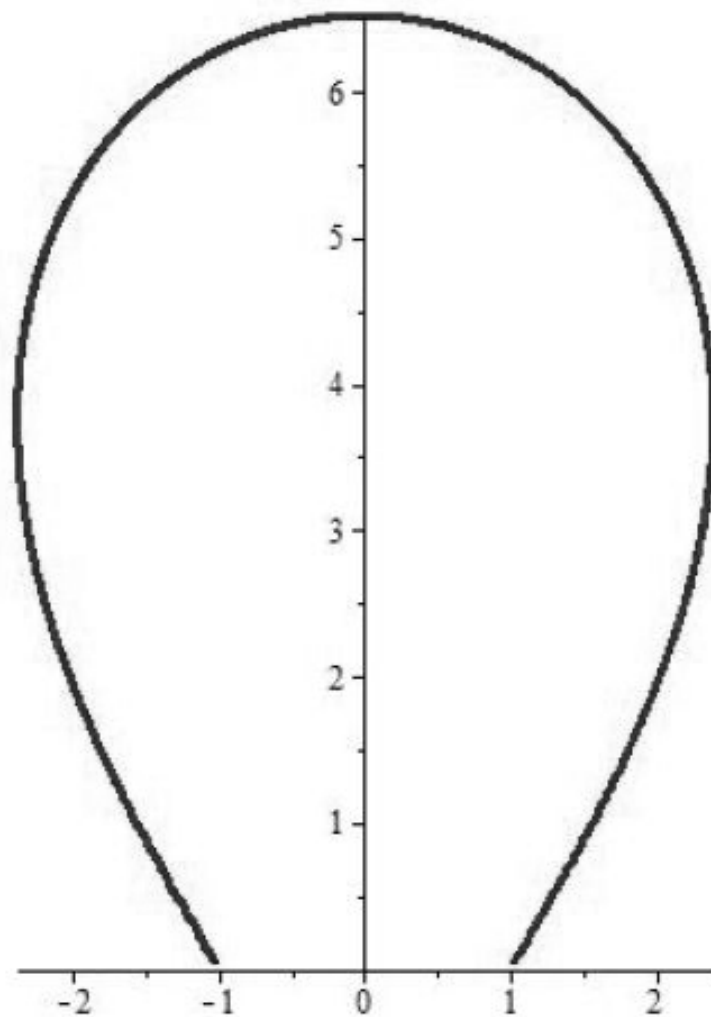
Tennis ra







Elastic curve

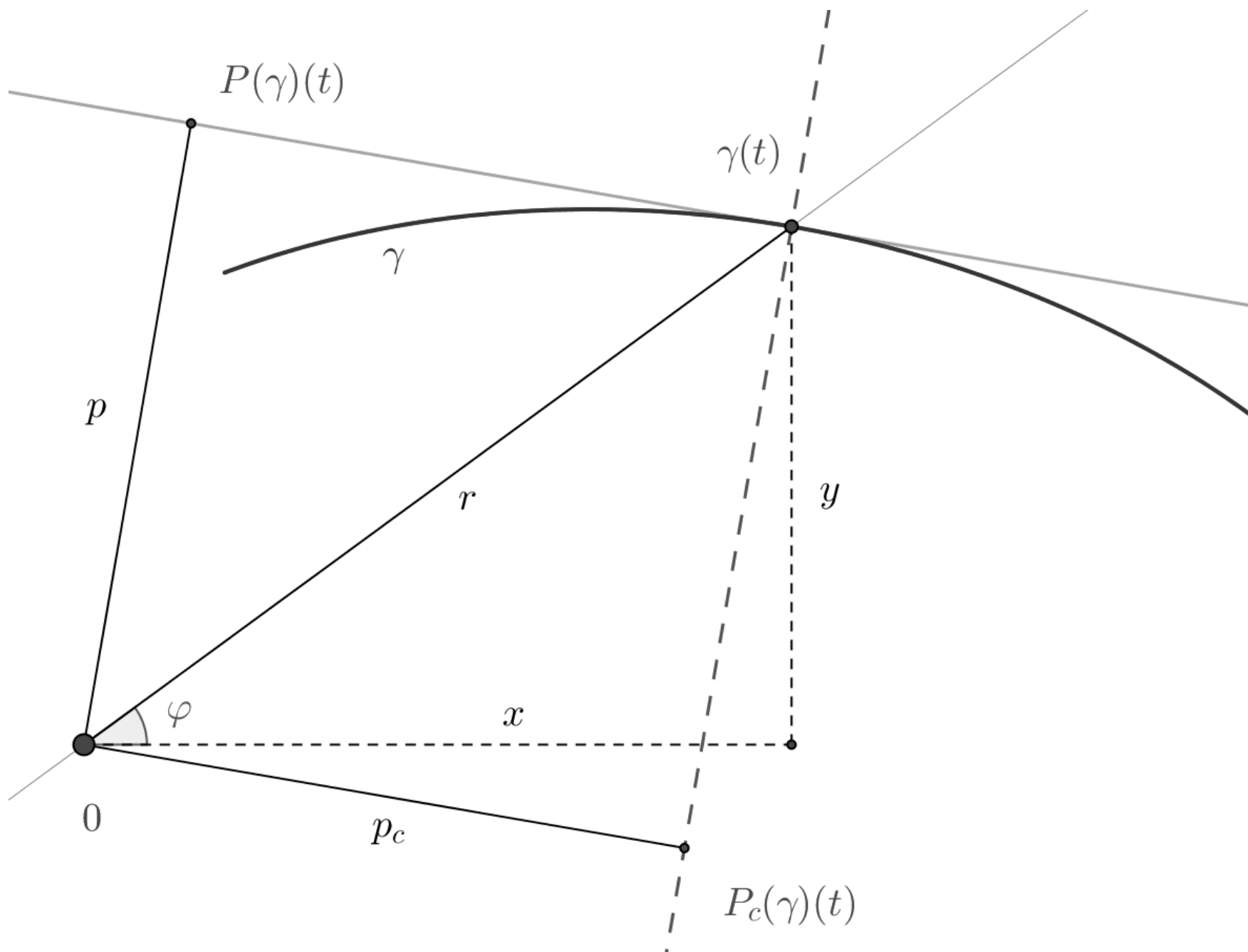




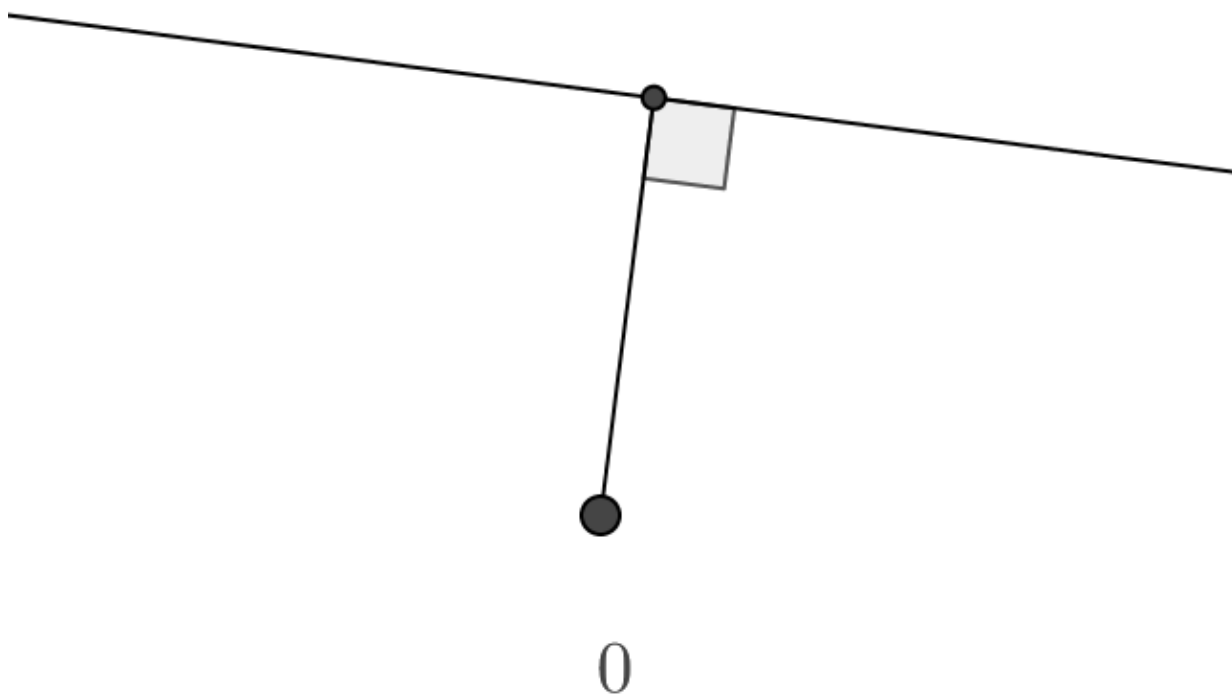
**Pedal
coordinates**

**Cartesian,
polar
coordinates**

Coordinates

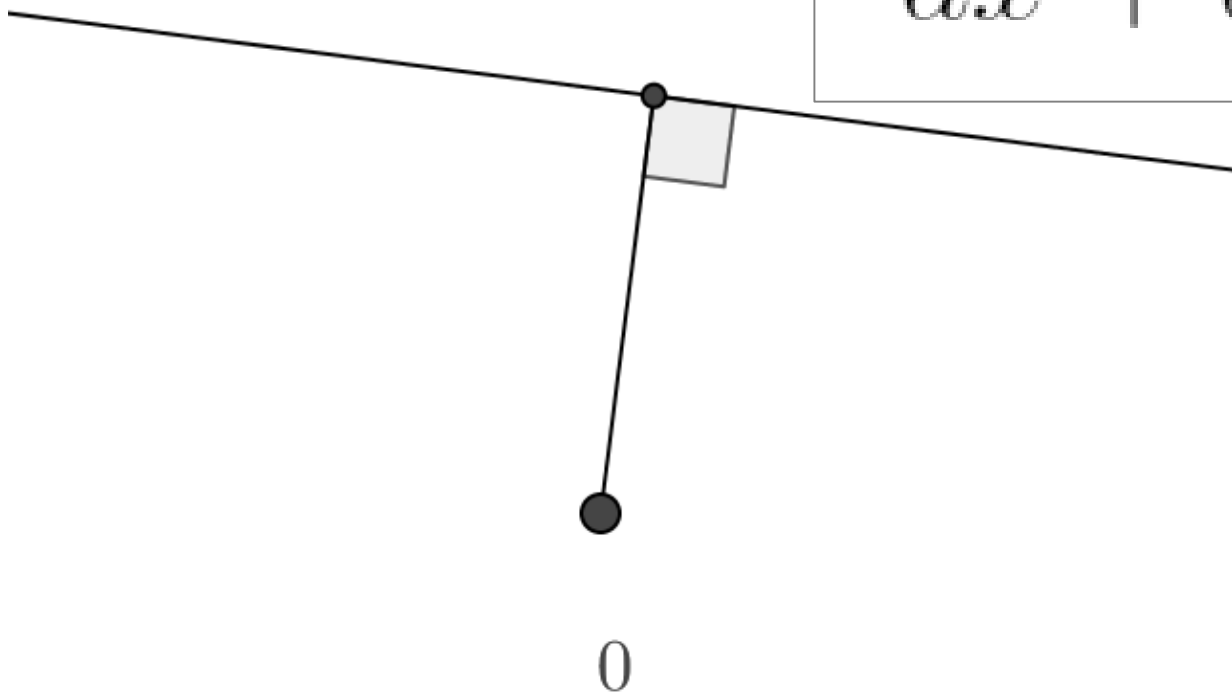


Line



Line

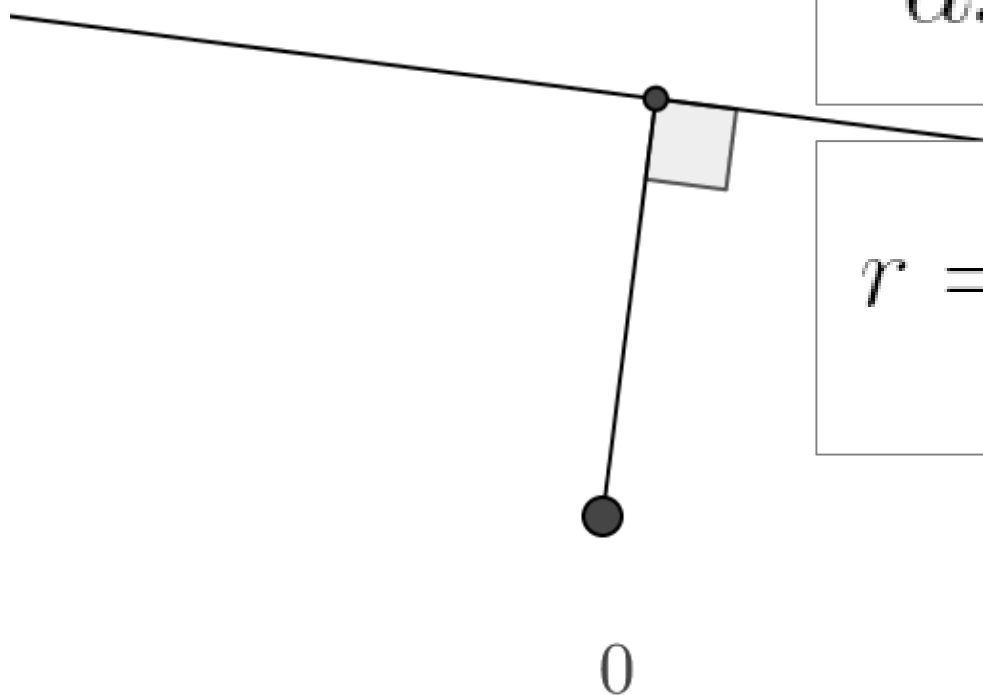
$$ax + by + c = 0.$$



Line

$$ax + by + c = 0.$$

$$r = -\frac{c}{a \cos \varphi + b \sin \varphi}.$$

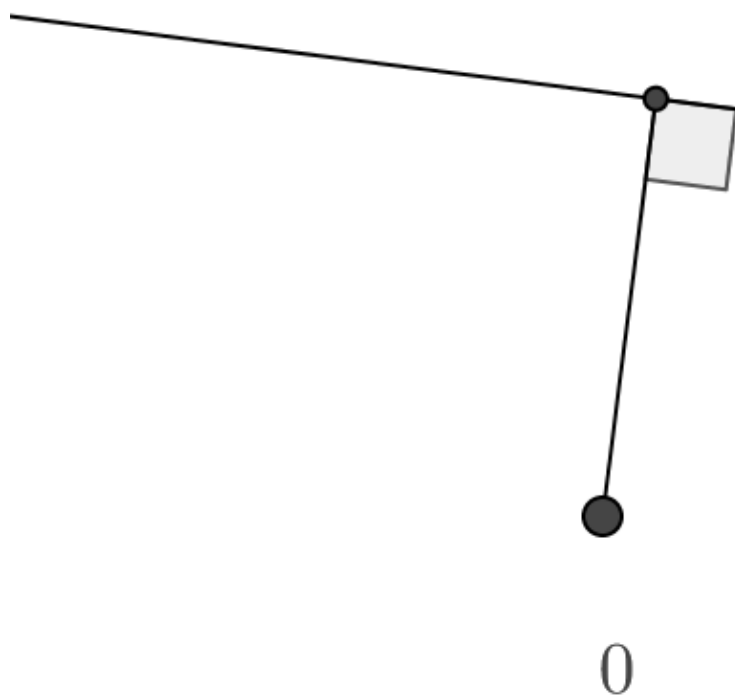


Line

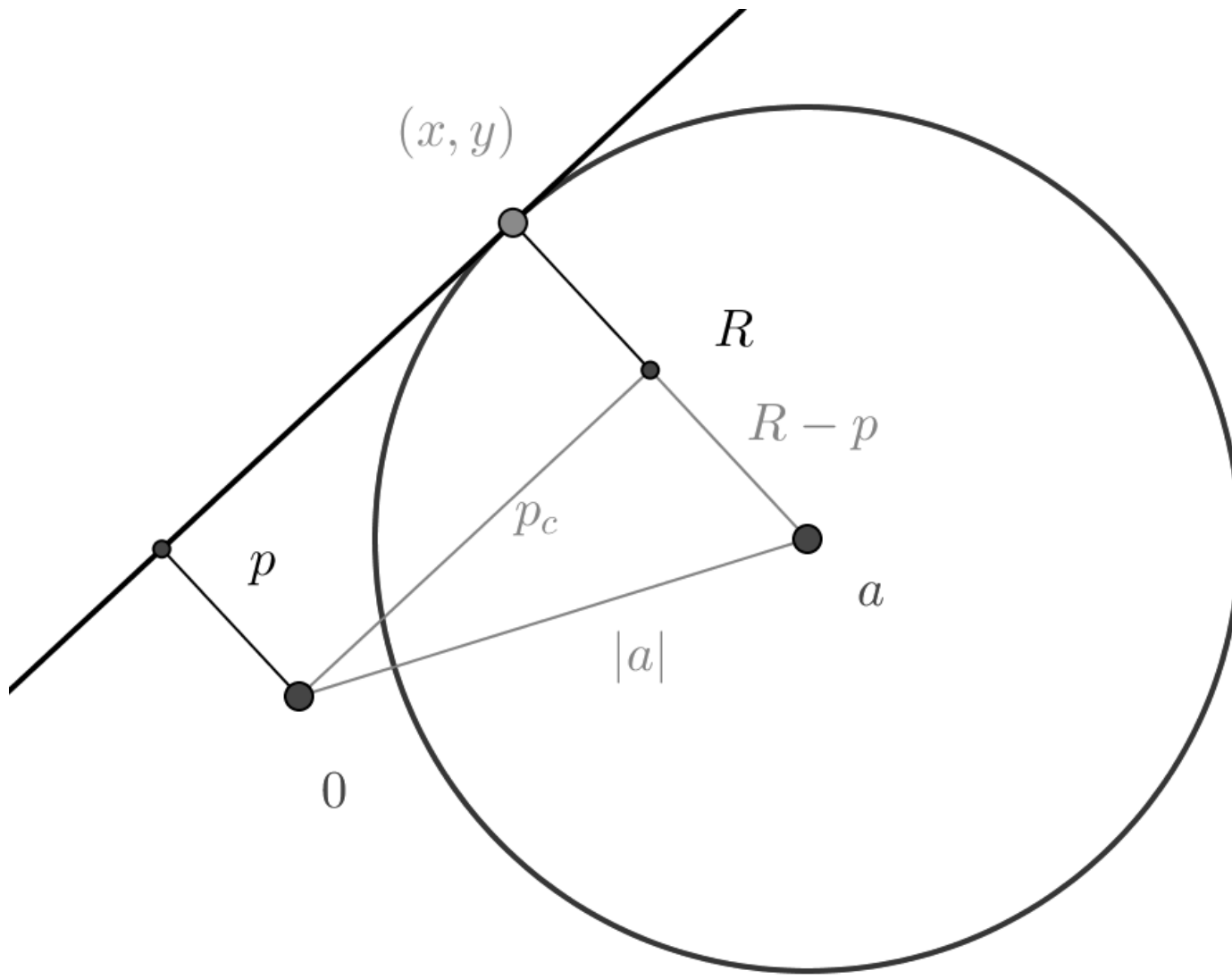
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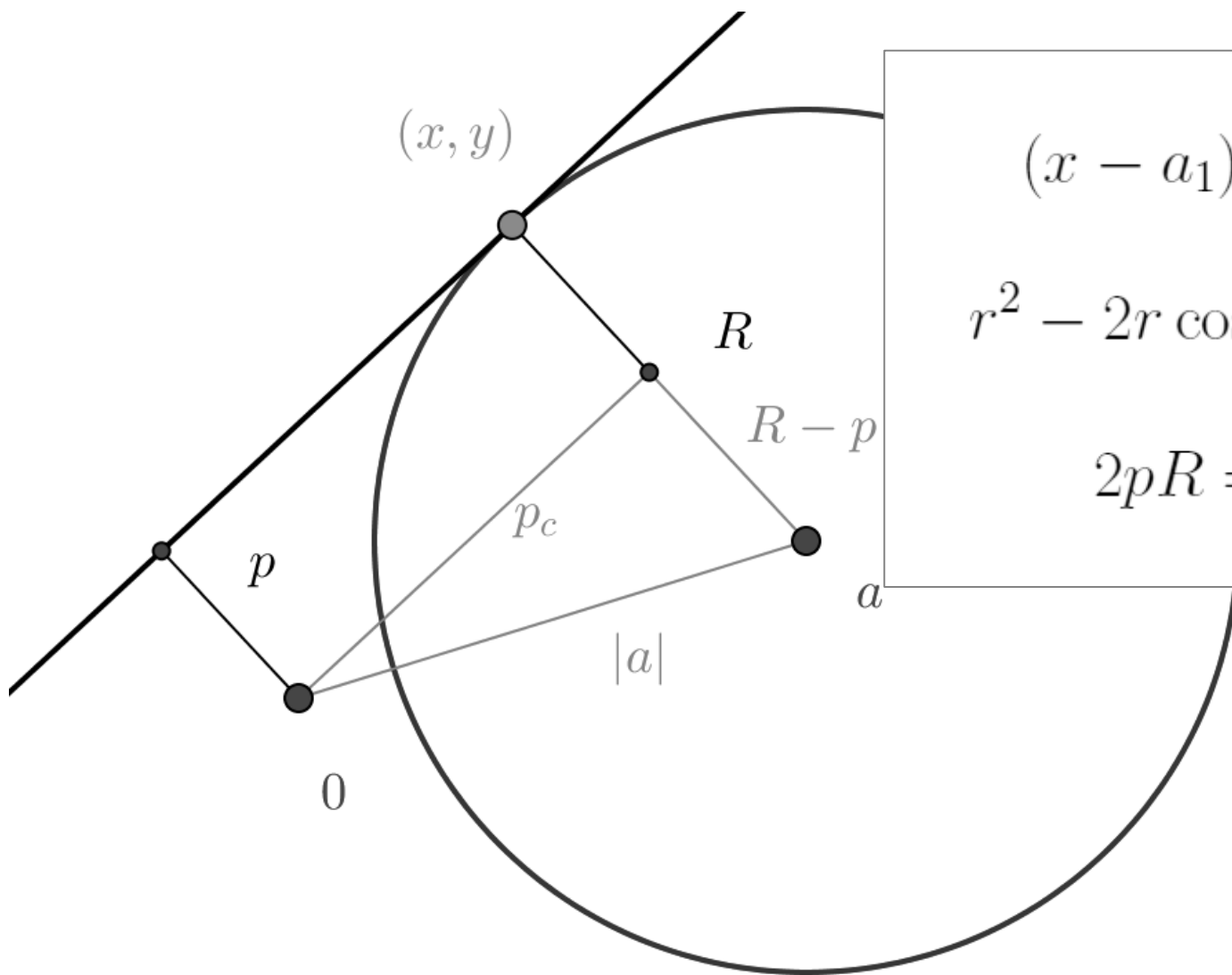
$$p = \alpha.$$



Circle



Circle

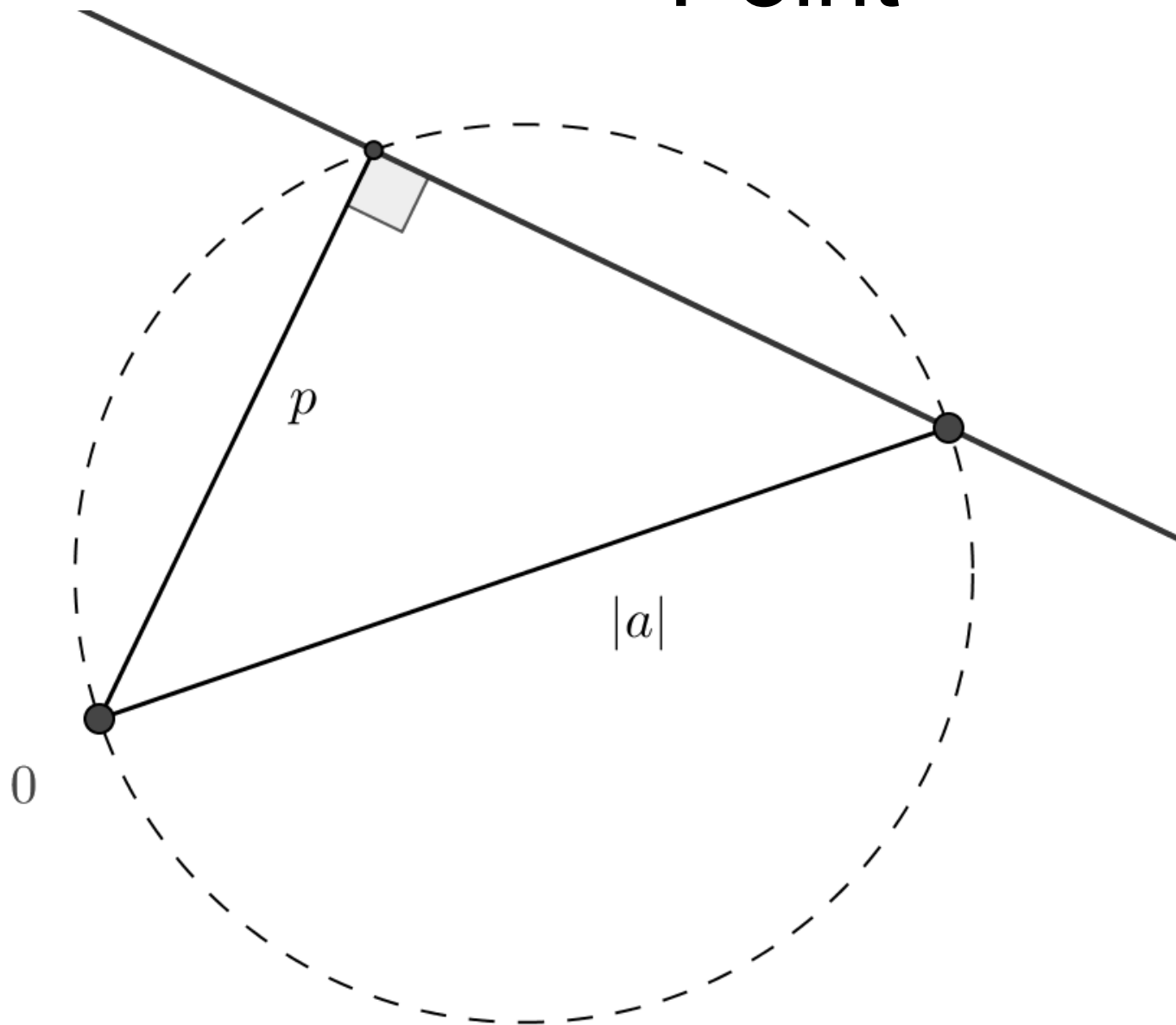


$$(x - a_1)^2 + (y - a_2)^2 = R^2.$$

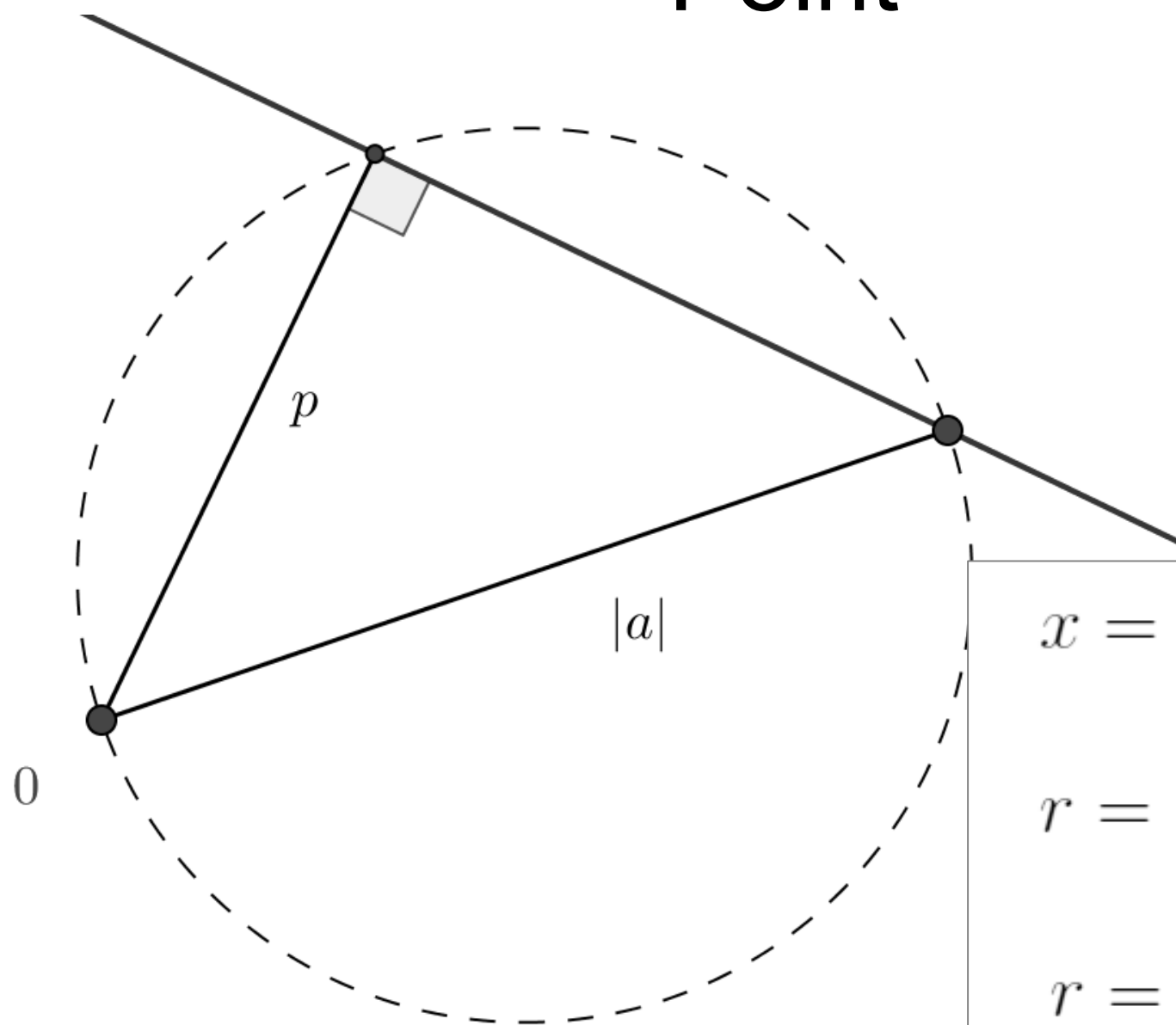
$$r^2 - 2r \cos(\varphi - \alpha) + |a|^2 = R^2.$$

$$2pR = r^2 + R^2 - |a|^2.$$

Point



Point

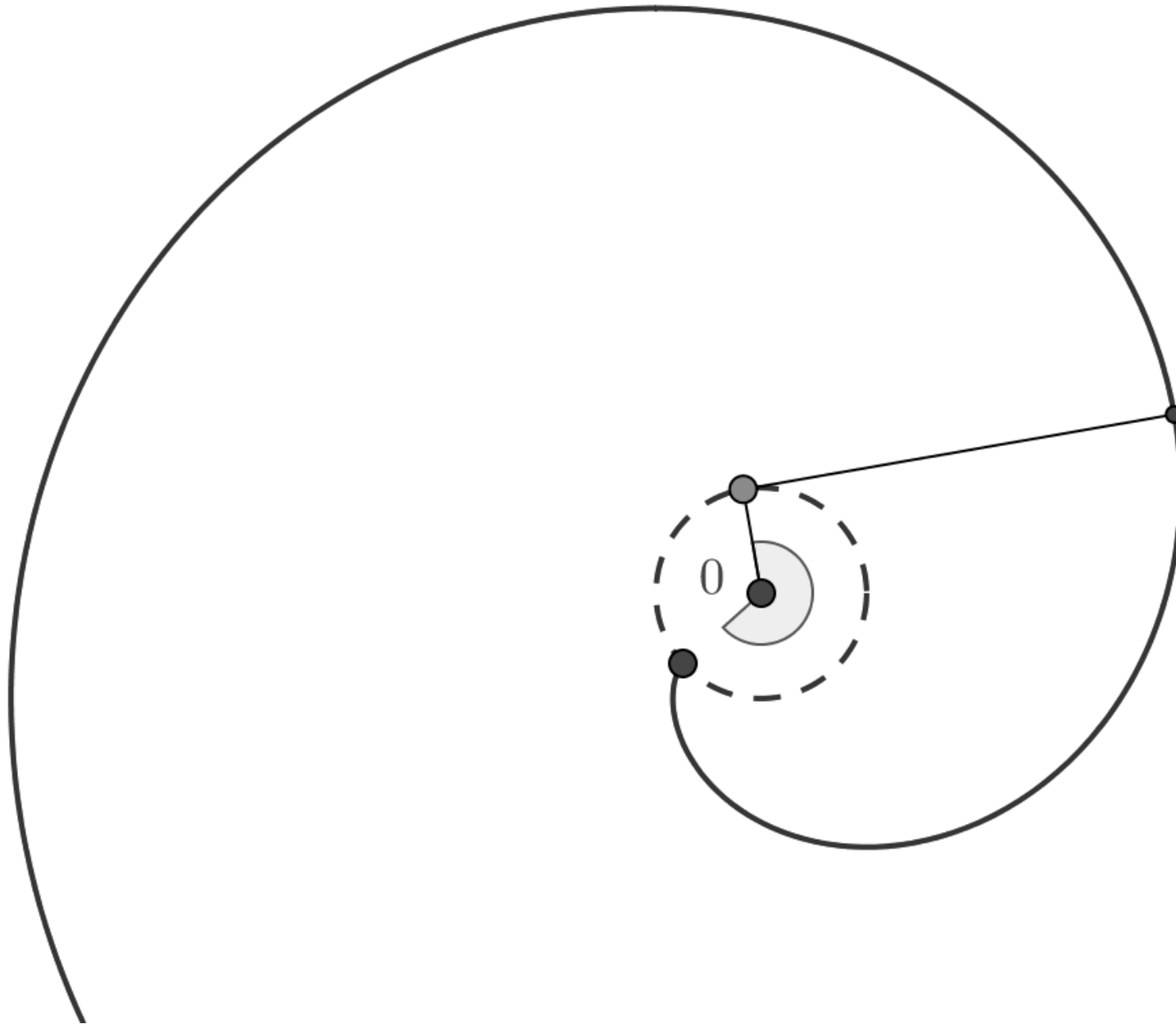


$$x = a_1, \quad y = a_2.$$

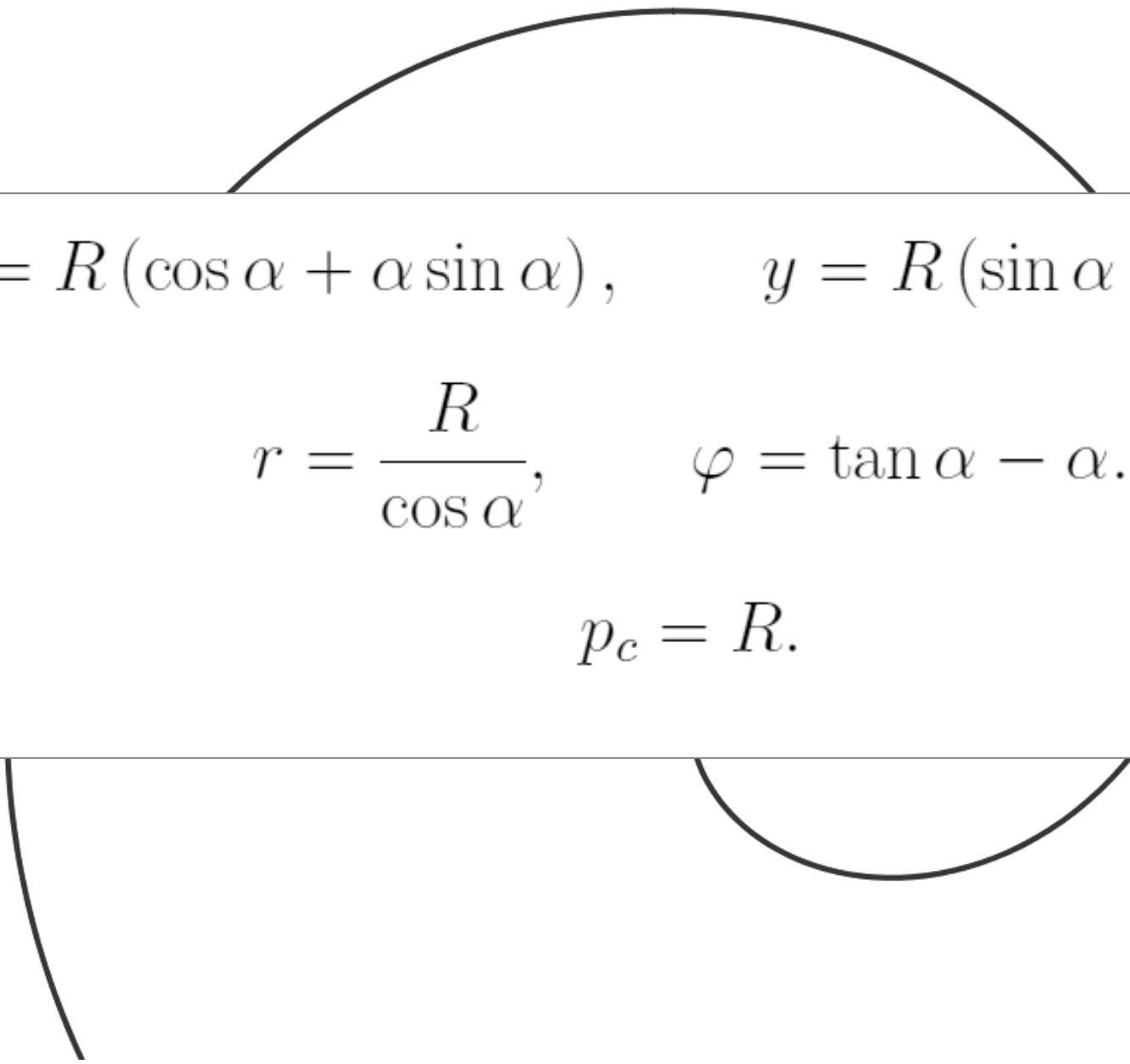
$$r = |a|, \quad \varphi = \alpha.$$

$$r = |a|, \quad p \leq r.$$

Involute of a circle



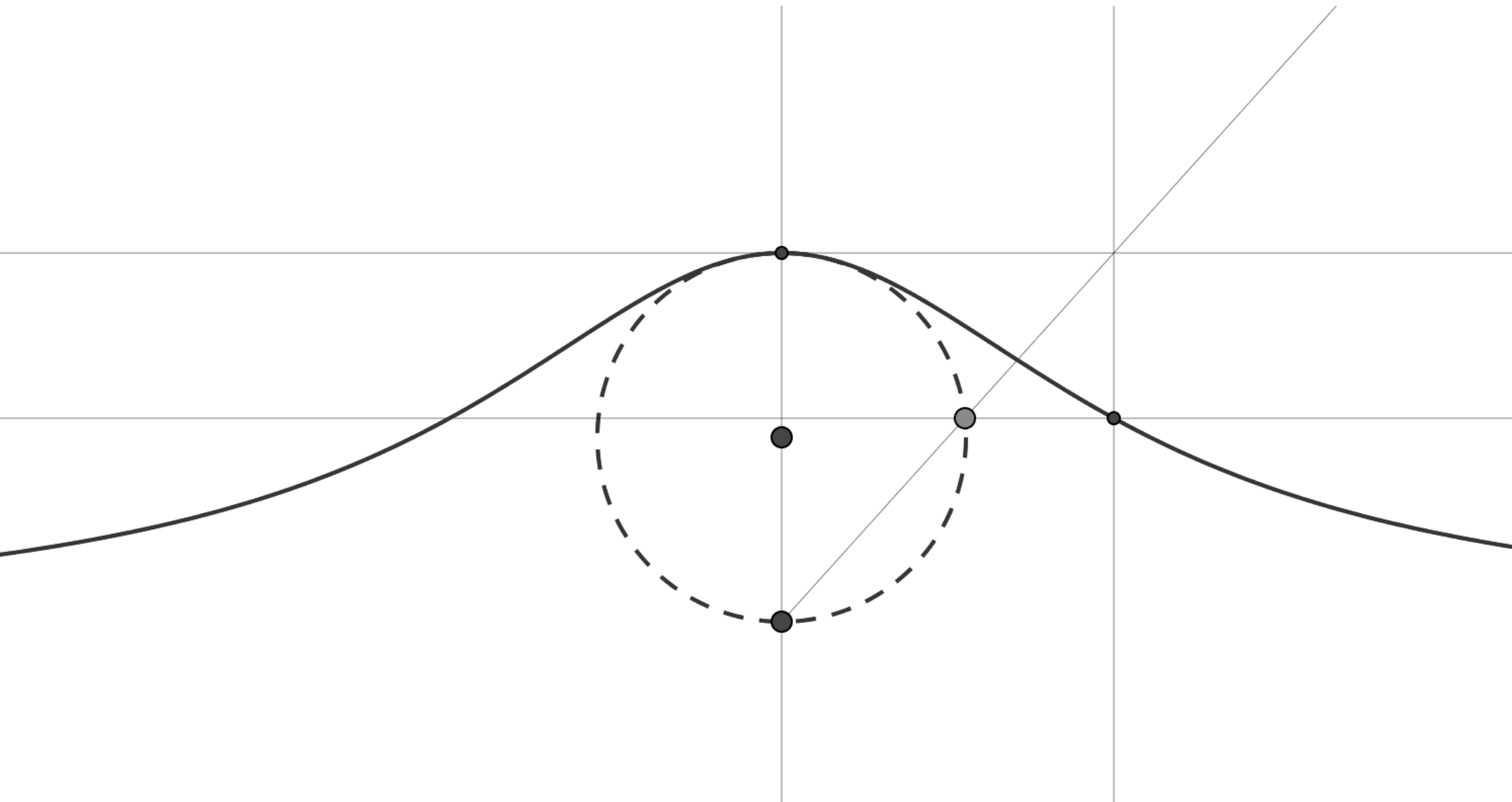
Involute of a circle

A diagram showing a circle with an involute curve. The circle is centered at the origin. The involute curve starts at a point on the circle and extends outwards, forming a series of loops. The curve is shown in black. The equations for the involute are displayed in a white box with a black border.
$$x = R (\cos \alpha + \alpha \sin \alpha), \quad y = R (\sin \alpha - \alpha \cos \alpha).$$

$$r = \frac{R}{\cos \alpha}, \quad \varphi = \tan \alpha - \alpha.$$

$$p_c = R.$$

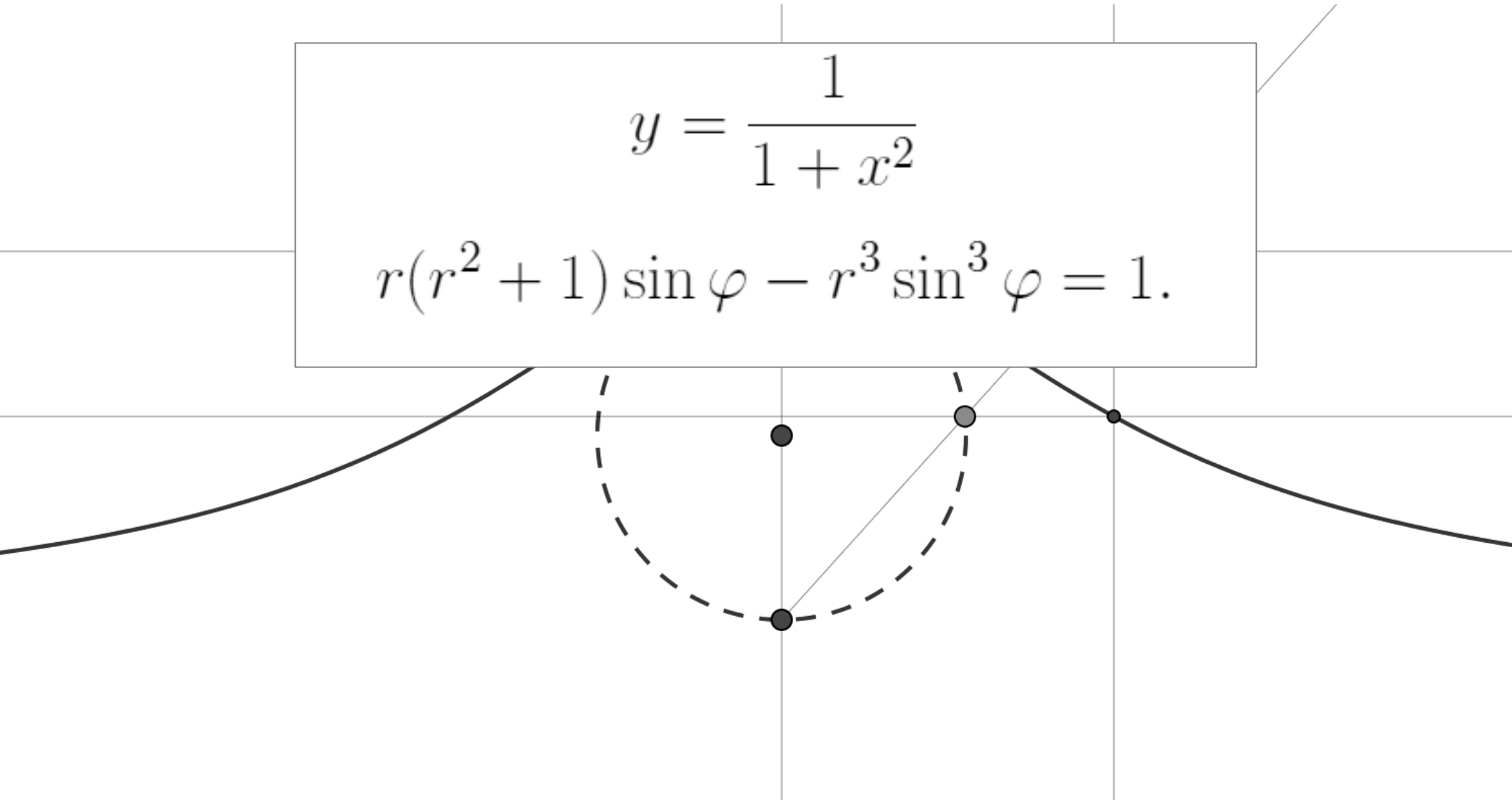
Witch of Agnesi



Witch of Agnesi

$$y = \frac{1}{1 + x^2}$$

$$r(r^2 + 1) \sin \varphi - r^3 \sin^3 \varphi = 1.$$



Witch of Agnesi

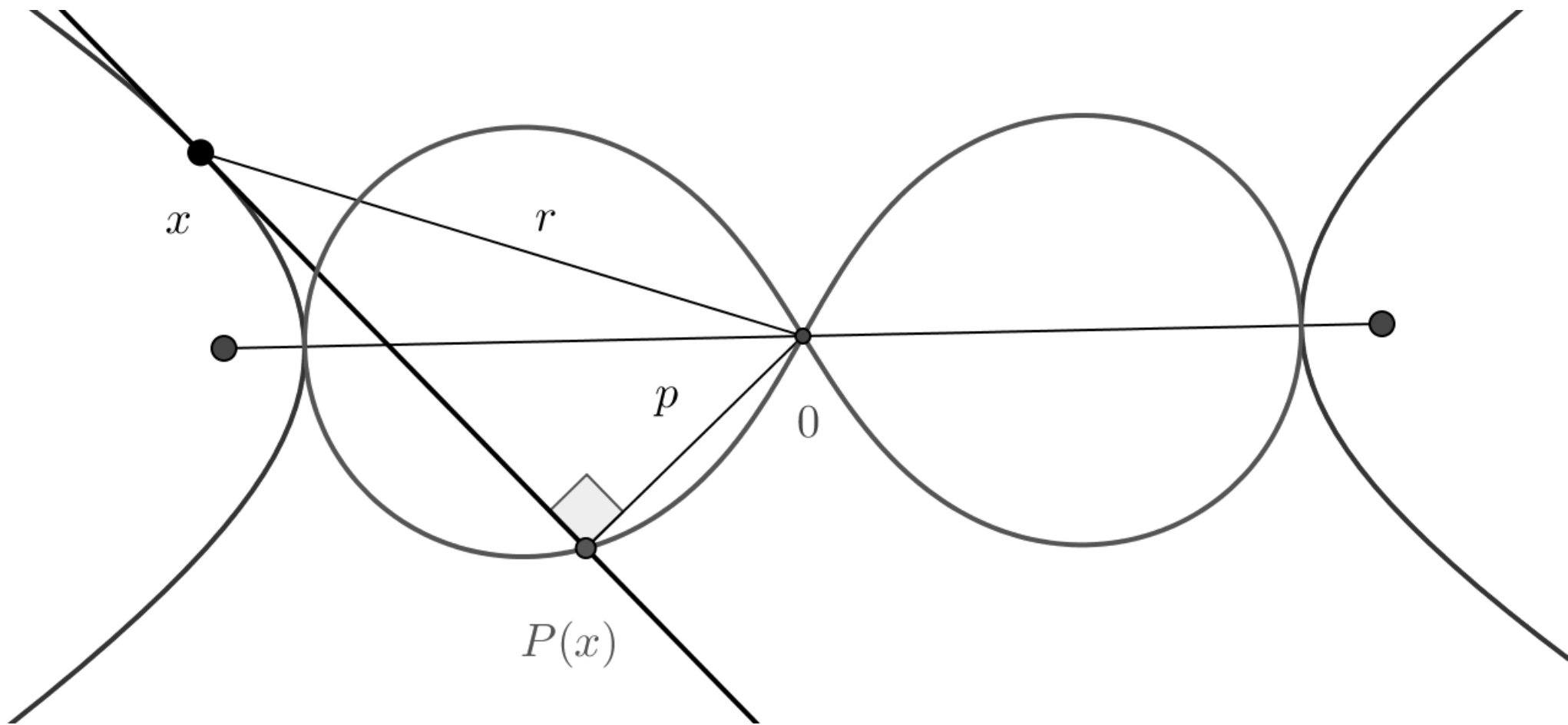
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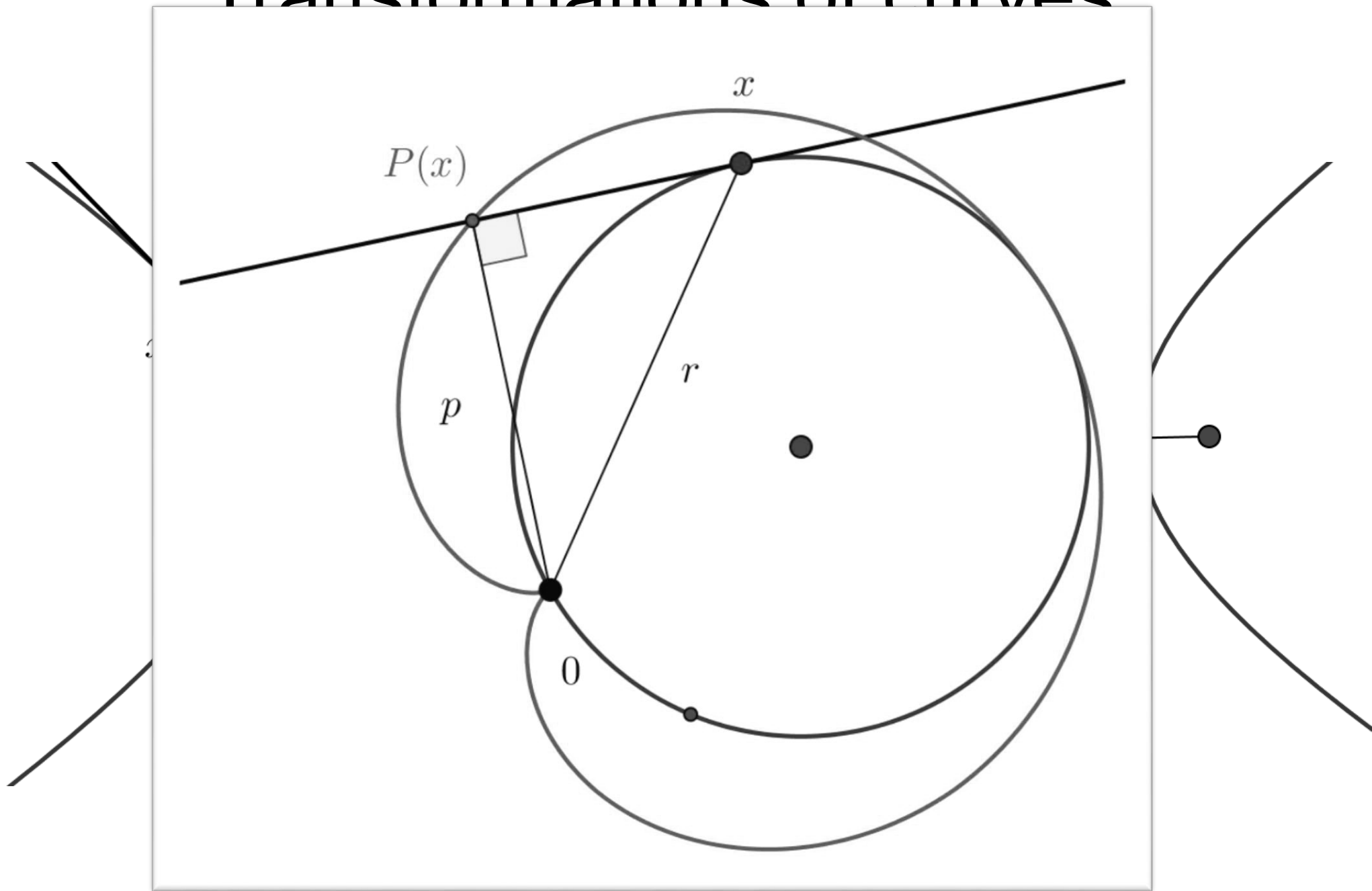
$$\begin{aligned} & \frac{1}{36} \frac{C^2}{p^2} + \frac{1}{3} \frac{p^2 - 2r^2 + 2}{p^2} + 4 \frac{r^4 + 4p^2 - 2r^2 + 1}{p^2 C^2} + 192 \frac{r^2 (r^2 + 1)^2 (p - r) (p + r)}{p^2 C^3 B} - 8 \frac{(r^2 + 1)^2 (p - r) (p + r)}{p^2 C B} \\ & - 1152 \frac{(r^2 + 1)^3 (r - 1) (r + 1) (p - r) (p + r)}{p^2 C^5 B} - 576 \frac{r^2 (r^2 + 1)^4 (p - r) (p + r)}{p^2 C^4 B^2} - 82944 \frac{r^2 (r^2 + 1)^6 (p - r) (p + r)}{p^2 C^8 B^2} \\ & + 13824 \frac{r^2 (r^2 + 1)^5 (p - r) (p + r)}{p^2 C^6 B^2} = 0, \end{aligned}$$

$$C := \sqrt[3]{12B - 108}, \quad B := \sqrt{-12r^6 - 36r^4 - 36r^2 + 69}.$$

Transformations of curves

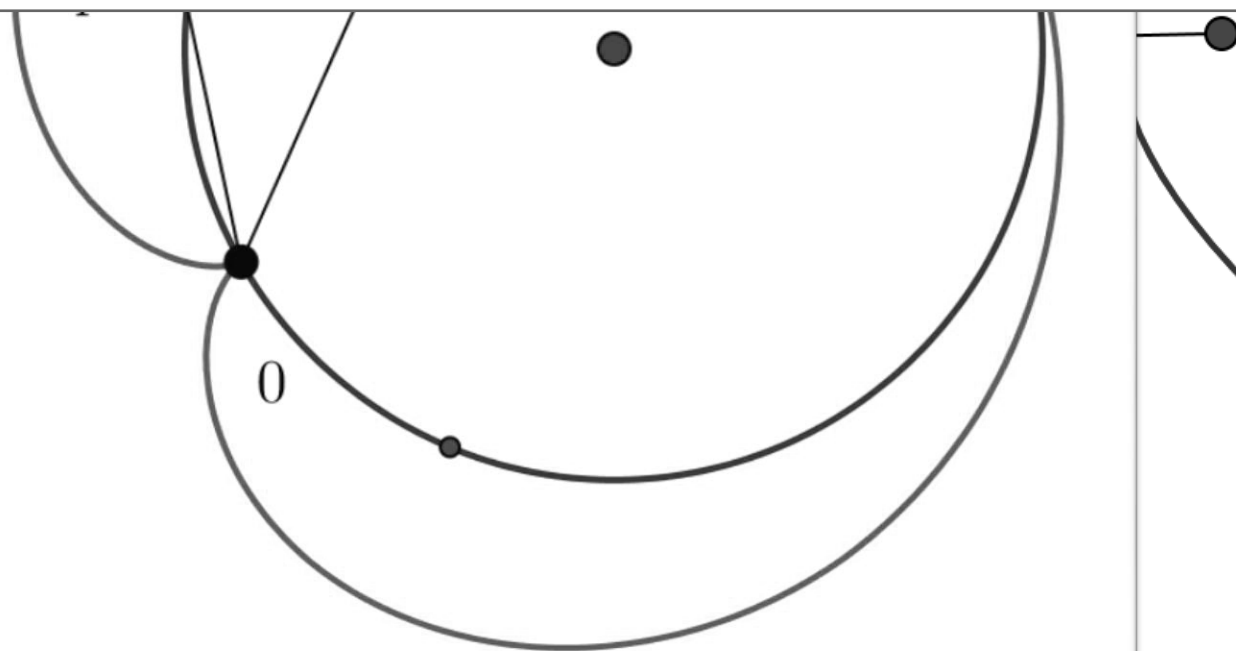


Transformations of curves



Transformations of curves

$$\begin{array}{lll} x & \rightarrow & x - \frac{\dot{x}x + \dot{y}y}{x^2 + y^2} \dot{x}, \\ y & \rightarrow & y - \frac{\dot{x}x + \dot{y}y}{x^2 + y^2} \dot{y}. \end{array}$$



Transformations of curves

$$\begin{aligned}x &\rightarrow x - \frac{\dot{x}x + \dot{y}y}{x^2 + y^2}\dot{x}, \\y &\rightarrow y - \frac{\dot{x}x + \dot{y}y}{x^2 + y^2}\dot{y}.\end{aligned}$$

$$f(p, r, p_c) = 0 \xrightarrow{P} f\left(r, \frac{r^2}{p}, \frac{r}{p}p_c\right) = 0,$$

0

Transformations of curves

$$x \rightarrow x - \frac{\dot{x}x + \dot{y}y}{\dot{x}} \dot{x},$$

$$f(p, r, p_c) = 0 \xrightarrow{S_\alpha} f(\alpha p, \alpha r, \alpha p_c) = 0,$$

$$f(p, r, p_c) = 0 \xrightarrow{P} f\left(r, \frac{r^2}{p}, \frac{r}{p} p_c\right) = 0,$$

$$f(p, r, p_c) = 0 \xrightarrow{I_R} f\left(\frac{Rp}{r^2}, \frac{R}{r}, \frac{R}{r^2} p_c\right) = 0,$$

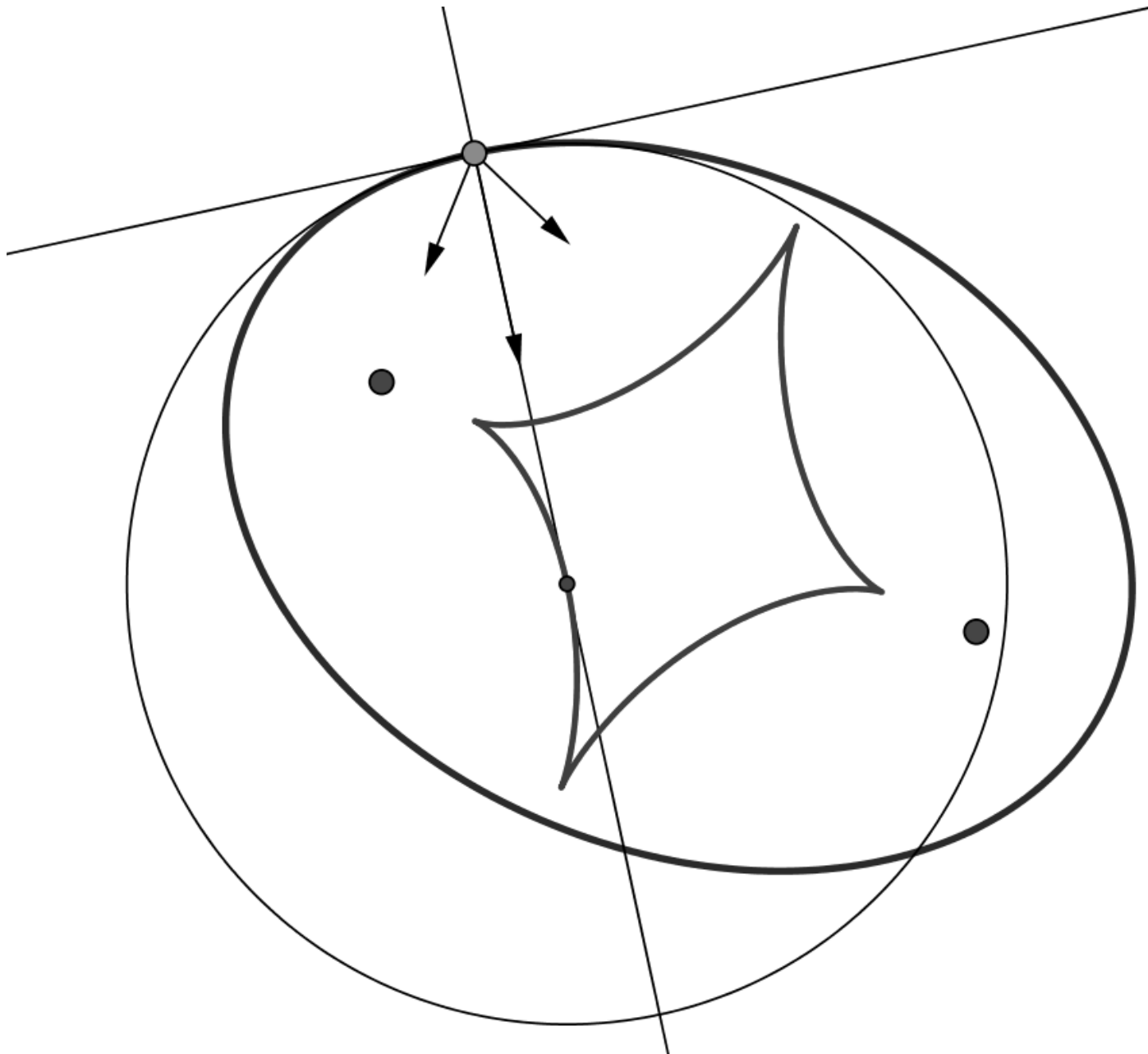
$$f(p, r^2, p_c) = 0 \xrightarrow{E_c} f(p - c, r^2 - 2pc + c^2, p_c) = 0,$$

$$f\left(\frac{1}{p^2}, r; \frac{r^2}{p^2}\right) = 0 \xrightarrow{J_\alpha} f\left(r^{2-2\alpha} \left(\frac{\alpha^2}{p^2} + \frac{1-\alpha^2}{r^2}\right), r^\alpha; \alpha^2 \frac{r^2}{p^2} + \alpha^2 - 1\right) = 0,$$

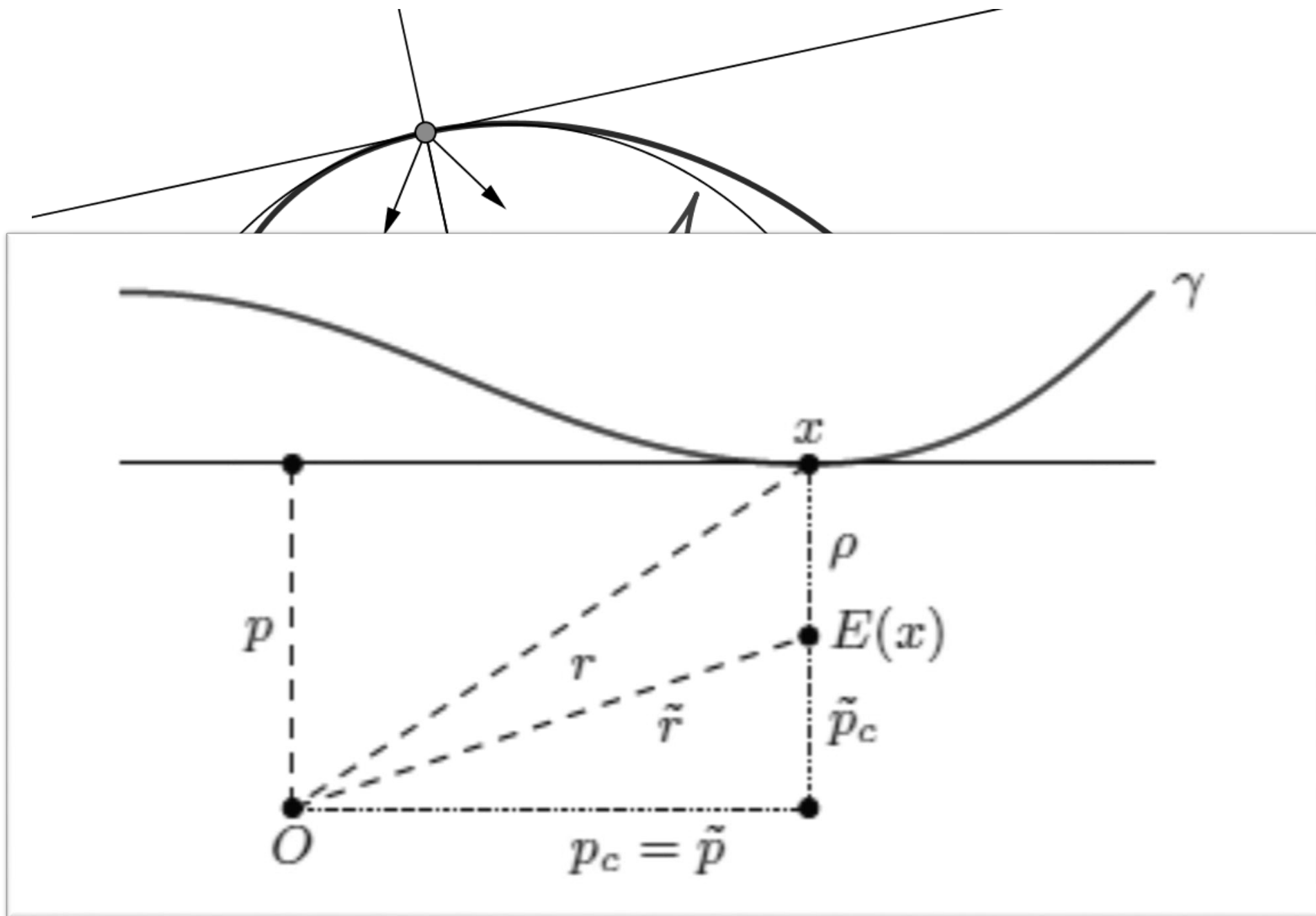
$$f\left(\frac{1}{p^2}, r\right) = 0 \xrightarrow{H_k} f\left(\frac{k^2}{p^2} - \frac{k^2 - 1}{r^2}, r\right) = 0,$$

$$\frac{(L - G(r^2))^2}{p^2} = F(r^2) + c \xrightarrow{R_\omega} \frac{(L - G(r^2) + \omega r^2)^2}{p^2} = F(r^2) + \omega^2 r^2 - 2G\omega + c + 2\omega L,$$

Evolute



Evolute



Evolute

PROPOSITION 2. *The evolute $E(\gamma)$ of a curve γ which satisfies*

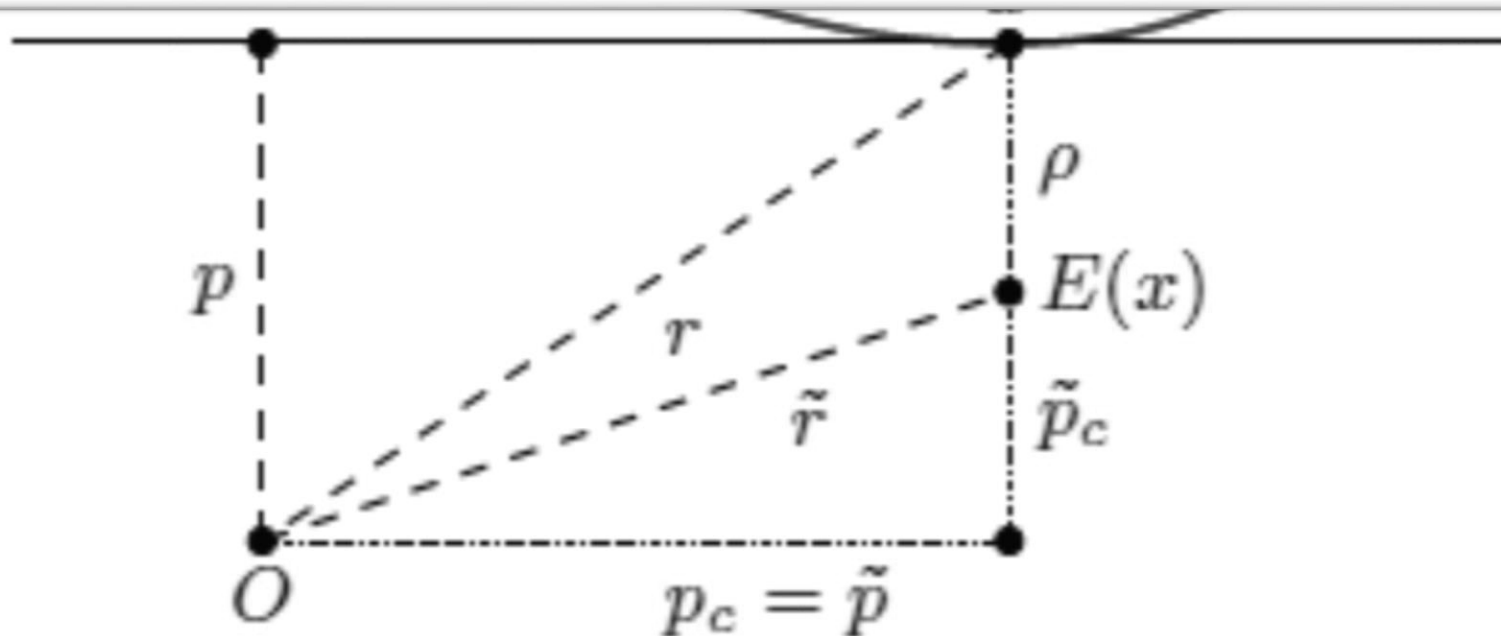
$$f\left(p_c, p_c p'_c, (p_c p'_c)' p_c, \dots, (p_c \partial_p)^n p\right) = 0,$$

where $n > 1$, satisfies

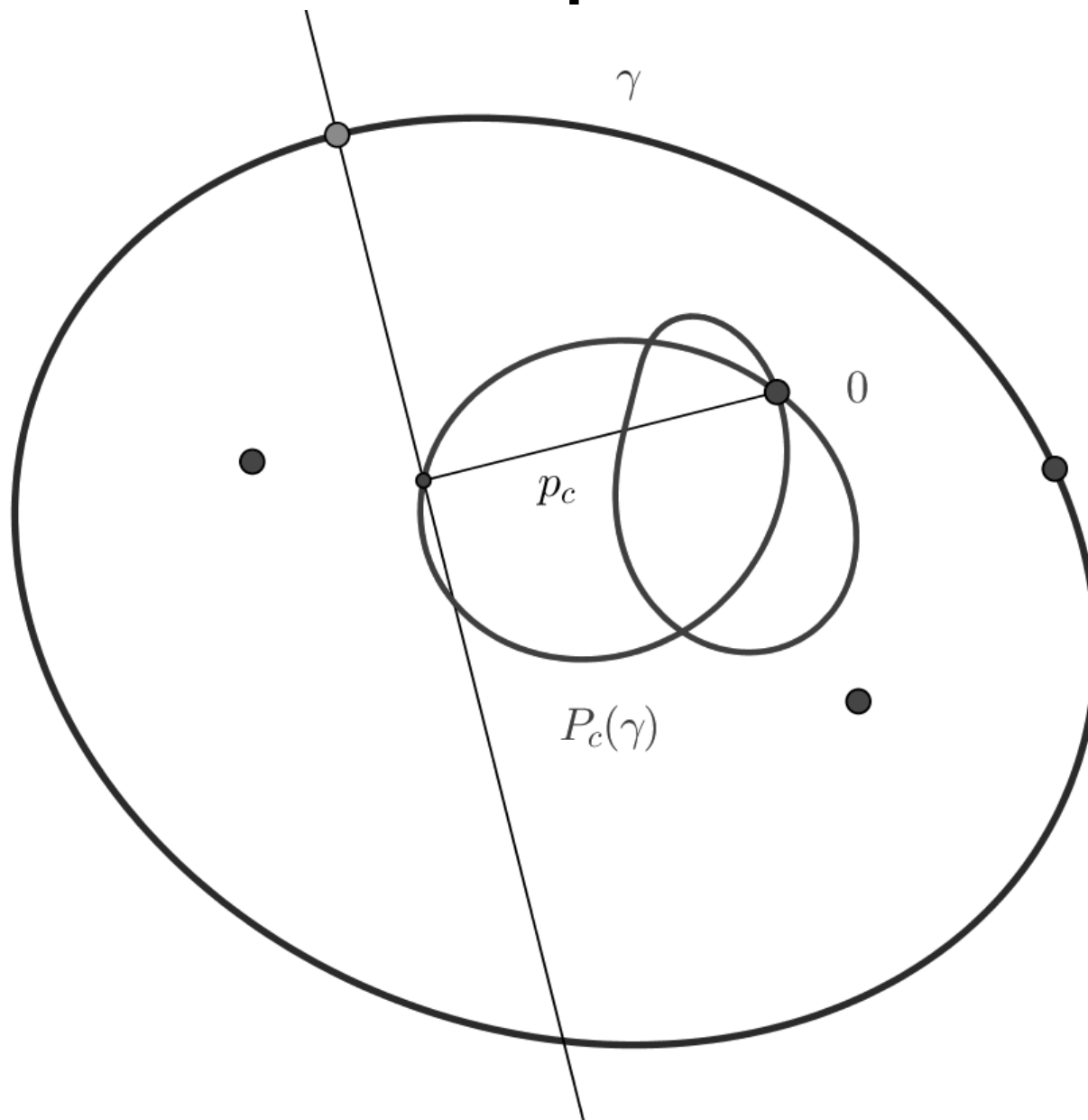
$$f\left(p, p_c, p_c p'_c, (p_c p'_c)' p_c, \dots, (p_c \partial_p)^{n-1} p\right) = 0.$$

In other words

$$f\left(p_c, p_c p'_c, \dots, (p_c \partial_p)^n p\right) = 0, \quad \xrightarrow{E} \quad f\left(p, p_c, p_c p'_c, \dots, (p_c \partial_p)^{n-1} p\right) = 0.$$



Contrapedal



Contrapedal



COROLLARY 2.

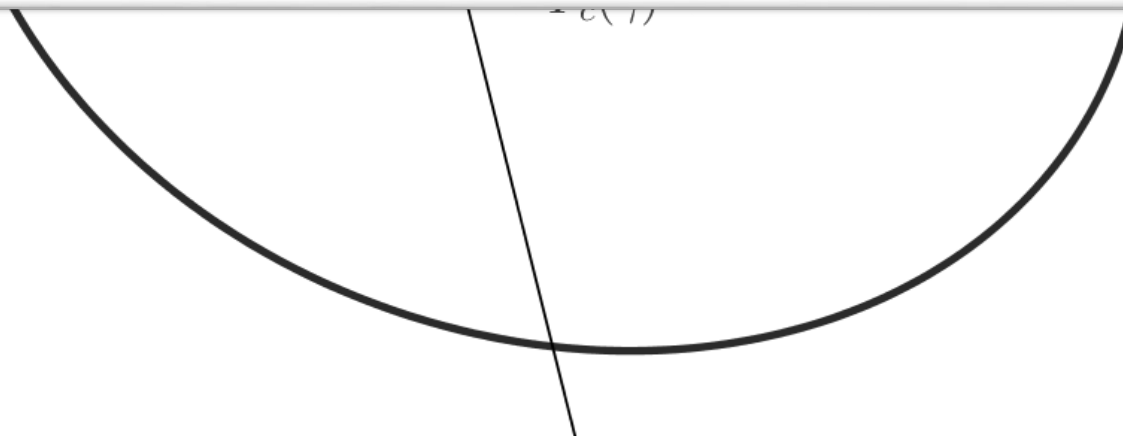
$$f(p_c, p_c p'_c, \dots, (p_c \partial_p)^n p) = 0, \quad P_c \xrightarrow{:= PE} P \left(f(p, p_c, p_c p'_c, \dots, (p_c \partial_p)^{n-1} p) = 0 \right),$$

or using Proposition 1:

$$f(p_c, p_c p'_c, \dots, (p_c \partial_p)^n p) = 0 \quad \xrightarrow{P_c} \quad f(r, |r'_\varphi|, r''_\varphi, \dots, r^{(n-1)}_\varphi) = 0.$$

Equivalently, we can say:

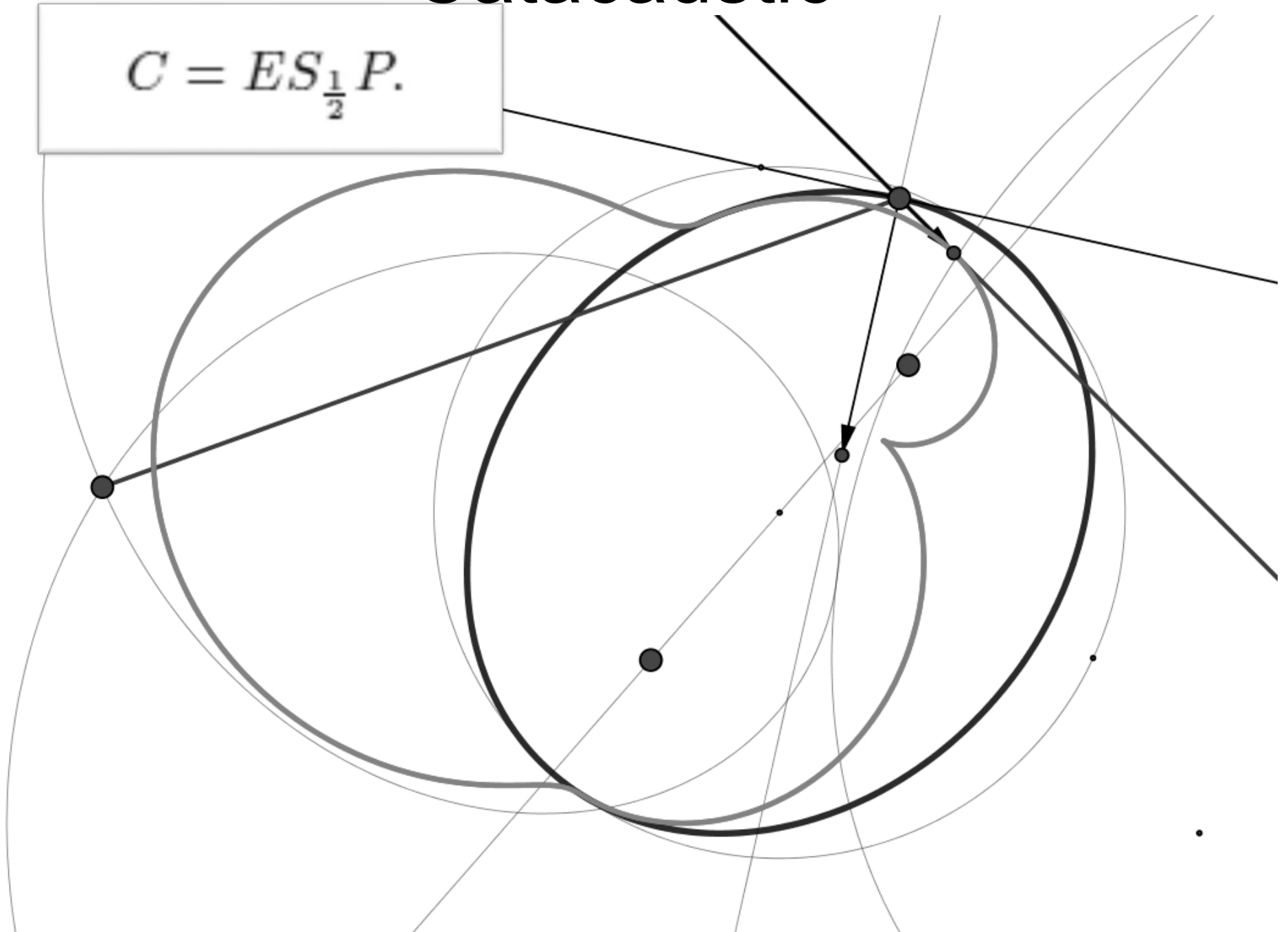
$$f(|r'_\varphi|, r''_\varphi, \dots, r^{(n)}_\varphi) = 0 \quad \xrightarrow{PEP^{-1}} \quad f(r, |r'_\varphi|, r''_\varphi, \dots, r^{(n-1)}_\varphi) = 0.$$



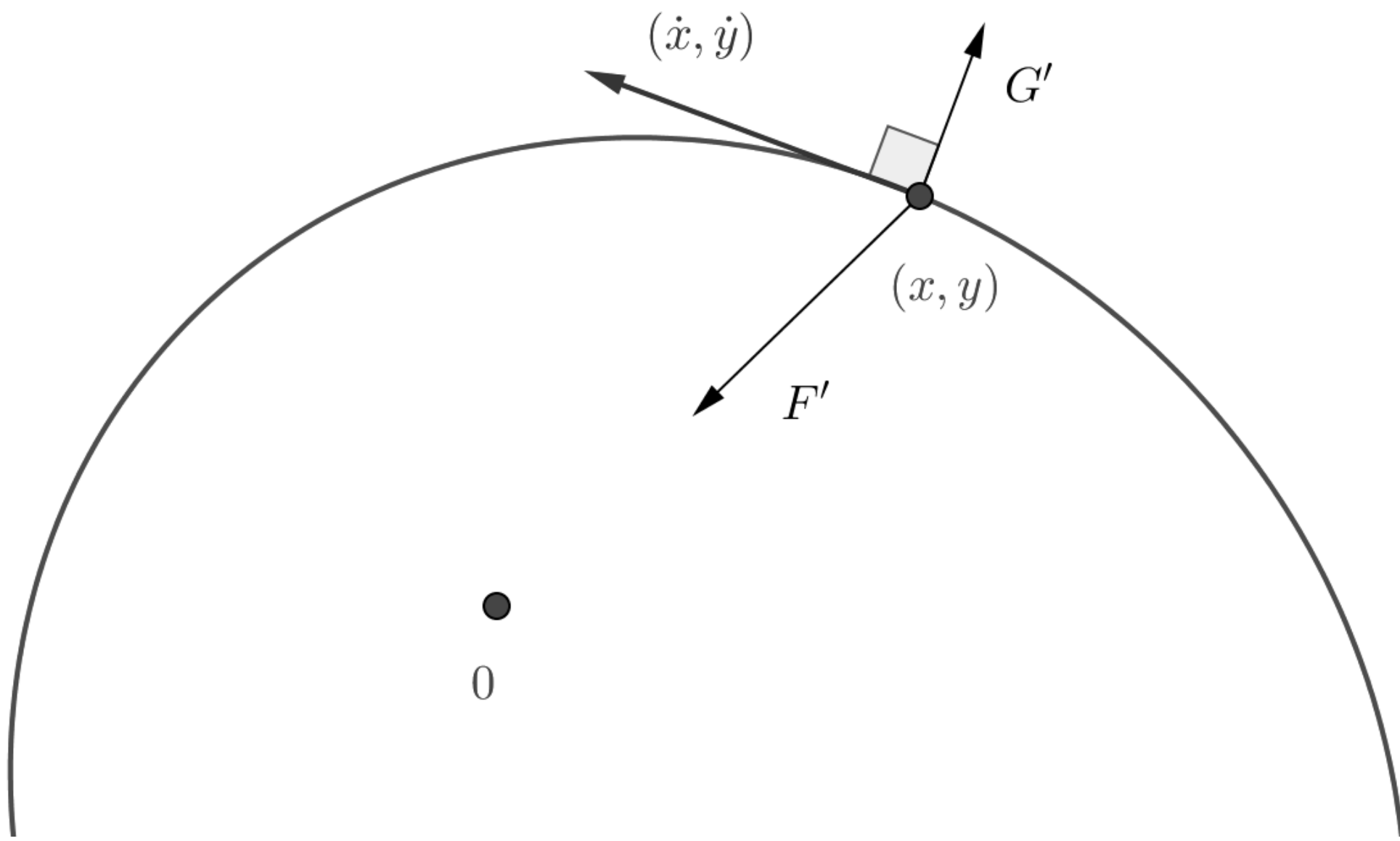
[illegible]

Catacaustic

$$C = ES_{\frac{1}{2}}P.$$

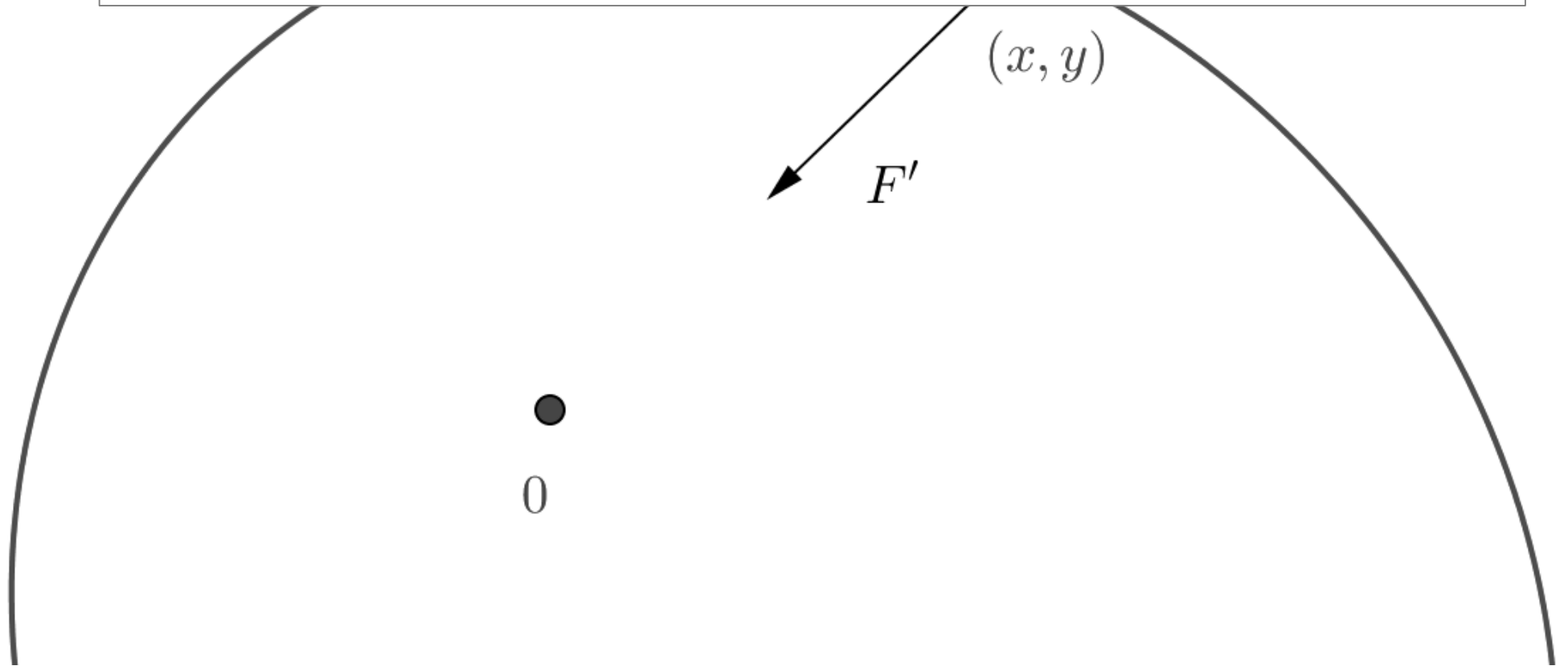


Force problems



Force problems

$$\begin{aligned}\ddot{x} &= F' (x^2 + y^2) x - 2G' (x^2 + y^2) \dot{y}, \\ \ddot{y} &= F' (x^2 + y^2) y + 2G' (x^2 + y^2) \dot{x}.\end{aligned}$$



Force problems

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$$rr'' - 2r'^2 + 2G'(r^2)r'^2 - r^2 + \frac{2r^4G'(r^2)}{(G(r^2) + L)} = \frac{F'(r^2)r^6}{(G + L)^2}$$



0

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$$\frac{(L - G(r^2))^2}{p^2} = F(r^2) + c.$$

Force problems generalized

$$\mathbf{x} := (x, y),$$

$$\mathbf{x}^\perp := (-y, x),$$

$$\mathbf{x} \cdot \mathbf{y}^\perp = -\mathbf{x}^\perp \cdot \mathbf{y},$$

$$(\mathbf{x}^\perp)^\perp = -\mathbf{x}.$$

$$p := \frac{\mathbf{x}^\perp \cdot \dot{\mathbf{x}}}{|\dot{\mathbf{x}}|},$$

$$p_c := \frac{\mathbf{x} \cdot \dot{\mathbf{x}}}{|\dot{\mathbf{x}}|},$$

$$\kappa := \frac{\dot{\mathbf{x}}^\perp \cdot \ddot{\mathbf{x}}}{|\dot{\mathbf{x}}|^3}$$

$$\ddot{\mathbf{x}} = \frac{\partial_t (|\dot{\mathbf{x}}|)}{p_c} \mathbf{x} + \frac{\partial_t (|\dot{\mathbf{x}}| p)}{p_c |\dot{\mathbf{x}}|} \dot{\mathbf{x}}^\perp,$$

$$\mathbf{x}^\perp = \frac{p}{p_c} \mathbf{x} + \frac{r^2}{p_c |\dot{\mathbf{x}}|} \dot{\mathbf{x}}^\perp,$$

$$\dot{\mathbf{x}} = \frac{|\dot{\mathbf{x}}|}{p_c} \mathbf{x} + \frac{p}{p_c} \dot{\mathbf{x}}^\perp.$$

Force problems generalized

$$\ddot{\mathbf{x}} = f\mathbf{x} + g\dot{\mathbf{x}}^\perp,$$

$$\frac{(\int g r dr)^2}{p^2} = 2 \int f r dr,$$

$$\mathbf{x} := (x, y),$$

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$$\ddot{\mathbf{x}} = \frac{\partial_t(|\dot{\mathbf{x}}|)}{p_c} \mathbf{x} + \frac{\partial_t(|\dot{\mathbf{x}}|p)}{p_c |\dot{\mathbf{x}}|} \dot{\mathbf{x}}^\perp, \quad \mathbf{x}^\perp = \frac{p}{p_c} \mathbf{x} + \frac{r^2}{p_c |\dot{\mathbf{x}}|} \dot{\mathbf{x}}^\perp,$$

$$\dot{\mathbf{x}} = \frac{|\dot{\mathbf{x}}|}{p_c} \mathbf{x} + \frac{p}{p_c} \dot{\mathbf{x}}^\perp.$$

Force problems generalized

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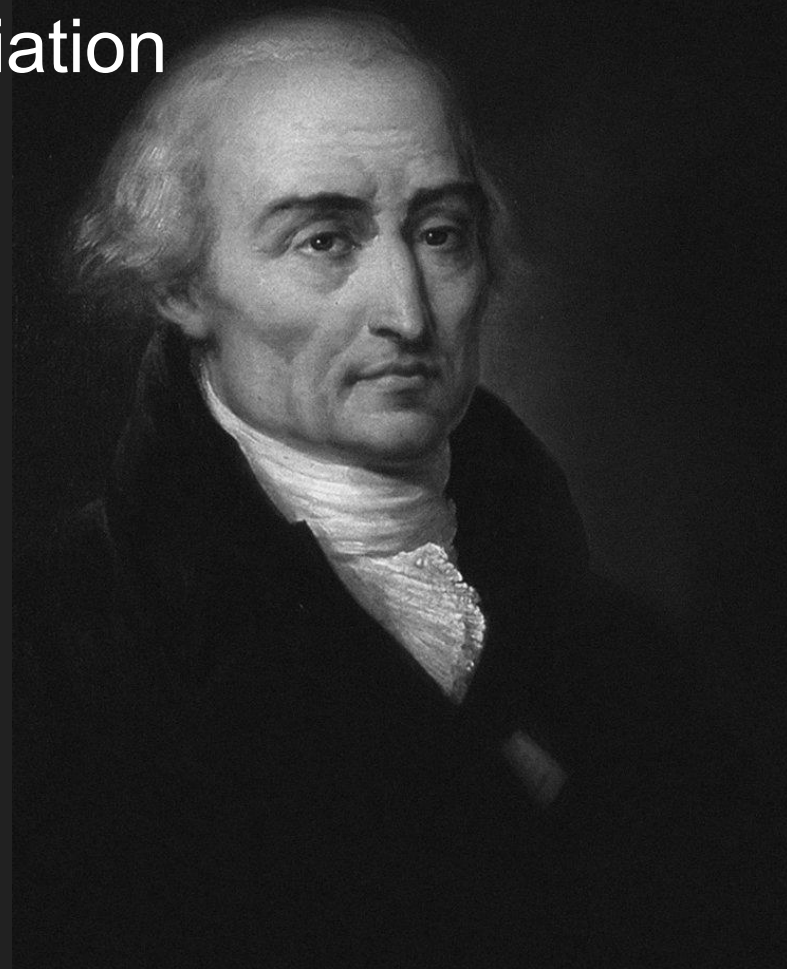
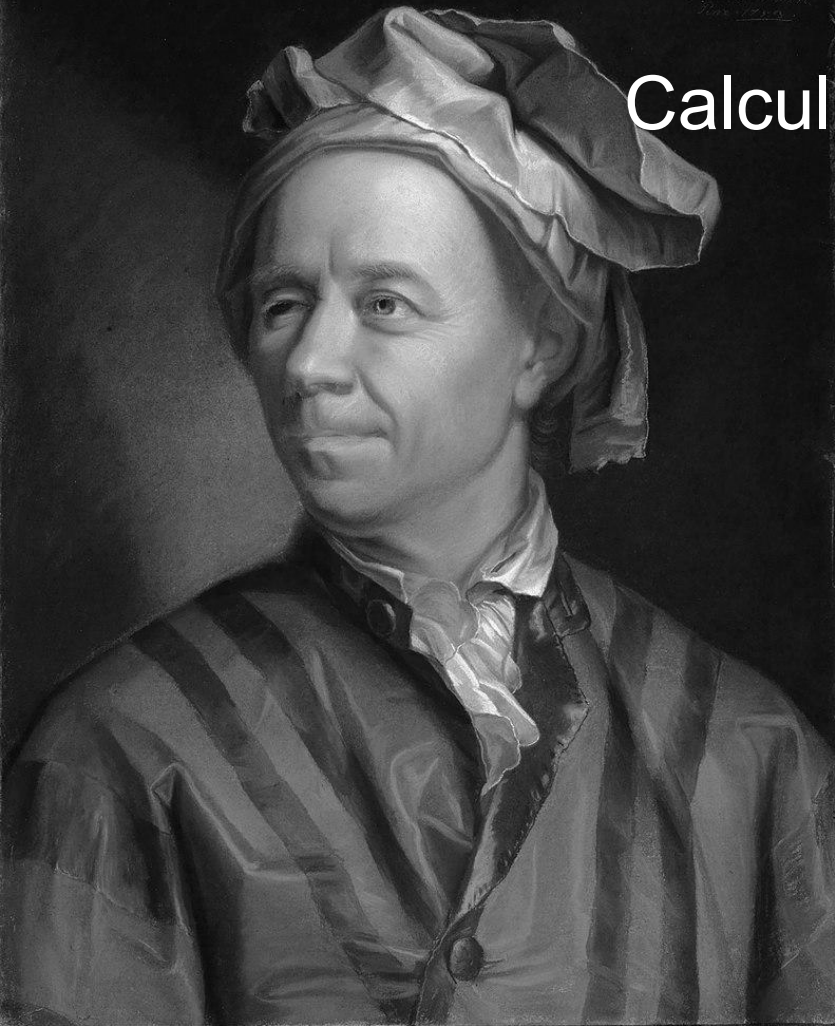
$$\mathbf{x}^\perp = \frac{p}{p_c} \mathbf{x} + \frac{r^2}{p_c |\dot{\mathbf{x}}|} \dot{\mathbf{x}}^\perp,$$

$$\dot{\mathbf{x}} = \frac{|\dot{\mathbf{x}}|}{p_c} \mathbf{x} + \frac{p}{p_c} \dot{\mathbf{x}}^\perp.$$

$$\ddot{\mathbf{x}} = f \frac{\mathbf{x}}{|\dot{\mathbf{x}}|^\alpha} + g \frac{\dot{\mathbf{x}}^\perp}{|\dot{\mathbf{x}}|^\beta},$$

$$\left(\frac{(1+\beta) \int g p^\beta r dr}{p^{1+\beta}} \right)^{2+\alpha} = \left((2+\alpha) \int f r dr \right)^{1+\beta}, \quad \begin{matrix} \alpha \neq -2 \\ \beta \neq -1 \end{matrix}$$

Calculus of variation



PROPOSITION 1. *Any extremal curve of the functional:*

$$\mathcal{L}[r] := \int_{s_0}^{s_1} f(r) ds,$$

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is the arc-length measure, has pedal equation

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REMARK 3. The constant L is actually a conserved quantity associated to the rotational symmetry of $\mathcal{L}$. The pedal equation (13) is, in fact, a conservation law.

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PROPOSITION 1. *Any extremal curve of the functional:*

$$\mathcal{L}[r] := \int_{s_0}^{s_1} f(r) ds$$

REMARK 3. The constant L is actually a conserved quantity associated to the rotational symmetry of $\mathcal{L}$. The pedal equation (13) is, in fact, a conservation law.

where

$$\mathcal{L}[r] := \int_{\varphi_0}^{\varphi_1} f(r, r'_\varphi, r''_\varphi, \dots, r_\varphi^{(n)}) d\varphi. \quad \text{is the arc-length } s = \int \sqrt{1 + y_x'^2} dx$$

(13)

Brachistochone



$$dt = \frac{ds}{|\dot{\mathbf{x}}|}, \text{ chistochrone}$$



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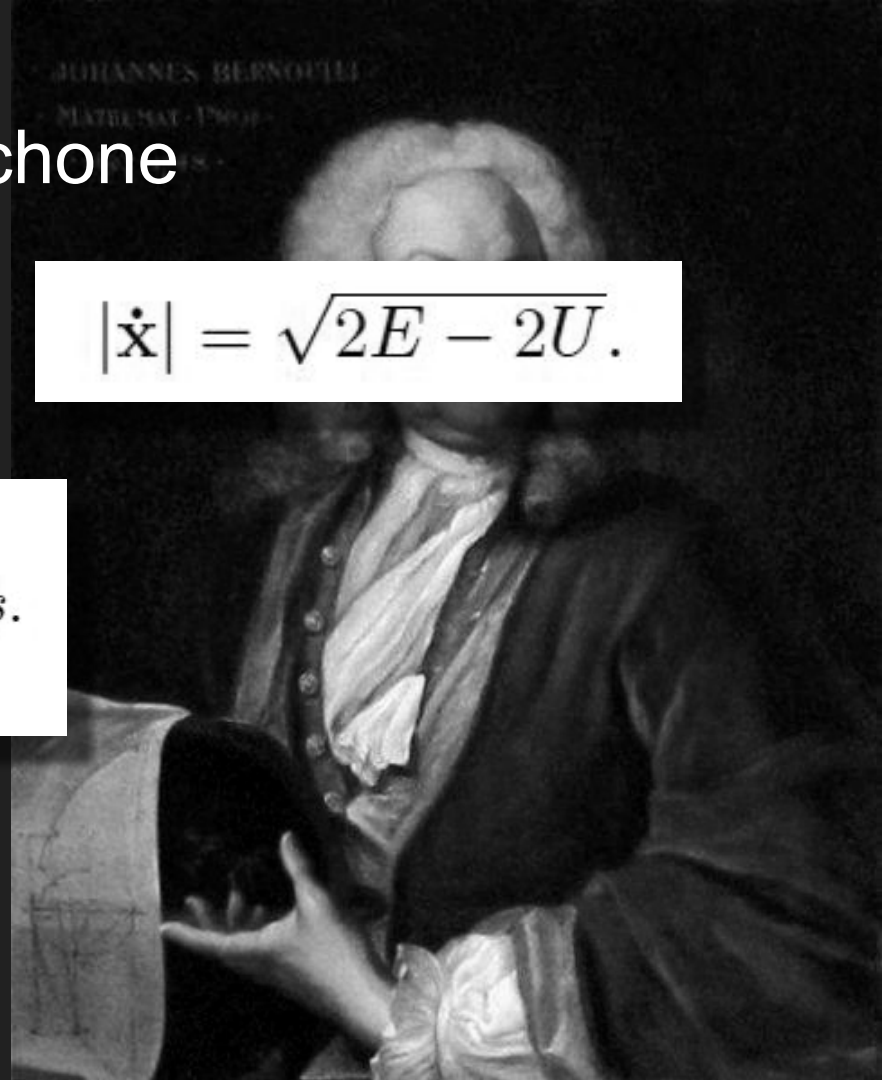


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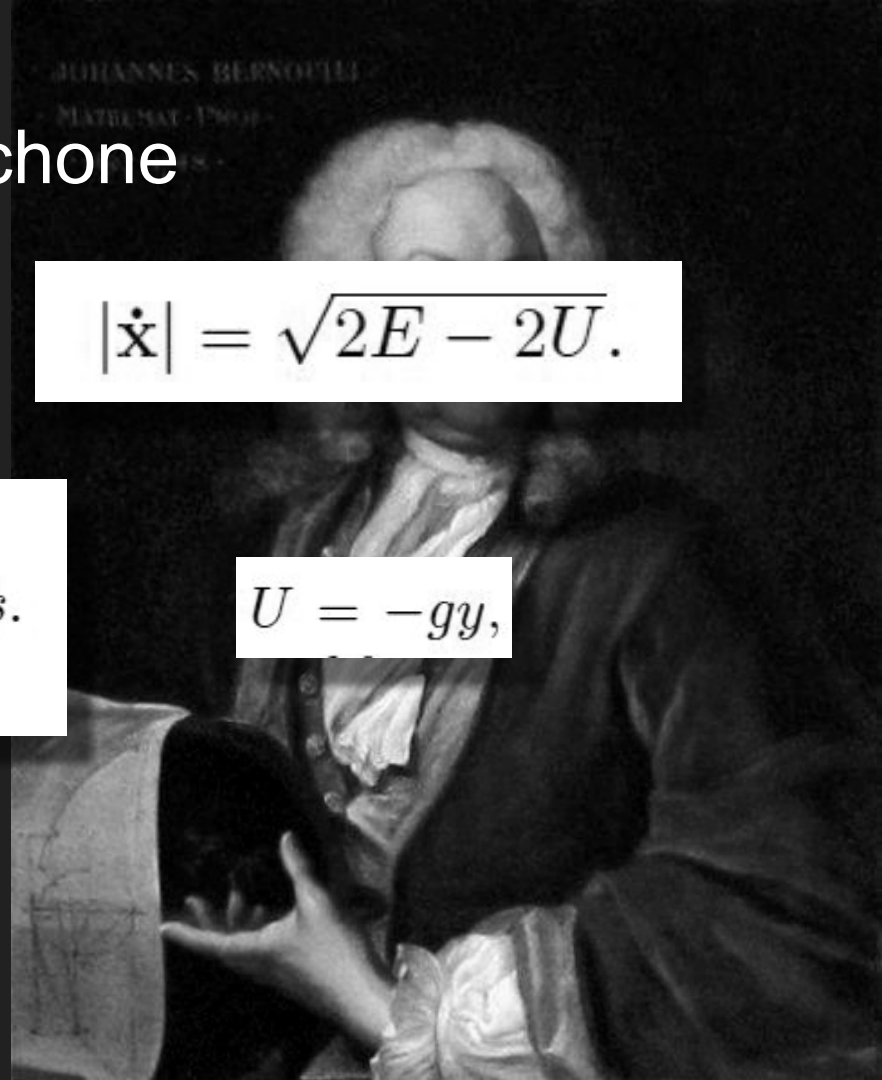
chistochrone

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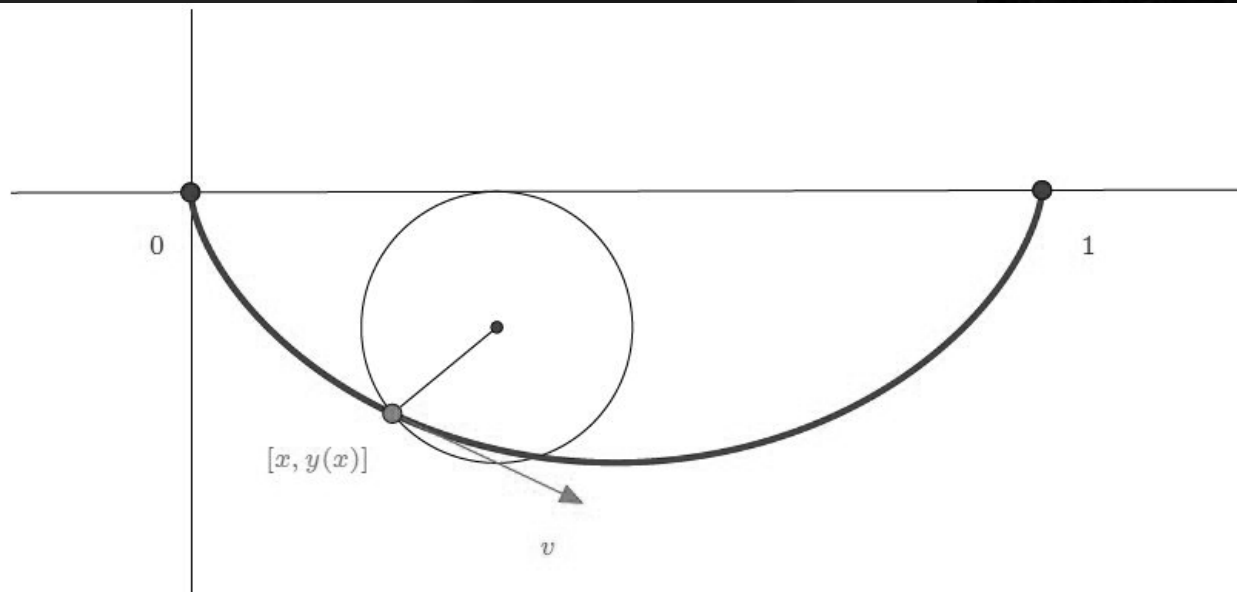
$$|\dot{\mathbf{x}}| = \sqrt{2E - 2U}.$$

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$$U = -gy,$$



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Gravity train



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ROBERT HOOKE
1635-1703

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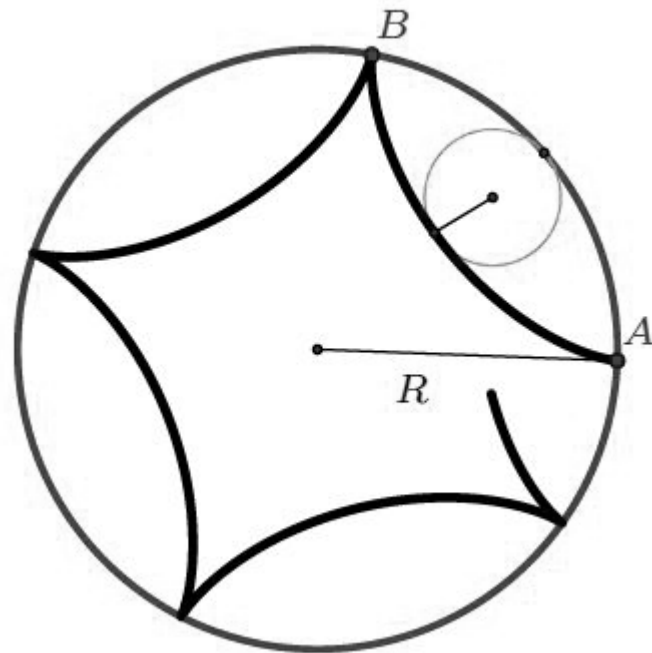


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Central Brachistochone



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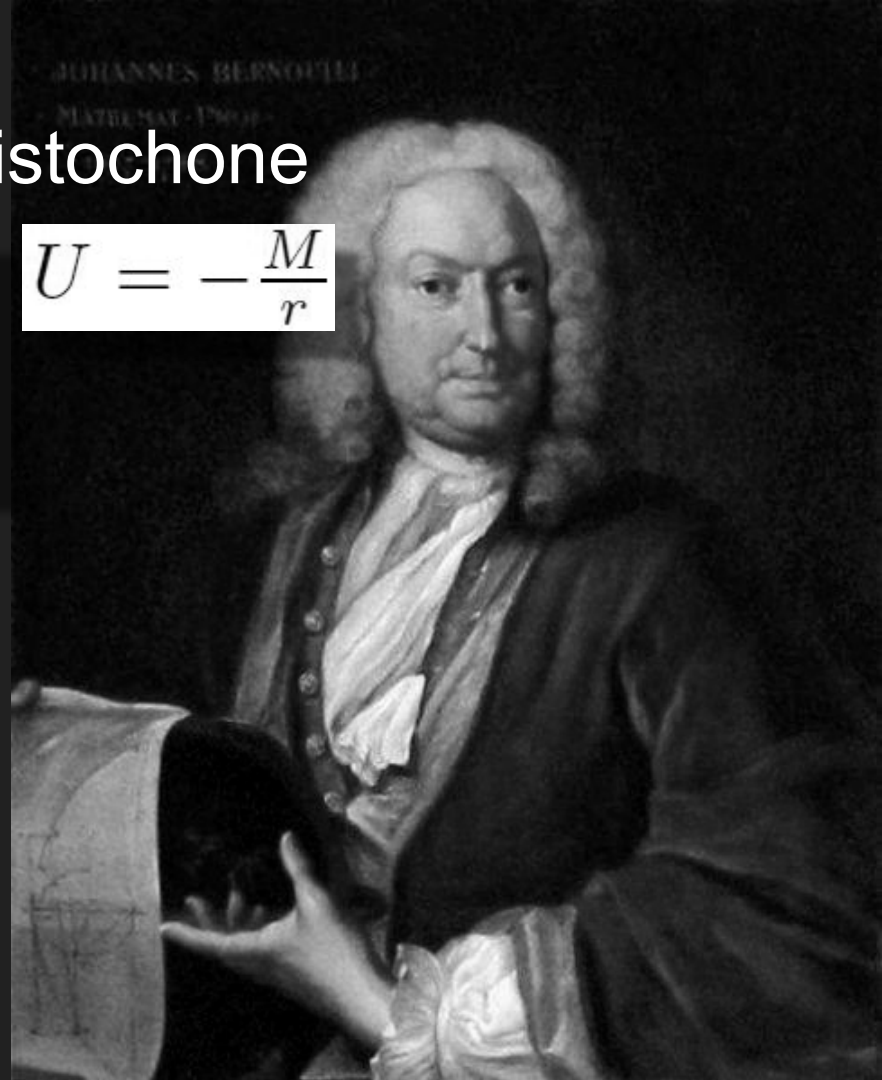
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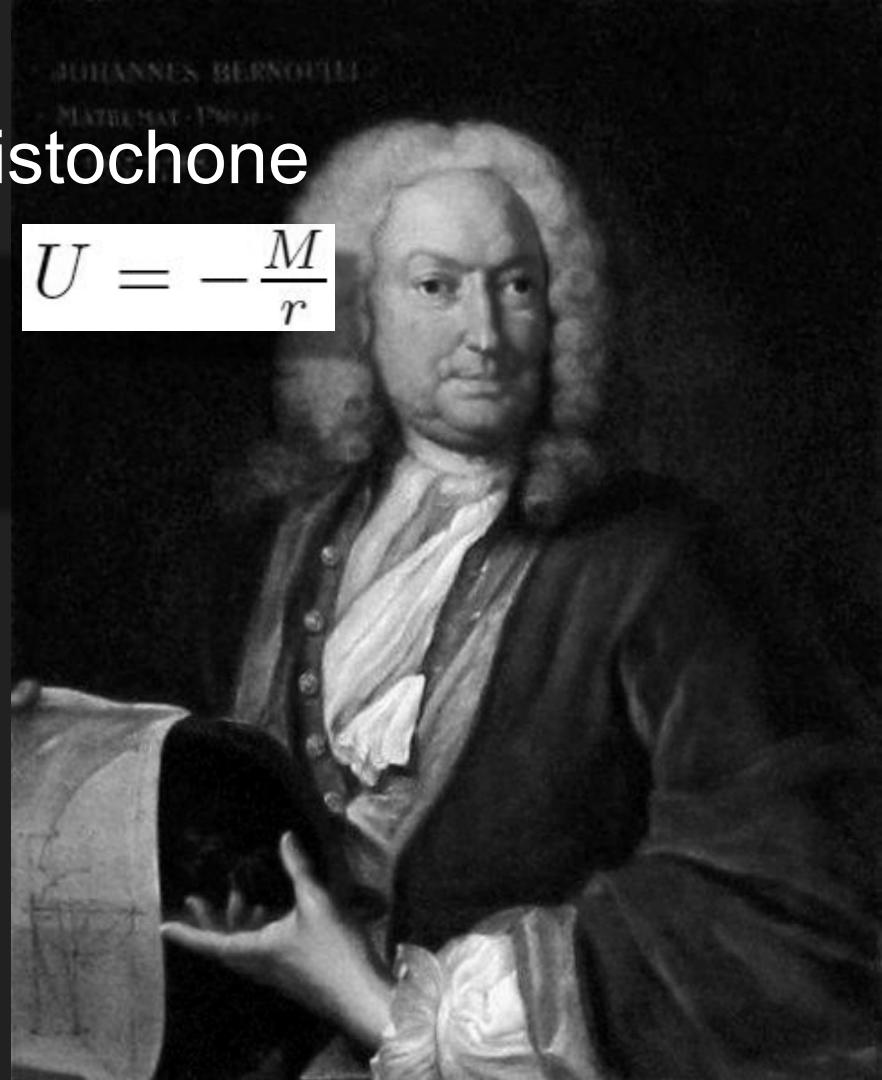


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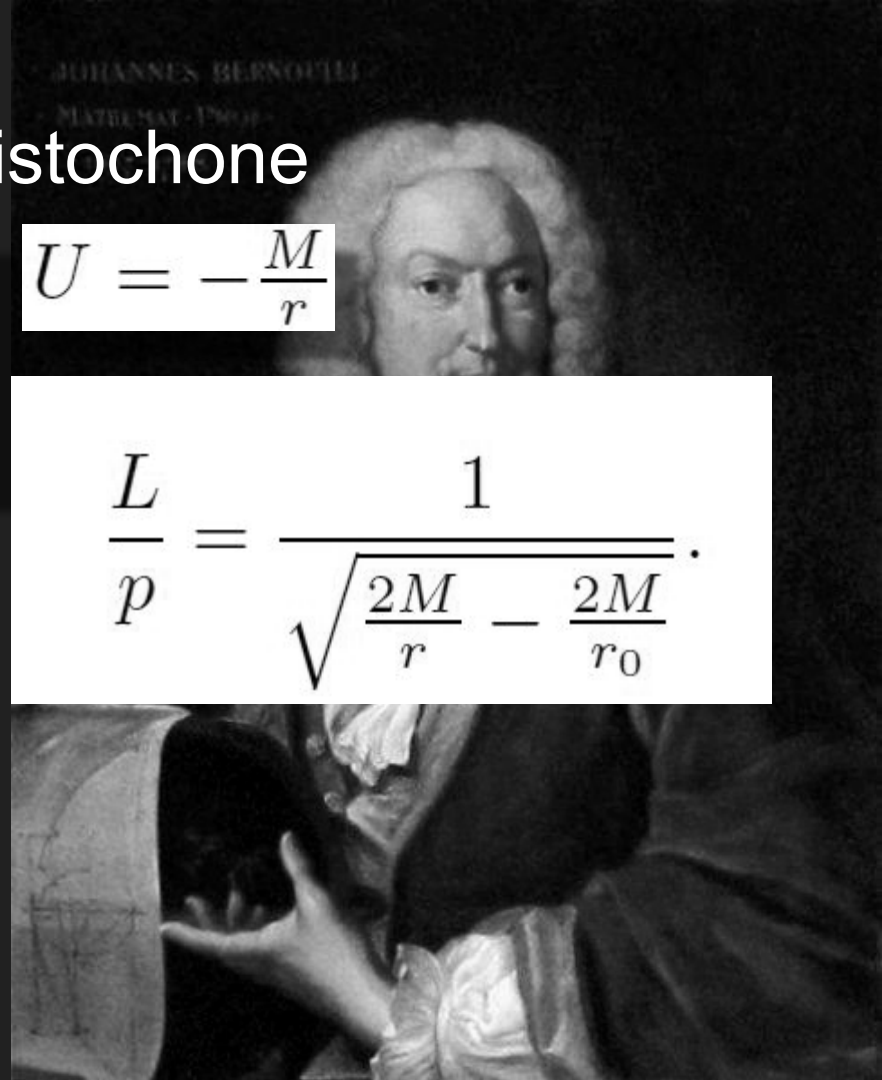
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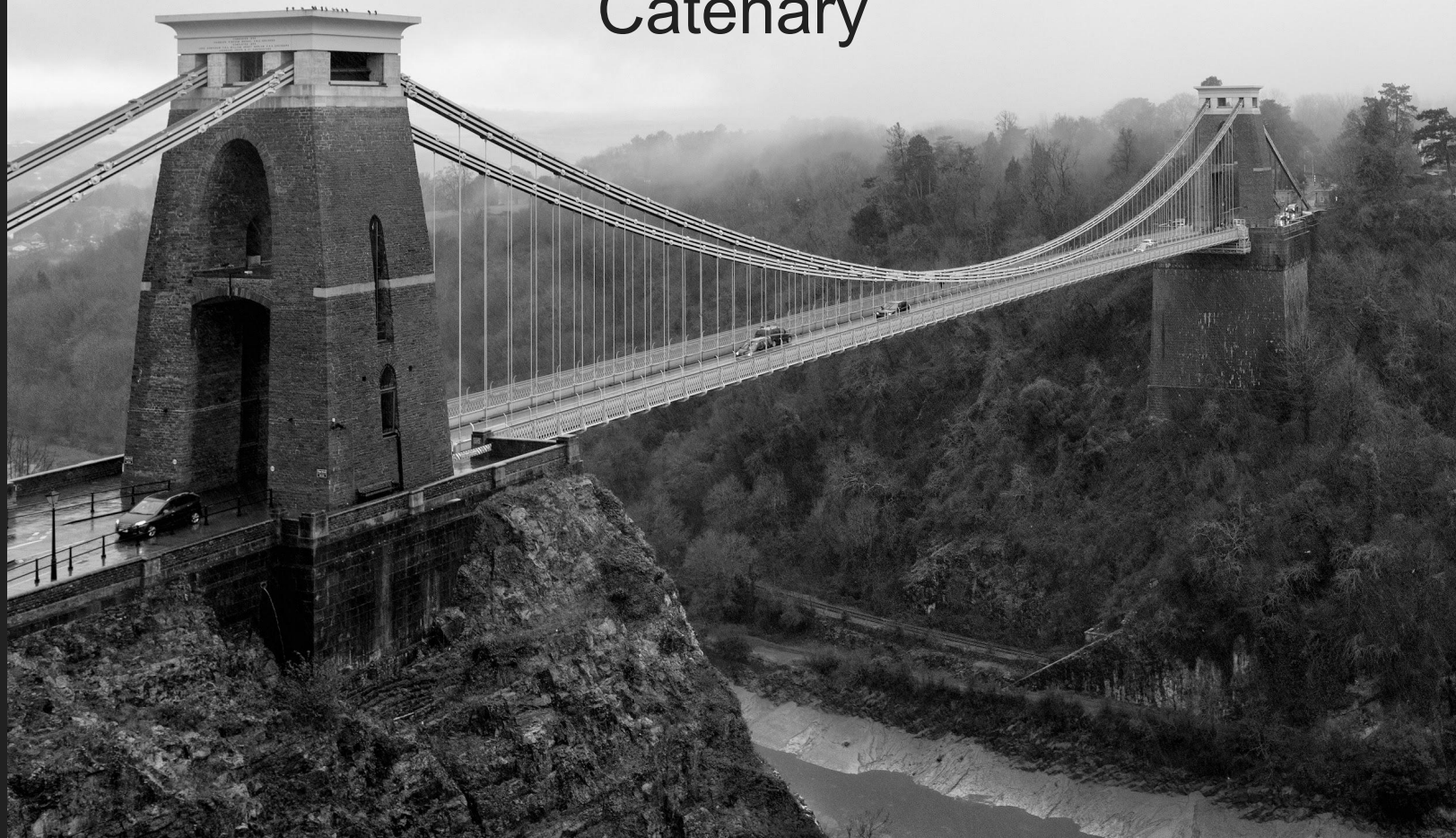
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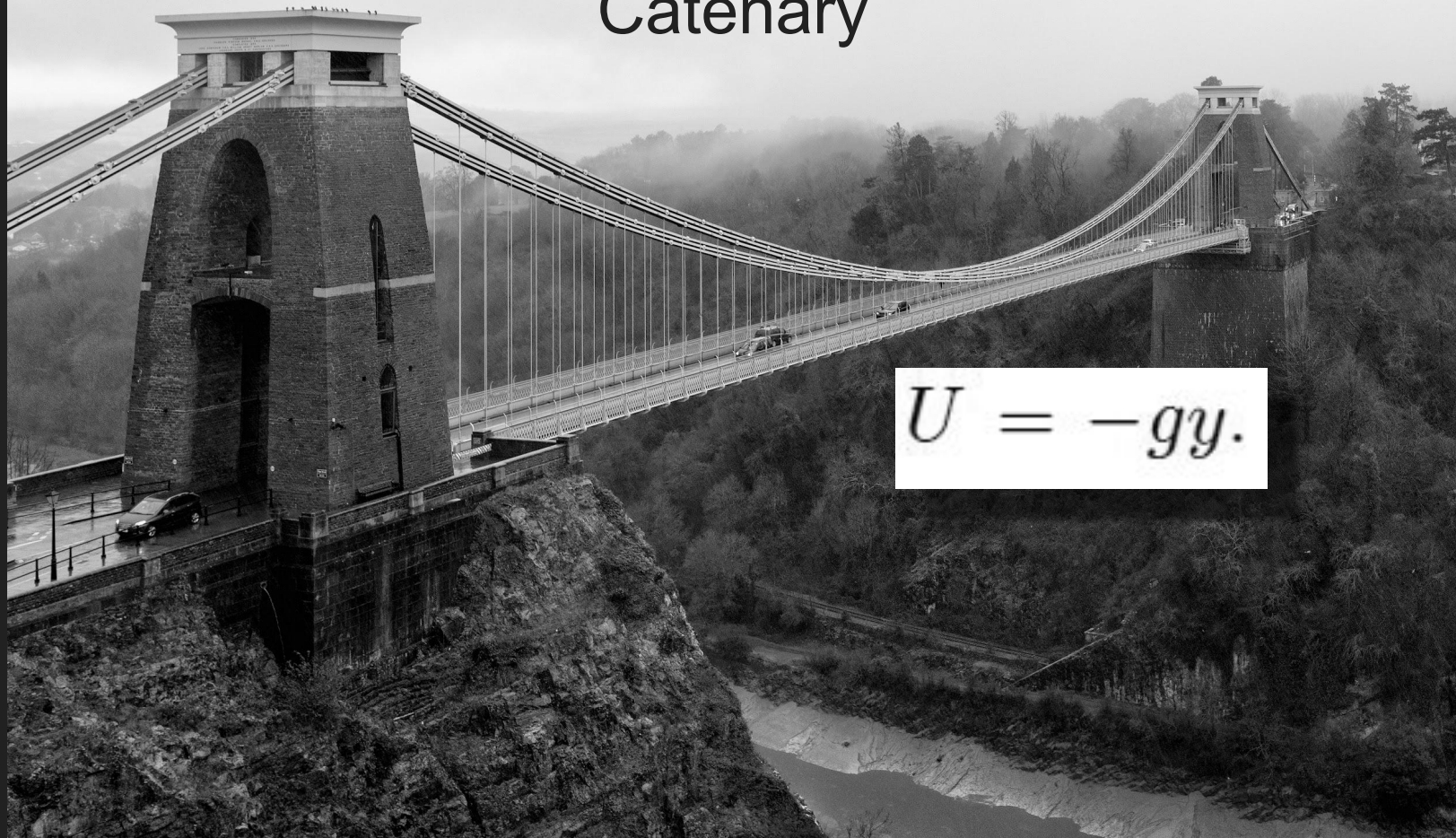
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Catenary

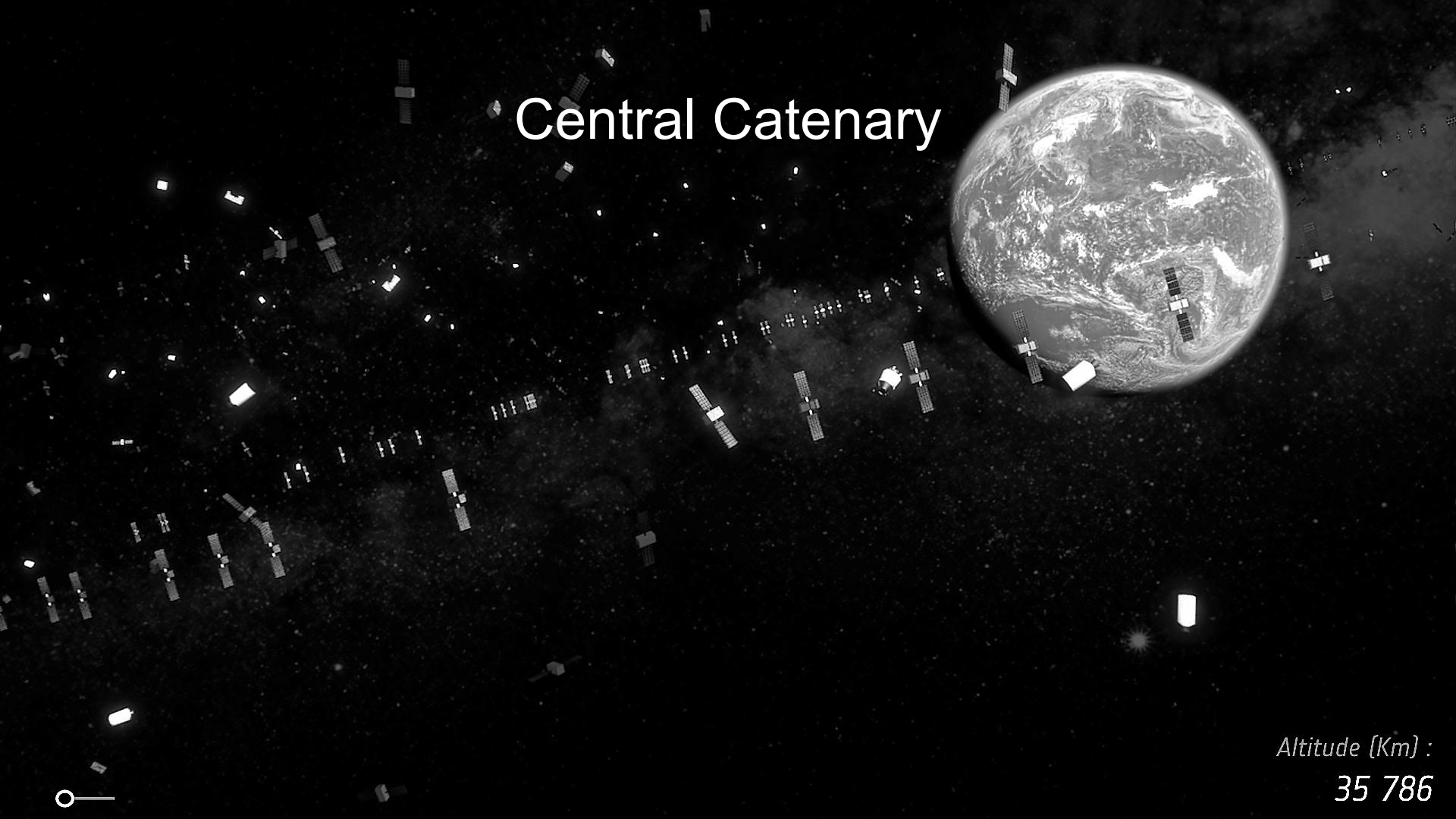


Catenary



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Central Catenary



Altitude (Km) :
35 786

Central Catenary

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Central Catenary

$$\mathcal{L} := \int_{s_0}^{s_1} \left(\frac{M}{r} + \lambda \right) ds.$$

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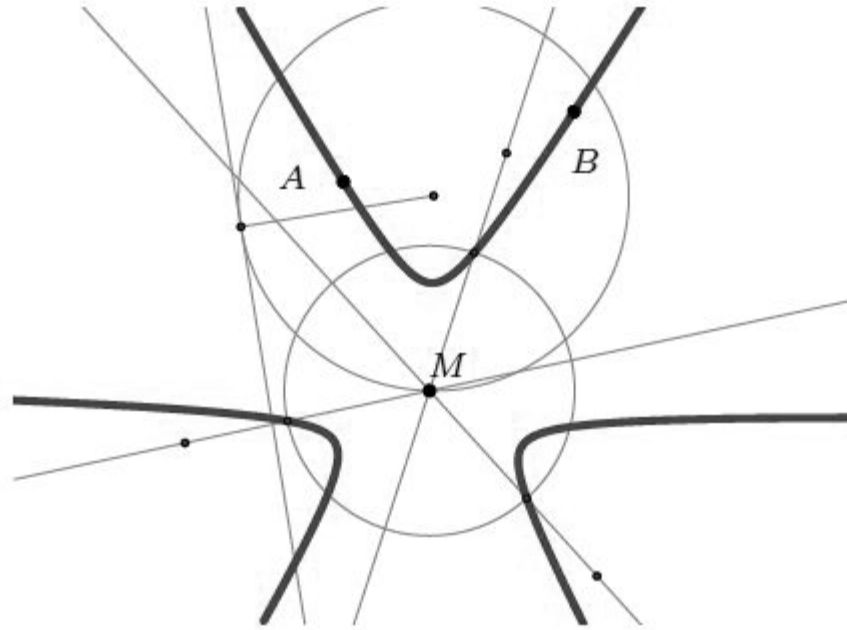
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35 786

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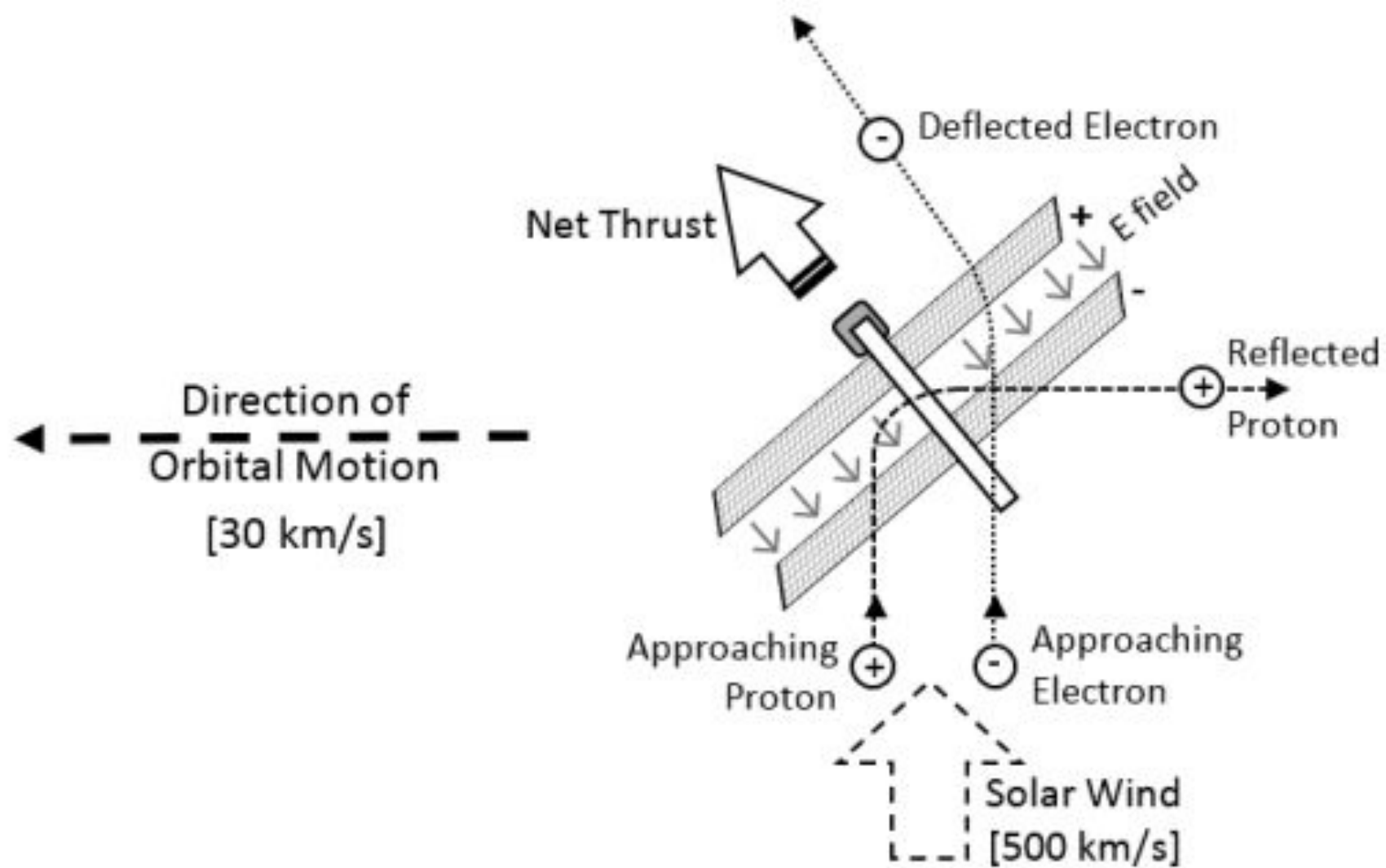
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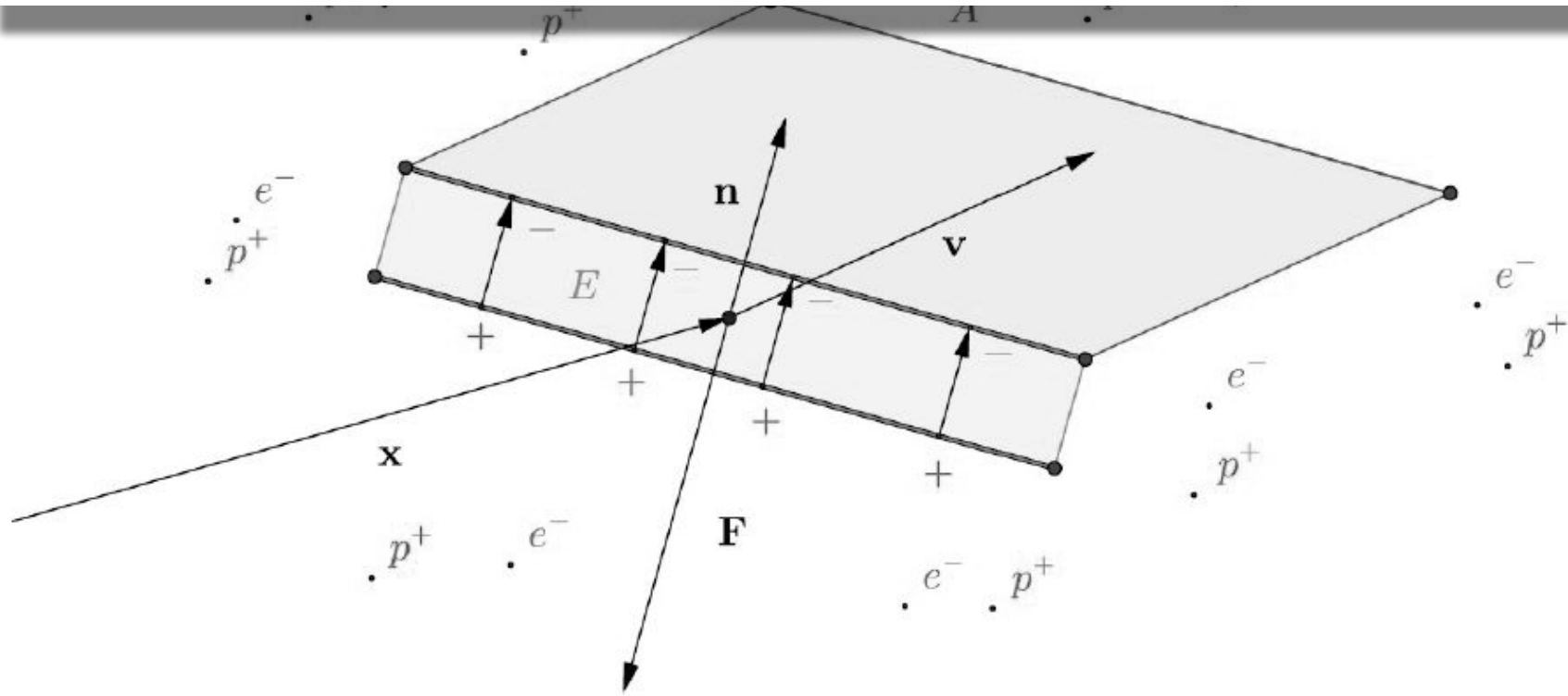
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Dipole drive by Robert Zubrin



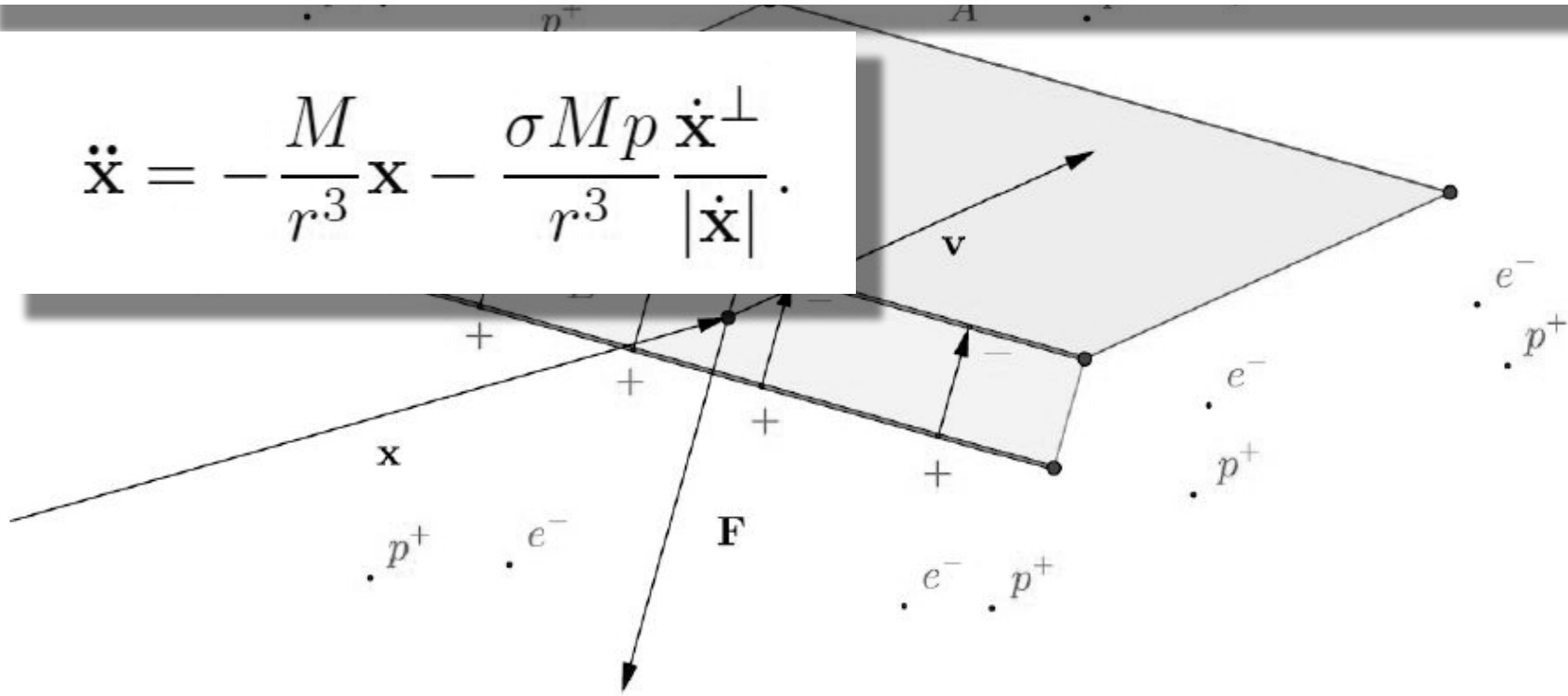


Orbits of Dipole drive pointing in direction perpendicular to motion.



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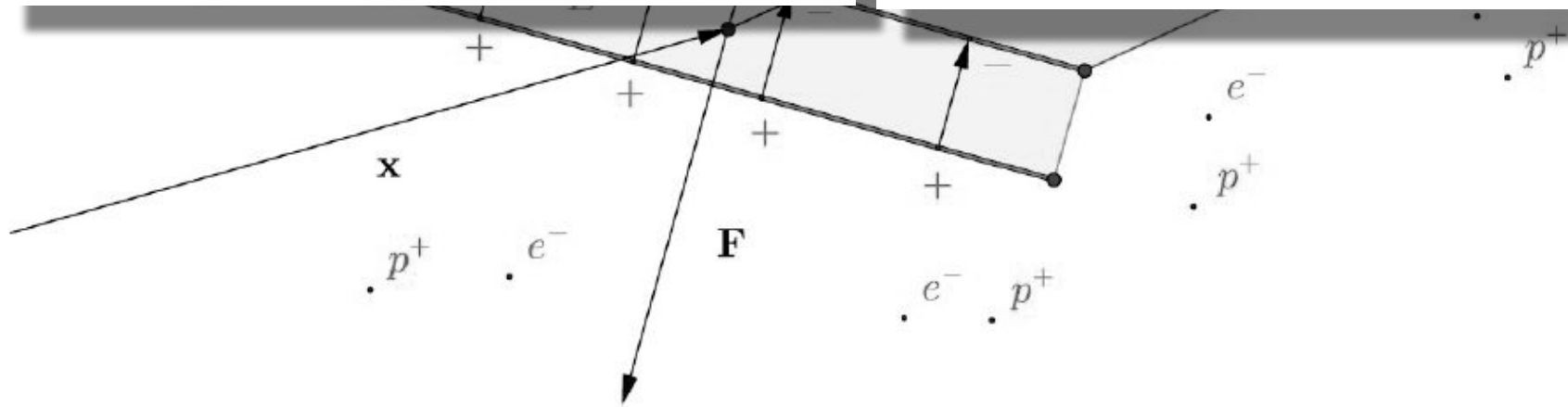
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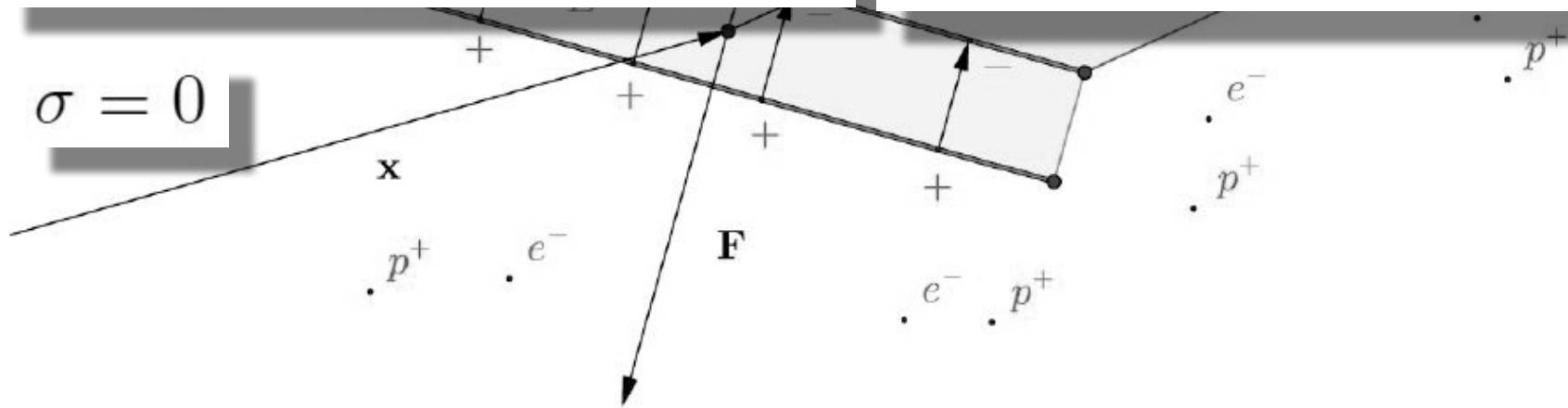


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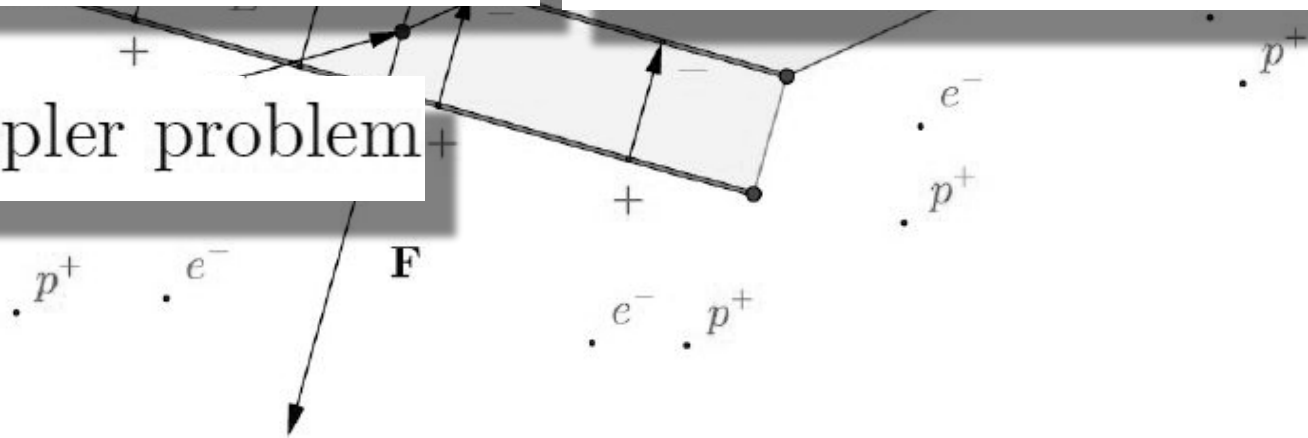
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Kepler problem



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e^-

$\mathbf{F}$

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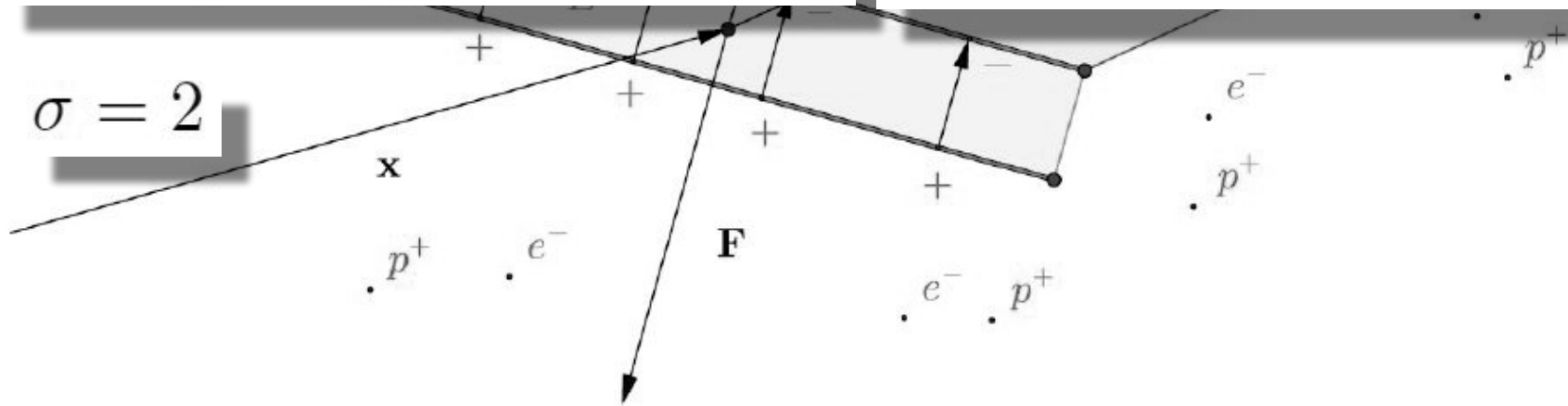
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central Catenary

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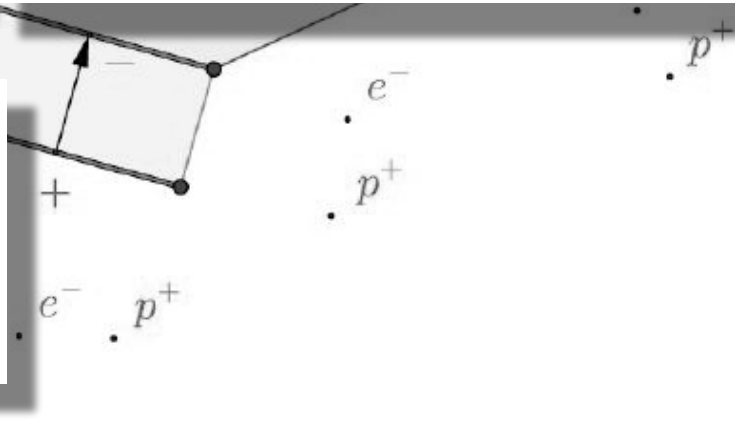
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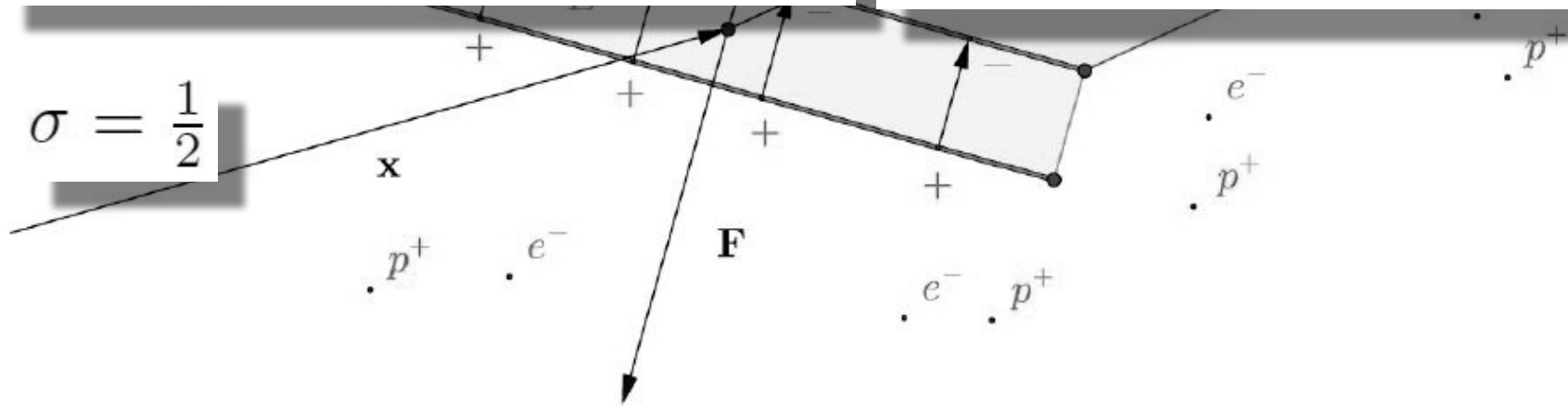
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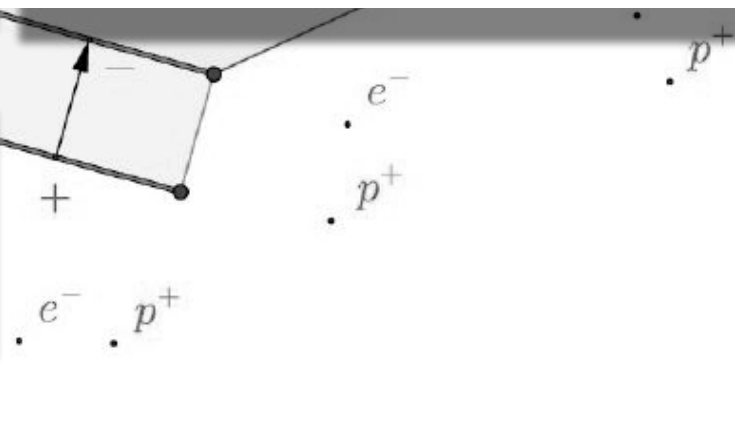
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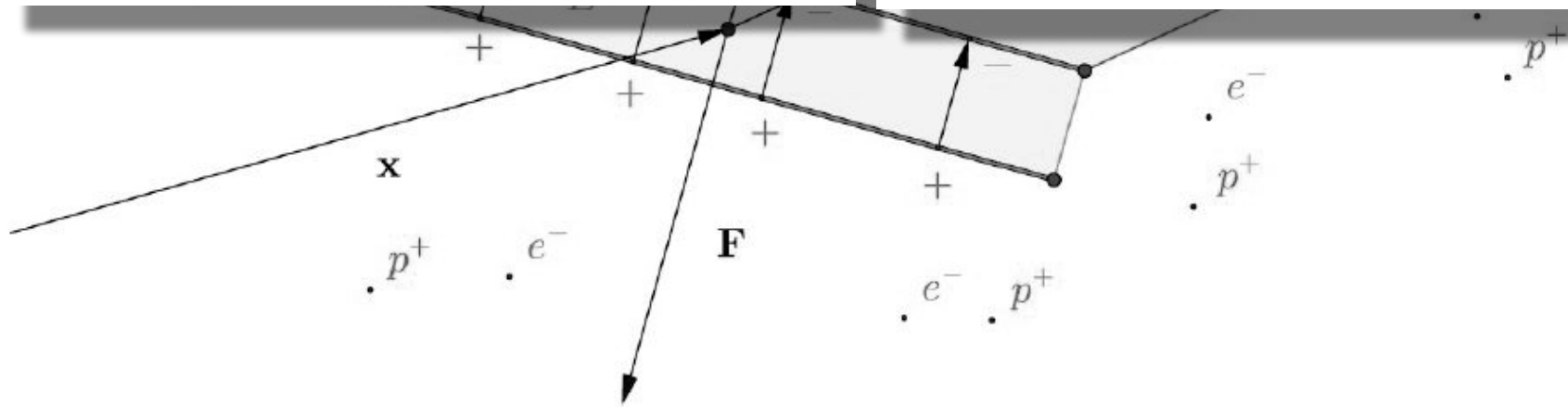
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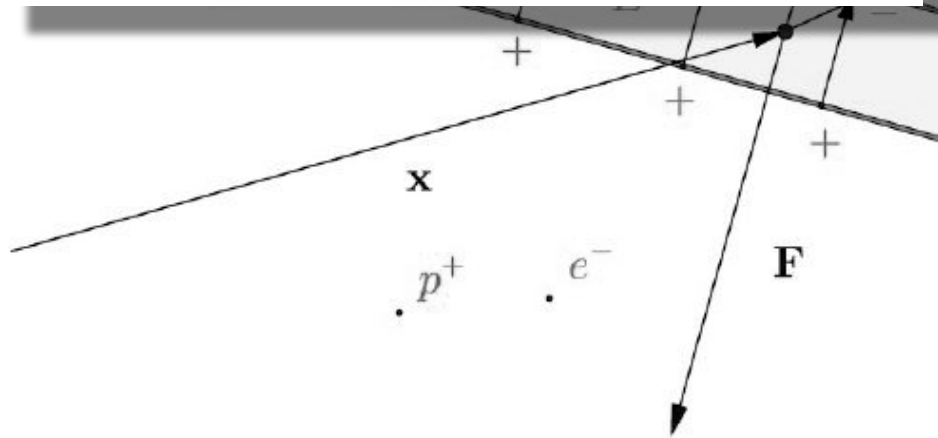
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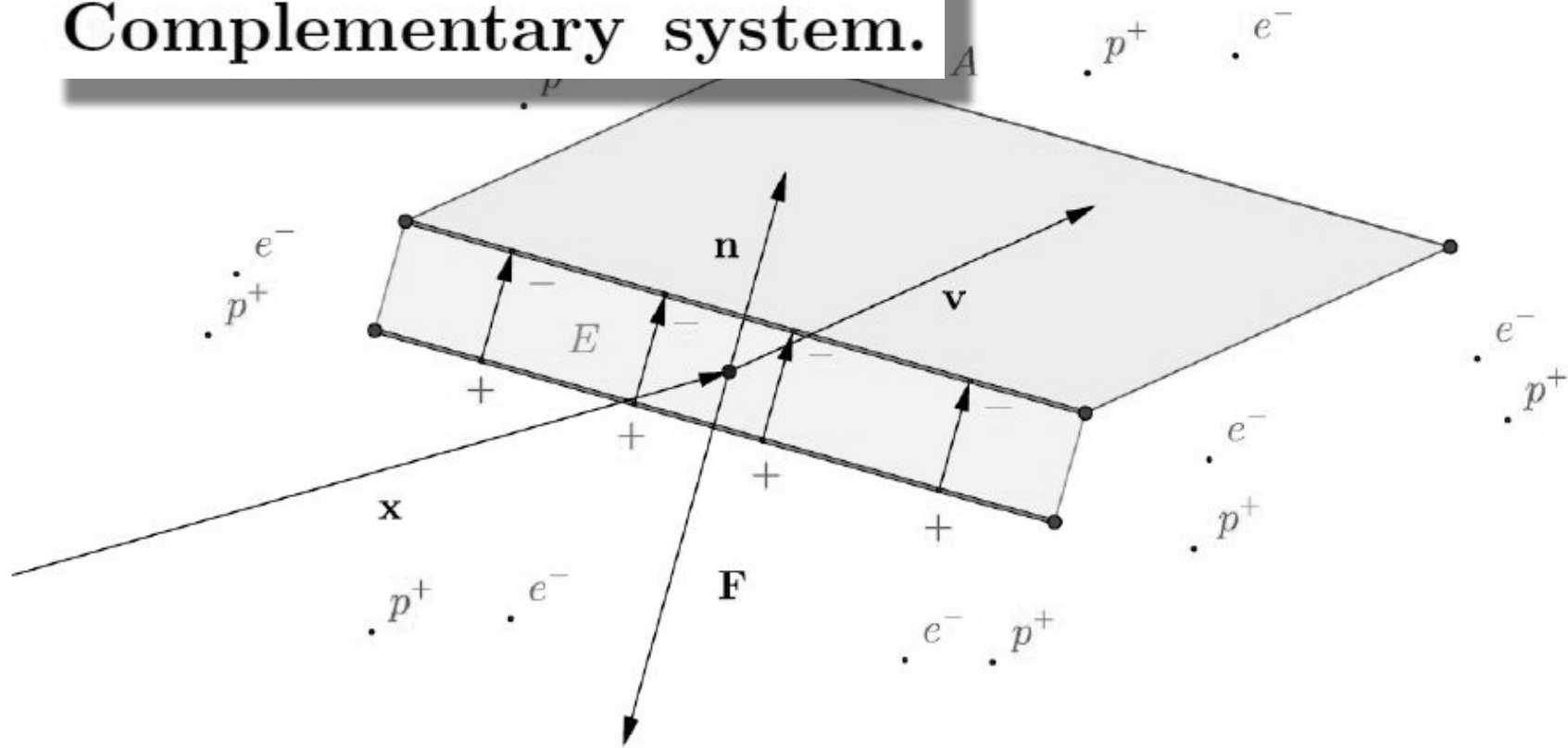
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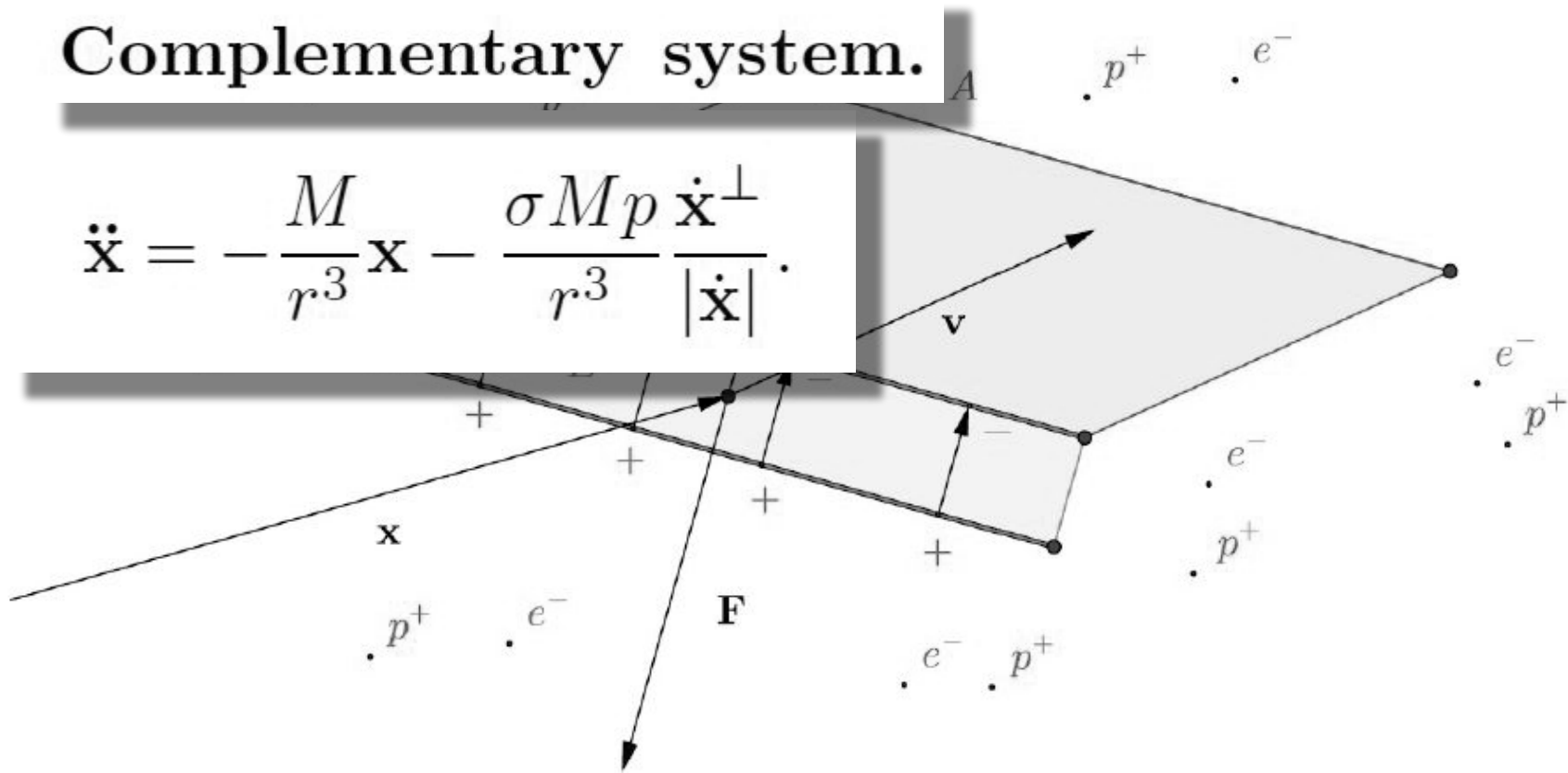
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Complementary system.



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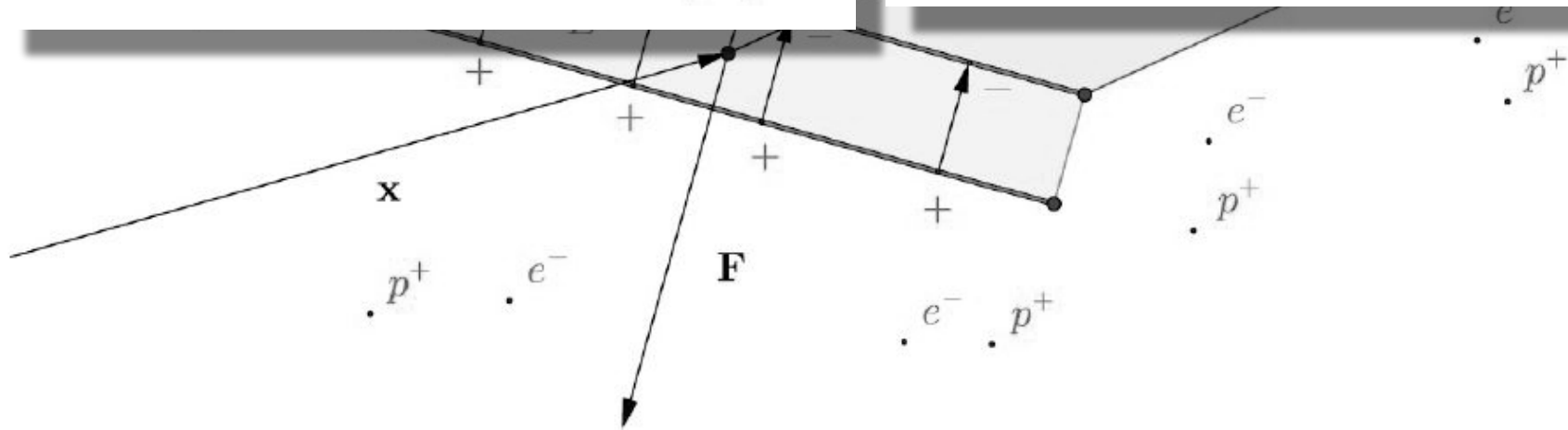


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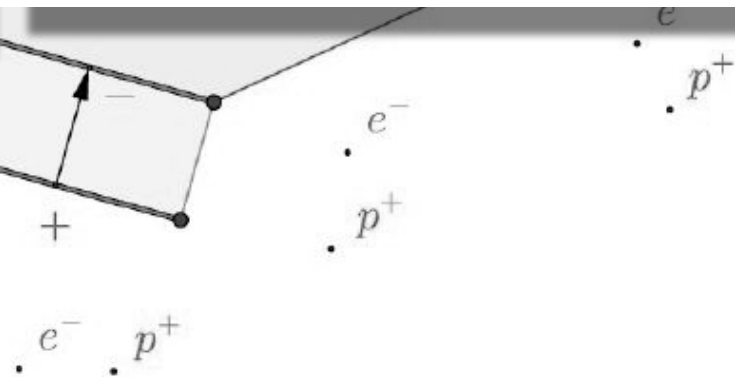
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Complementary system.

$A \quad \cdot p^+ \quad \cdot e^-$

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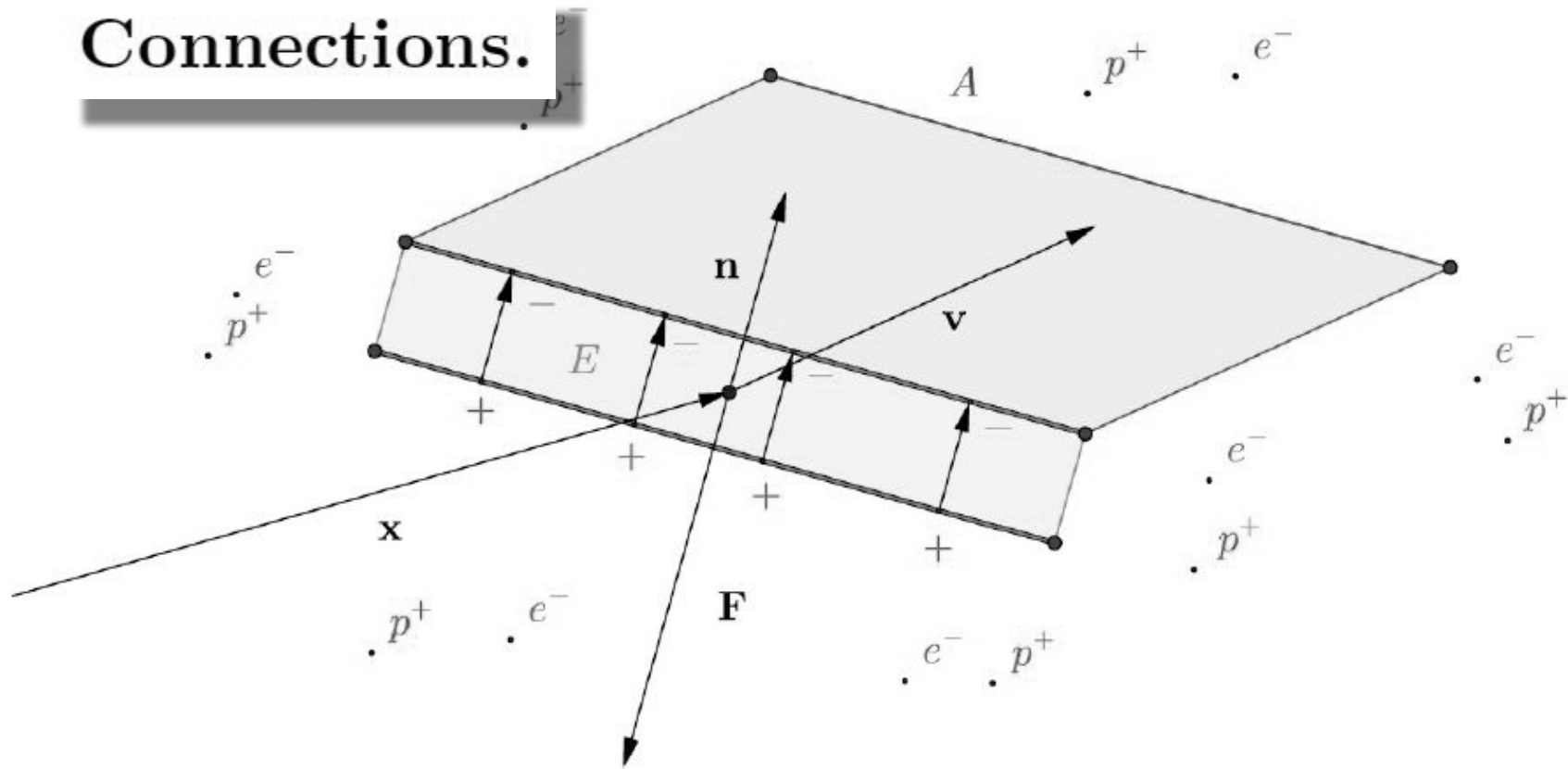
$$\ddot{\mathbf{x}} = -\frac{M}{r^3} \mathbf{x} + \frac{\sigma M p_c}{r^3} \frac{\dot{\mathbf{x}}}{|\dot{\mathbf{x}}|}.$$



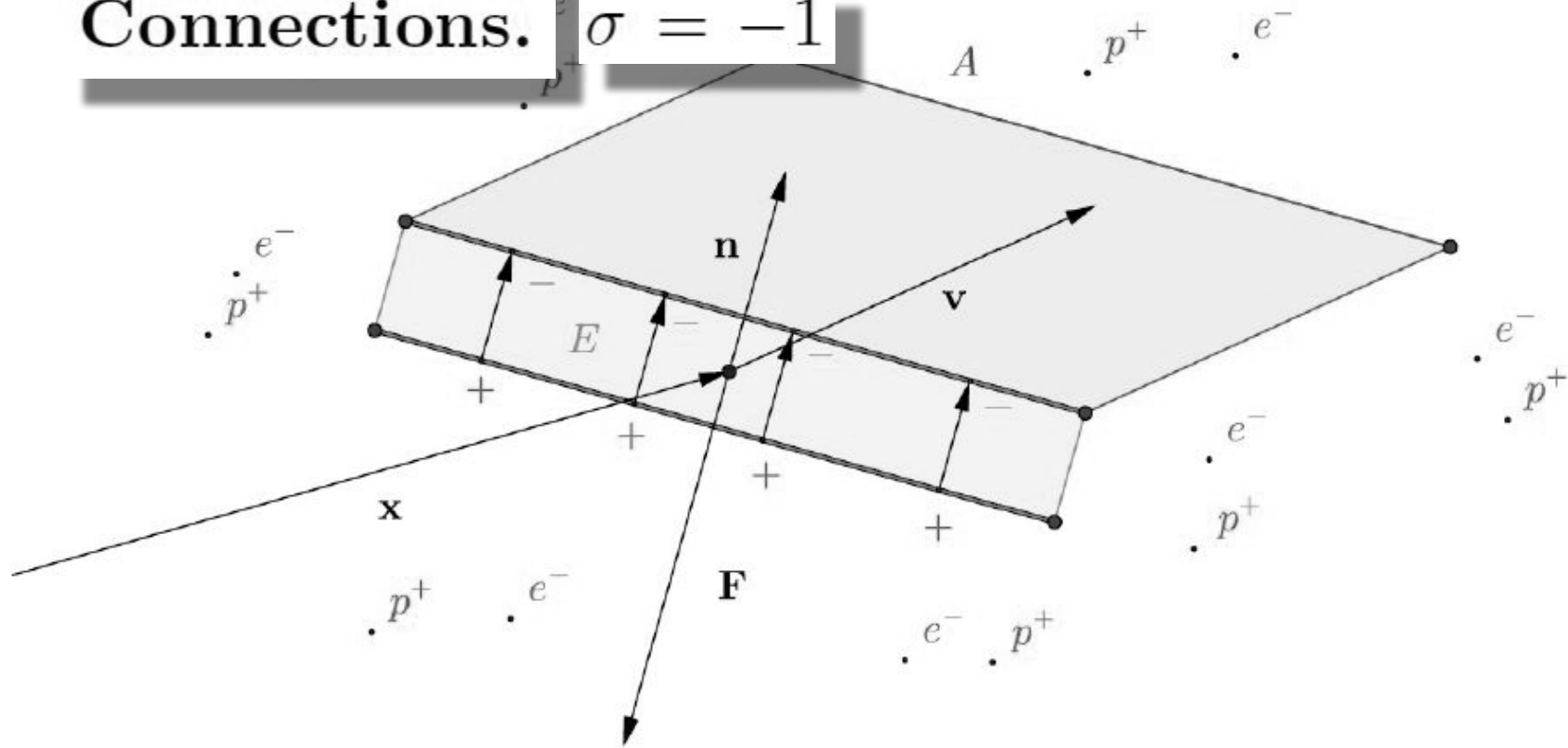
$$-\frac{L^2}{p^2} = \left(\frac{2M}{r} + c \right)^{1-\sigma}.$$

$$\frac{L^2}{p^2} = \left(\frac{2M(1-\sigma)}{r} + c \right)^{\frac{1}{1-\sigma}}.$$

Connections.



Connections. $\sigma = -1$

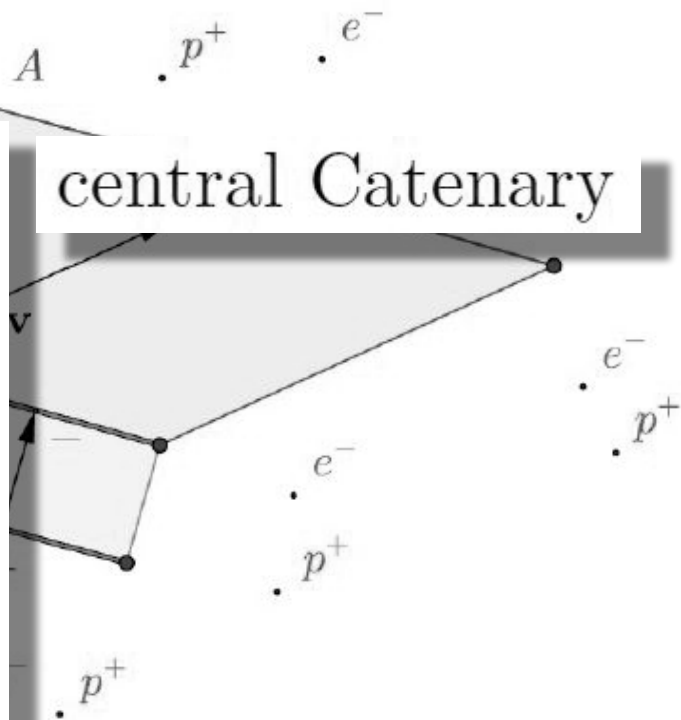


Connections. $\sigma = -1$

$$\ddot{\mathbf{x}} = -\frac{M}{r^3} \mathbf{x} + \frac{Mp}{r^3} \frac{\dot{\mathbf{x}}^\perp}{|\dot{\mathbf{x}}|},$$

$$\ddot{\mathbf{x}} = -\frac{2M}{r^3} \mathbf{x} + \frac{Mp_c}{2r^3} \frac{\dot{\mathbf{x}}}{|\dot{\mathbf{x}}|},$$

$$\ddot{\mathbf{x}} = -\frac{M}{r^3} |\dot{\mathbf{x}}| \mathbf{x}.$$

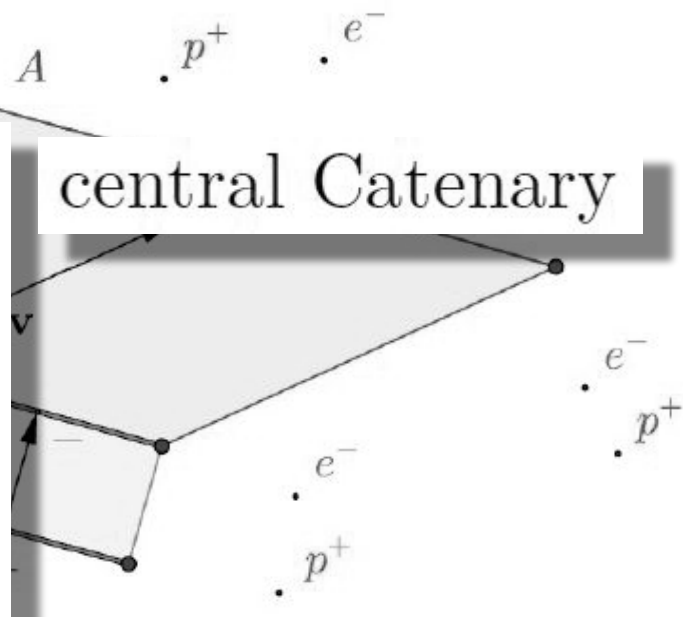


Connections. $\sigma = -1$

$$\ddot{\mathbf{x}} = -\frac{M}{r^3} \mathbf{x} + \frac{Mp}{r^3} \frac{\dot{\mathbf{x}}^\perp}{|\dot{\mathbf{x}}|},$$

$$\ddot{\mathbf{x}} = -\frac{2M}{r^3} \mathbf{x} + \frac{Mp_c}{2r^3} \frac{\dot{\mathbf{x}}}{|\dot{\mathbf{x}}|},$$

$$\ddot{\mathbf{x}} = -\frac{M}{r^3} |\dot{\mathbf{x}}| \mathbf{x}. \quad \text{Same orbits in Pedal coordinates!}$$

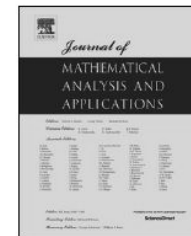




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Pedal coordinates, solar sail orbits, Dipole drive and other force problems

Petr Blaschke



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Pedal coordinates, dark Kepler, and other force problems

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THANK YOU