

**SOLITON EQUATIONS  
AND THEIR HOLOMORPHIC SOLUTIONS**

VIII School on Geometry and Physics, Białowieża, June 2019

**PLAN OF THE COURSE**

**Lecture 1. Riemann problem and soliton equations.**

**Lecture 2. Local holomorphic inverse scattering.**

**Lecture 3. The Painlevé property.**

## **Aims:**

Describe all  $(1 + 1)$ -dim soliton equations of parabolic type and ALL of their local holomorphic solutions using a local version of the inverse scattering method.

Discuss most interesting classes of solutions.

Give a CRITERION for solubility of the Cauchy problem in terms of the scattering data of the initial condition.

Prove the Painlevé property: ALL local holomorphic solutions are globally meromorphic and monodromy-free in the spatial variable.

# LECTURE 1

## RIEMANN PROBLEM AND SOLITON EQUATIONS

# 1. Examples and history

Korteweg–de Vries, nonlinear Schrödinger and Boussinesq eqs

$$(1) \quad u_t = au_{xxx} + buu_x, \quad a, b \in \mathbb{C} \setminus \{0\},$$

$$(2) \quad iu_t = au_{xx} + bu|u|^2, \quad a, b \in \mathbb{R} \setminus \{0\},$$

$$(3) \quad u_{tt} = au_{xxxx} + buu_{xx} + bu_x^2, \quad a, b \in \mathbb{C} \setminus \{0\}$$

with  $|u(x, t)|^2$  in (2) understood as  $u(x, t)\overline{u(\bar{x}, \bar{t})}$ .

(KdV) 
$$u_t = au_{xxx} + buu_x$$

describes long waves on shallow water.

The inverse scattering method as discovered by Gardner, Green, Kruskal, Miura 1967:

when the potential  $u(x, \cdot)$  evolves according to (KdV), the evolution of its scattering data

(spectral characteristics of  $L = \partial_x^2 + u(x, \cdot)$  on  $L^2(\mathbb{R}_x^1)$ ) is linear and can be integrated explicitly!

Explanation (Lax 1968): (KdV) with  $a = 1/4$ ,  $b = 3/2$  is the compatibility condition for the **auxiliary linear problem**

$$(4) \quad L\psi = \lambda\psi, \quad \psi_t = P\psi$$

where  $L := \partial_x^2 + u$  and  $P := \partial_x^3 + (3/2)u\partial_x + (3/4)u_x$ ,

i.e. equation (KdV) can be written as  $\boxed{L_t = [P, L]}$ .

$\implies$  the evolution of the operator  $L$  is its conjugation

by a  $t$ -dependent unitary operator on  $L^2(\mathbb{R}_x^1)$

$\implies$  the evolution of its spectral characteristics is simple.

$$(NLS) \quad iu_t = au_{xx} + bu|u|^2$$

describes propagation of wave packages in nonlinear dispersive media.

Zakharov and Shabat (1971) replaced the scalar second-order ODE  $L\psi = \lambda\psi$  in (4) by a first-order  $2 \times 2$ -matrix system:

$$(5) \quad E_x = UE, \quad \text{and then} \quad E_t = VE$$

where  $U(x, t, z)$  and  $V(x, t, z)$  are polynomials of degree 1 and 2 in the spectral parameter  $z \in \mathbb{C}$  related to  $\lambda$  in (4) by  $\lambda = z^2$ .

Hence (NLS) arises from the zero curvature equation

$$(6) \quad U_t - V_x + [U, V] = 0$$

(the compatibility condition of the auxiliary linear problem (5); first explicitly written and used in soliton theory by Novikov 1974).

The Boussinesq equation (3) (describing water waves that can move left or right) was similarly studied by Zakharov (1973): replace  $2 \times 2$ -matrices in (5) or the second-order operator  $L$  in (4) by  $3 \times 3$ -matrices or a third-order operator.



## 2. Zero curvature equations

LEMMA 1. *Let  $\Omega \subset \mathbb{C}_{xt}^2$  be a simply connected domain and  $U, V : \Omega \rightarrow \mathfrak{gl}(n, \mathbb{C})$  holomorphic maps. Then the system*

$$(ALP) \quad E_x = UE, \quad E_t = VE$$

*has a holomorphic solution  $E : \Omega \rightarrow GL(n, \mathbb{C})$  if and only if*

$$(ZCC) \quad U_t - V_x + [U, V] = 0 \quad \text{everywhere in } \Omega.$$

DEFINITION. A  $(1 + 1)$ -dimensional *soliton equation* is the ZCC  $U_t - V_x + [U, V] = 0$ , where  $U, V : \Omega \times \mathbb{C}P_z^1 \rightarrow \mathfrak{gl}(n, \mathbb{C})$  are rational functions of  $z \in \mathbb{C}P^1$  such that the expression  $U_t - V_x + [U, V]$  is independent of  $z$ .

Unknown functions are the entries of the  $\mathfrak{gl}(n, \mathbb{C})$ -valued coefficients of the partial fraction decompositions of  $U, V$ . Some of them can be expressed in terms of the others from the condition “ $U_t - V_x + [U, V]$  is independent of  $z$ ”.

The type of a soliton equation is determined by the lists of poles of  $U$  and  $V$  counting multiplicities. For example,

(1) the poles of  $U$  and  $V$  are single, simple and distinct  $\implies$  **hyperbolic type** (PCM, Sine-Gordon);

(2) the poles of  $U$  and  $V$  are single and coincide  $\implies$  **parabolic type** (Kdv, NLS, Boussinesq).

## Structure of soliton equations of parabolic type.

Consider the case when the common pole of  $U$  and  $V$  is  $\infty$ , so  $U$  and  $V$  are polynomials in  $z$ ,  $\deg U = 1$  and  $\deg V = m \geq 2$ . Then there is no loss of generality in assuming that

$$\begin{cases} U(x, t, z) = az + q(x, t), \\ V(x, t, z) = bz^m + r_1(x, t)z^{m-1} + \cdots + r_m(x, t), \end{cases}$$

where  $a, b \in \mathfrak{gl}(n, \mathbb{C})$  are **diagonal** matrices,  $a$  has **simple spectrum** (all eigenvalues are distinct),  $q : \Omega \rightarrow \mathfrak{gl}(n, \mathbb{C})$  is holomorphic and **off-diagonal**,  $r_1, \dots, r_m : \Omega \rightarrow \mathfrak{gl}(n, \mathbb{C})$  are holomorphic.

Claim: the condition “ $U_t - V_x + [U, V]$  is independent of  $z$ ” determines  $r_1, \dots, r_m$  as **differential polynomials**  $r_j = F_j(q)$  (i.e. polynomials in  $q$  and its derivatives with respect to  $x$ ) uniquely up to diagonal constants of integration at each step.

The functions  $F_j(q)$  satisfy the **resolvent equation**

$$\boxed{F_x = [U, F]}, \quad \text{where } U := az + q, \quad F := b + \sum_{j=1}^{\infty} \frac{F_j(q)}{z^j}$$

and we have  $U_t - V_x + [U, V] = q_t - [a, F_{m+1}(q)]$ . Hence

$$\text{ZCC takes the form } \boxed{q_t = [a, F_{m+1}(q)]}.$$

In more detail,

LEMMA 2. Fix  $a, b$  as above and any point  $x_0 \in \mathbb{C}$  and put

$\mathcal{O}(x_0) := \{\text{holomorphic } \mathfrak{gl}(n, \mathbb{C})\text{-valued germs } q(x) \text{ at } x_0\},$

$\mathcal{O}(x_0)^{od} := \{\text{all off-diagonal } q \in \mathcal{O}(x_0)\}.$

Then for every sequence  $c_1, c_2, \dots \in \mathfrak{gl}(n, \mathbb{C})$  of diagonal matrices there is a unique sequence of differential polynomials  $F_j : \mathcal{O}(x_0) \rightarrow \mathcal{O}(x_0), j = 0, 1, 2, \dots$  such that

1)  $F_0(q) \equiv b$  for all  $q \in \mathcal{O}(x_0),$

2)  $F_j(0) \equiv c_j$  for all  $j \geq 1,$

3) the formal power series  $F(q, z) := \sum_{j=0}^{\infty} F_j(q)z^{-j}$  satisfies

$$\partial_x F = [az + q, F] \quad \text{for all } q \in \mathcal{O}(x_0)^{od}.$$

**Proof** is not completely trivial since the resolvent equation

$$\begin{aligned}\partial_x D_{j-1} &= [q, N_{j-1}]_d, \\ [a, N_j] &= \partial_x N_{j-1} - [q, F_{j-1}]_{od}\end{aligned}$$

(where  $j = 0, 1, 2, \dots$ ,  $F_{-1} := 0$ ,  $D_j := (F_j)_d$ ,  $N_j := (F_j)_{od}$ ) determines  $F_j(q)$  only as integro-differential polynomials in  $q$  (since  $a$  has simple spectrum, the operator  $X \mapsto [a, X]$  is invertible on the space of off-diagonal matrices in  $\mathfrak{gl}(n, \mathbb{C})$ ). Use the equalities  $\partial_x F^k = [U, F^k] \implies \partial_x \operatorname{tr} F^k = 0$  to get another formula for  $D_j$ , solving a linear system.  $\square$

LEMMA 3. Fix  $a, b$  as above. Then

$U_t - V_x + [U, V]$  is independent of  $z \iff r_j = F_j(q) (j = 1, \dots, m)$

for some sequence  $c_1(t), \dots, c_m(t)$  of diagonal matrices holomorphically depending on  $t$  in the projection of  $\Omega$  to the  $t$ -axis.

In this case, the ZCC  $\boxed{U_t - V_x + [U, V] = 0}$  with  $U = az + q$  and  $V = az^m + F_1(q)z^{m-1} + \dots + F_m(q)$  takes the form

$$(Eq_m) \quad q_t = [a, F_{m+1}(q)],$$

where  $q(x, t)$  is the unknown off-diagonal  $\mathfrak{gl}(n, \mathbb{C})$ -valued germ at the point  $(x_0, t_0) \in \mathbb{C}^2$ .

**Examples.** (almost always  $b = a$ ,  $c_1 = c_2 = \dots = 0$ )

1) The hierarchy of the heat equation:

$$a = \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix}, \quad q(x, t) = \begin{pmatrix} 0 & u(x, t) \\ 0 & 0 \end{pmatrix} \implies$$
$$\implies (\text{Eq}_m) \text{ takes the form } \boxed{\partial_t u = \partial_x^m u}.$$

2) The Korteweg–de Vries equation:

$$a = \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix}, \quad q(x, t) = \begin{pmatrix} 0 & u(x, t) \\ 1 & 0 \end{pmatrix} \implies$$
$$\implies (\text{Eq}_3) \text{ takes the form } \boxed{u_t = u_{xxx} - 6uu_x}.$$



3) The nonlinear Schrödinger equation:

$$a = \begin{pmatrix} -i/2 & 0 \\ 0 & i/2 \end{pmatrix}, \quad q(x, t) = \begin{pmatrix} 0 & u(x, t) \\ -u(\bar{x}, \bar{t}) & 0 \end{pmatrix} \implies$$
$$\implies \text{(Eq}_2\text{)} \text{ takes the form } \boxed{iu_t = -u_{xx} - 2u|u|^2}.$$

4) The modified Korteweg–de Vries equation ( $C := (c_2)_{11} - (c_2)_{22}$ ):

$$a = \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix}, \quad q(x, t) = \begin{pmatrix} 0 & u(x, t) \\ u(x, t) & 0 \end{pmatrix} \implies$$
$$\implies \text{(Eq}_3\text{)} \text{ takes the form } \boxed{u_t = u_{xxx} + (6u^2 + C)u_x}.$$

### 3. Riemann problem and ZS dressing

*Riemann problem:* Let  $D_+, D_- \subset \mathbb{C}P_z^1$  be disjoint open disks with  $\overline{D}_+ \cup \overline{D}_- = \mathbb{C}P^1$ . A continuous function  $\gamma : \Gamma \rightarrow \text{GL}(n, \mathbb{C})$  on the circle  $\Gamma := \overline{D}_+ \cap \overline{D}_-$  is said to be **left-factorable** (resp. **right-factorable**) if there are continuous functions  $\gamma_{\pm} : \overline{D}_{\pm} \rightarrow \text{GL}(n, \mathbb{C})$ , holomorphic on  $D_{\pm}$  and satisfying  $\boxed{\gamma = \gamma_+ \gamma_-^{-1}}$  on  $\Gamma$  (resp.  $\boxed{\gamma = \gamma_-^{-1} \gamma_+}$  on  $\Gamma$ ).

We regard  $\gamma$  as **data** of the Riemann problem, and the pair  $(\gamma_+, \gamma_-)$  as a **solution**. When a solution exists, it is unique up to right (resp. left) multiplication by  $A \in \text{GL}(n, \mathbb{C})$ .

*Zakharov–Shabat dressing method:* Let  $(U_0, V_0)$  be a holomorphic solution of ZCC on  $\Omega \subset \mathbb{C}_{xt}^2$ ,  $E_0$  a holomorphic solution of ALP on  $\Omega$ ,  $E_0(x_0, t_0) = I$ , and  $g : \Gamma \rightarrow \text{GL}(n, \mathbb{C})$  right-factorable, where  $\Gamma = \overline{D}_+ \cap \overline{D}_-$  does not pass through the poles of  $U_0, V_0$ .

For every  $(x, t) \in \Omega$  we pose the Riemann problem of finding continuous  $\theta_{\pm} : \overline{D}_{\pm} \rightarrow \text{GL}(n, \mathbb{C})$  holomorphic on  $D_{\pm}$  with

$$E_0(x, t, z)g(z)E_0^{-1}(x, t, z) = \theta_-^{-1}(x, t, z)\theta_+(x, t, z), \quad z \in \Gamma.$$

A solution  $\theta_{\pm}$  exists in a neighbourhood of  $(x_0, t_0)$  and, actually, in  $\Omega$  except maybe a pole along a complex curve.

For uniqueness require  $\theta_-(x, t, z_0) = I$  for all  $(x, t)$  and some  $z_0$ . Then the pair  $(U_1, V_1)$  defined by the formulae

$$U_1(x, t, z) = \begin{cases} (\theta_+)_x \theta_+^{-1} + \theta_+ U_0 \theta_+^{-1}, & z \in \overline{D}_+, \\ (\theta_-)_x \theta_-^{-1} + \theta_- U_0 \theta_-^{-1}, & z \in \overline{D}_- \end{cases}$$

and similarly for  $V_1(x, t, z)$  with  $U_0 \longrightarrow V_0$  and  $\partial_x \longrightarrow \partial_t$  is a meromorphic solution of ZCC on  $\Omega$  with **the same divisors of poles in  $z$**  for  $U_1, V_1$  and  $U_0, V_0$ .

Proofs will be given in a more concrete context below.

**DEFINITION.** The solution  $(U_1, V_1)$  is said to be obtained by **dressing the solution  $(U_0, V_0)$  by means of  $g$** .

## A limiting case of dressing for SEPT.

For soliton equations of parabolic type, the divisors of poles of  $U$  and  $V$  are  $\infty$  and  $m\infty$  respectively. Hence it is natural to shrink the disk  $D_- = \{|z| > R\} \cup \{\infty\}$  to a single point  $\infty$  and expand  $D_+ = \{|z| < R\}$  to the whole plane  $\mathbb{C}$  as  $R \rightarrow +\infty$ . The dressing function  $g(z)$  becomes an element of the set

$$\mathcal{D} := \{\text{holom GL}(n, \mathbb{C})\text{-valued germs } f(z) \text{ at } \infty \text{ with } f(\infty) = I\}$$

We will dress the zero solution  $(U_0, V_0) = (0, 0)$  of ZCC or, equivalently, the solution  $q(x, t) \equiv 0$  of equation  $(E_{q_m})$ , by the invertible holomorphic germ  $f^{-1}(z)$  for every  $f \in \mathcal{D}$ .

**THEOREM 1.** *Suppose that  $a, b, c_1, c_2, \dots \in \mathfrak{gl}(n, \mathbb{C})$  are diagonal matrices and  $a$  has simple spectrum. Fix an integer  $m \geq 2$  and a point  $(x_0, t_0) \in \mathbb{C}^2$ . For every  $f \in \mathcal{D}$  let  $\Omega(f)$  be the set of all  $(x, t) \in \mathbb{C}^2$  such that the function*

$$\gamma(x, t, z) := \exp\{az(x-x_0) + (bz^m + c_1z^{m-1} + \dots + c_m)(t-t_0)\} f^{-1}(z)$$

*is right-factorable on some (and then any) circle  $\{|z|=R\}$ ,  $R_0 < R < +\infty$ . Then  $\Omega(f) \subset \mathbb{C}^2$  contains a neighbourhood of  $(x_0, t_0)$ . For every point  $(x, t) \in \Omega(f)$  let  $(\gamma_+(x, t, z), \gamma_-(x, t, z))$  be the solution of the Riemann problem*

$$(7) \quad \gamma(x, t, z) = \gamma_-^{-1}(x, t, z)\gamma_+(x, t, z), \quad R_0 < |z| < +\infty$$

with normalization  $\gamma_-(x, t, \infty) = I$ . Put

$$(8) \quad q(x, t) := \lim_{z \rightarrow \infty} z[\gamma_-(x, t, z) - I, a].$$

Then  $q : \Omega(f) \rightarrow \mathfrak{gl}(n, \mathbb{C})$  is off-diagonal, holomorphic at  $(x_0, t_0)$  and satisfies the soliton equation (Eq <sub>$q_m$</sub> )

$$(9) \quad q_t = [a, F_{m+1}(q)] \quad \text{in a neighbourhood of } (x_0, t_0),$$

where  $F_j : \mathcal{O}(x_0) \rightarrow \mathcal{O}(x_0)$  ( $j = 0, 1, 2, \dots$ ) is the sequence of differential polynomials determined by the sequence  $a, b, c_1, \dots$  by Lemma 2.

REMARK. In what follows we denote this  $q(x, t)$  by  $q_f(x, t)$ .

**Proof.** 1) The Riemann problem  $\gamma = \gamma_-^{-1}\gamma_+$  is equivalent (for every  $R \geq R_0$ ) to a linear equation  $A\xi = \eta$  on the Banach space  $E$  of all  $\mathfrak{gl}(n, \mathbb{C})$ -valued functions holomorphic for  $|z| > R$ , continuous for  $|z| \geq R$  and vanishing at  $z = \infty$ . (Here  $\eta := -P\gamma$  and  $A\xi := P(\xi\gamma)$ , where  $P$  is the operator of taking the negative part of a Laurent series. The solutions  $\gamma_{\pm}$  are recovered by the formulae  $\gamma_- = I + \xi$ ,  $\gamma_+ = (I + \xi)\gamma_-$ .) The operator  $A$  and the vector  $\eta$  depend holomorphically on  $(x, t) \in \mathbb{C}^2$ , and  $A = \text{Id}$  at  $(x, t) = (x_0, t_0)$ . Hence  $A$  is invertible in a neighbourhood of  $(x_0, t_0)$  and the solution  $\xi$  is holomorphic there. Thus  $\Omega(f)$  contains a neighbourhood of  $(x_0, t_0)$  and  $\gamma_{\pm}(x, t)$  are holomorphic there.



2) Claim: the function  $\gamma_{+x}\gamma_+^{-1} - az$  is independent of  $z$  and equal to  $q(x, t)$ , so that for all  $(x, t)$  near  $(x_0, t_0)$  and all  $z \in \mathbb{C}$  we have

$$(10) \quad \gamma_{+x} = U(x, t, z)\gamma_+, \quad \text{where} \quad U(x, t, z) := az + q(x, t).$$

Indeed, write  $\gamma_+(x, t, z) = \gamma_-(x, t, z)E_0(x, t, z)f^{-1}(z)$  (where  $E_0(x, t, z) := \exp\{az(x - x_0) + (bz^j + c_1z^{j-1} + \dots + c_j)(t - t_0)\}$ ) and differentiate with respect to  $x$ :

$$\begin{aligned} \gamma_{+x}\gamma_+^{-1} &= (\gamma_-E_0f^{-1})_x(\gamma_-E_0f^{-1})^{-1} = \\ & \text{(since } f \text{ is independent of } x) = (\gamma_-E_0)_x(\gamma_-E_0)^{-1} = \\ & (\gamma_{-x} + \gamma_-az)E_0(\gamma_-E_0)^{-1} = \gamma_{-x}\gamma_-^{-1} + z \cdot \gamma_-a\gamma_-^{-1}. \end{aligned}$$

As Laurent series in  $z$ , the left- and right-hand sides of

$$\gamma_{+x}\gamma_{+}^{-1} = \gamma_{-x}\gamma_{-}^{-1} + z \cdot \gamma_{-} a \gamma_{-}^{-1}$$

contain only powers  $\geq 0$  and  $\leq 1$  respectively. Hence both are polynomials of degree  $\leq 1$  in  $z$ :

$$\gamma_{+x}\gamma_{+}^{-1} = \{z\gamma_{-} a \gamma_{-}^{-1}\}_{+},$$

where  $\{\cdot\}_{+}$  is the “non-negative part” of a Laurent series:

if  $X = \sum_{n=-\infty}^{\infty} X_n z^n$ , then  $X_{+} = \sum_{n=0}^{\infty} X_n z^n$ .

A calculation gives  $\{z\gamma_{-}(x, t, z)a\gamma_{-}^{-1}(x, t, z)\}_{+} = az + q(x, t)$ , where  $q(x, t)$  is defined by (8). This proves (10).

3) Repeating part 2 with  $x$  replaced by  $t$ , we have

$$(11) \quad \gamma_{+t}\gamma_{+}^{-1} = \{z^m F(x, t, z)\}_+,$$

where  $F(x, t, z) := \gamma_{-}(x, t, z)(b+c_1z^{-1}+\dots+c_mz^{-m})\gamma_{-}(x, t, z)^{-1}$ .  
 Claim: for every fixed  $t$  the function  $F(x, t, z)$  satisfies the resolvent equation  $\boxed{F_x = [U, F]}$  near  $x_0$ , where  $U(x, t, z) = az + q(x, t)$ . Indeed, write  $F(x, t, z) = \gamma_{-}(x, t, z)\Phi(t, z)\gamma_{-}^{-1}(x, t, z)$ , where  $\Phi(t, z)$  is diagonal and independent of  $x$ . Differentiate  $F\gamma_{-} = \gamma_{-}\Phi$  with respect to  $x$  and multiply by  $\gamma_{-}^{-1}$ . We get  $F_x + F\gamma_{-x}\gamma_{-}^{-1} = \gamma_{-x}\Phi\gamma_{-}^{-1}$ , i.e.  $F_x = [\gamma_{-x}\gamma_{-}^{-1}, F]$ . Here  $\gamma_{-x}\gamma_{-}^{-1}$  may be replaced by  $U$  since  $U - \gamma_{-x}\gamma_{-}^{-1} = \gamma_{-}az\gamma_{-}^{-1}$  commutes with  $F = \gamma_{-}\Phi\gamma_{-}^{-1}$  (the matrices  $az$  and  $\Phi$  are diagonal). This proves that  $F_x = [U, F]$ .

By (the proof of) the uniqueness in Lemma 2, it follows that

$$(12) \quad F(x, t, z) = \sum_{l=0}^{\infty} F_l^{(a, b, c'_1(t), \dots, c'_l(t))} (q)(x, t) z^{-l}$$

for some sequence  $c'_1(t), c'_2(t), \dots$  of diagonal matrices depending only on  $t$ . For all  $k = 1, 2, \dots$  and all  $z$  near  $\infty$  we have

$$\operatorname{tr} F(x, t, z)^k = \begin{cases} \operatorname{tr}(b + c'_1(t)z^{-1} + c'_2(t)z^{-2} + \dots)^k, \\ \operatorname{tr}(b + c_1z^{-1} + \dots + c_jz^{-j})^k, \end{cases}$$

(first by the proof of Lemma 2, second by the definition of  $F$  after (11)). Since all matrices on the right are diagonal, we conclude

that  $c'_l(t) \equiv c_l$  for  $l = 1, \dots, m$ . Hence the differential polynomials in (12) coincide with the differential polynomials  $F_l$  determined by  $a, b, c_1, \dots$  by Lemma 2. Thus (11) and (12) yield

$$(13) \quad \gamma_{+t} = V(x, t, z)\gamma_+,$$

where  $V(x, t, z) := \sum_{j=0}^m F_{m-j}(q)(x, t)z^j$ .

4) Differentiate (13) with respect to  $x$ , (10) with respect to  $t$ , equate the results and divide by the invertible matrix  $\gamma_+$ . This gives the ZCC for  $U, V$  defined above, that is, by Lemma 3, the soliton equation (9) for  $q(x, t)$ .  $\square$

## GEOMETRICAL MEANING OF SOLUTIONS OF THE RP.

$\boxed{\gamma_+(x, t)}$  is a parallel frame field with respect to the flat connection  $\nabla(q) := d - U(q) dx - V(q) dt$ ,

$$E_x = UE, \quad E_t = VE, \quad \text{where } E = \gamma_+,$$

and  $\boxed{\gamma_-(x, t)}$  is a gauge transformation of the trivial flat connection  $\nabla(0) = d - az dx - bz^m dt$  to the connection  $\nabla(q)$ ,

$$dm = \{U(q) dx + V(q) dt\}m - m\{U(0) dx + V(0) dy\},$$

where  $m = \gamma_-$ ,  $U(q) = az + q$ ,  
 $V(q) = bz^m + F_1(q)z^{m-1} + \dots + F_m(q)$ .

LEMMA 4 (NON-UNIQUENESS OF A GERM  $f \in \mathcal{D}$  AS THE “SCATTERING DATA” OF THE “POTENTIAL”  $q_f \in \mathcal{O}(x_0)^{od}$ ).  
*Functions  $f, g \in \mathcal{D}$  determine the same solution  $q_f(x, t) = q_g(x, t)$  of  $\text{Eq}_m$  near  $(x_0, t_0) \in \mathbb{C}^2 \iff$  the function  $f^{-1}g \in \mathcal{D}$  is diagonal  $\iff q_f(x, t_0) = q_g(x, t_0)$  near  $x_0 \in \mathbb{C}$ .*

Why should the map  $f \mapsto q_f$  be regarded as the inverse scattering transform?

Because it is so, under appropriate reduction of non-uniqueness, whenever the rapidly decaying or finite-gap versions apply.

Non-uniqueness is something useful (see “Addition of a soliton”).

## 4. Examples of local inverse scattering transforms

### A. Upper-triangular case and the Laplace transform.

Let  $u : [0, +\infty) \rightarrow \mathbb{C}$  be a locally integrable function with  $|u(x)| \leq Ae^{Bx}$  for all  $x \geq 0$  and some  $A, B \in \mathbb{R}$ .

The *Laplace transform* of  $u$  is

$$(LAP) \quad Lu(z) := \int_0^{\infty} e^{-zx} u(x) dx.$$

The function  $Lu(z)$  is holomorphic for  $\Re z > B$  and tends to 0 as  $\Re z \rightarrow +\infty$ . If  $Lu_1 = Lu_2$ , then  $u_1 = u_2$ . The function  $Lu(z)$  is rational (and vanishes at  $z = \infty$ )  $\iff u(x)$  is an exponential



polynomial, that is a finite linear combination of  $x^k e^{cx}$  with integer  $k \geq 0$  and complex  $c$ .

More generally,  $Lu(z)$  is holomorphic in a neighbourhood of  $\infty$  (and vanishes at  $z = \infty$ )  $\iff u$  is an entire function of exponential type, i.e.  $u \in \mathcal{O}(\mathbb{C}^1)$  and there are  $A, B > 0$  such that  $|u(x)| \leq Ae^{B|x|}$  for all  $x \in \mathbb{C}$ . Then the inverse transform  $u = B\varphi$  is called the *Borel transform* and is given by the formula

$$\text{(BOR)} \quad \varphi(z) = \sum_{j=1}^{\infty} \frac{\varphi_j}{z^j} \quad \implies \quad B\varphi(x) = \sum_{k=0}^{\infty} \varphi_{k+1} \frac{x^k}{k!}, \quad x \in \mathbb{C}.$$

LEMMA 5. Fix a diagonal matrix  $a = \text{diag}(a_{11}, a_{22})$  with  $\alpha := a_{11} - a_{22} \neq 0$  and put  $x_0 = 0$ ,  $E_0(x, z) := \exp(azx)$ . For every germ  $f \in \mathcal{D}$  we regard the solution  $q_f : \Omega(f) \rightarrow \mathfrak{gl}(2, \mathbb{C})$  of  $\text{Eq}_m$  with  $b = c_1 = c_2 = \dots = 0$  as a function of  $x$  only. Then:

(A)  $f$  is upper-triangular for  $|z| > R_0 \iff q_f(x)$  is upper-triangular near  $x_0 = 0$ .

(B) If  $q \in \mathcal{O}(x_0)$  is upper-triangular and  $q = q_f$  for some  $f \in \mathcal{D}$ , then there is a unique upper-triangular  $f \in \mathcal{D}$  such that  $q = q_f$  and  $f_{11} = f_{22} \equiv 1$ . Define  $\mathbb{C}$ -valued functions  $\varphi(z)$  and  $u(x)$  by putting

$$f(z) = \begin{pmatrix} 1 & \varphi(z) \\ 0 & 1 \end{pmatrix}, \quad q(x) = q_f(x) = \begin{pmatrix} 0 & u(x) \\ 0 & 0 \end{pmatrix}.$$

Then the bijection  $f \leftrightarrow q$  corresponds to the following relation between  $\varphi(z)$  and  $u(x)$ :

$$\text{if } \varphi(z) = \sum_{j=1}^{\infty} \frac{\varphi_j}{z^j}, \quad \text{then } u(x) = - \sum_{k=0}^{\infty} \frac{\alpha^{k+1} x^k \varphi_{k+1}}{k!}.$$

Thus  $u(x) = -\alpha B\varphi(\alpha x)$ , where  $B\varphi$  is the Borel transform (BOR) of  $\varphi$ . In particular,  $u(x)$  is an entire function of exponential type. Conversely, any off-diagonal upper-triangular map  $q : \mathbb{C}_x^1 \rightarrow \mathfrak{gl}(n, \mathbb{C})$  with  $n = 2$  whose only non-zero entry  $q_{12}(x)$  is an entire function of exponential type, can be written in the form  $q = q_f$  for some  $f \in \mathcal{D}$ .

## B. Constant potentials.

In the upper-triangular case, the maps  $f \mapsto q_f$  and  $q_f \mapsto f$  appear to be linear (after natural normalization). This is not the case in general, already for constant potentials (the simplest case of finite-gap potentials).

LEMMA 6. *Let  $a \in \mathfrak{gl}(n, \mathbb{C})$  be a diagonal matrix with simple spectrum and  $C \in \mathfrak{gl}(n, \mathbb{C})$  any off-diagonal matrix. Then there is a function  $f \in \mathcal{D}$  such that  $q_f(x, t_0) = C$  for all  $x \in \mathbb{C}^1$ . (The choice of  $b, c_1, \dots$  is irrelevant).*

**Proof** The matrix  $a + Cz^{-1}$  is holomorphic in  $z$  and equals  $a$  at  $z = \infty$ . Hence, for all  $z$  in a neighbourhood of  $\infty$ , its eigenvalues are distinct and their eigenspaces depend holomorphically on  $z$ . Thus there is an  $f \in \mathcal{D}$  such that the function

$$r(z) := f^{-1}(z)(a + Cz^{-1})f(z)$$

is *diagonal* and holomorphic in a neighbourhood of  $\infty$ . Here the columns of  $f(z)$  form a basis of eigenvectors of  $a + Cz^{-1}$ , which is uniquely determined by the condition that  $f$  is holomorphic and  $f(\infty) = I$ . Substituting the Laurent expansions

$$f(z) = I + f_1 z^{-1} + \dots \quad \text{and} \quad r(z) = r_0 + r_{-1} z^{-1} + \dots$$

into the definition of  $r(z)$ , we get  $r_0 = a$  and  $r_{-1} = C + [a, f_{-1}]$ . But the left-hand side of the last equality is diagonal and the right-hand side is off-diagonal. Hence  $r_{-1} = 0$ . Thus the diagonal function  $az - zr(z)$  vanishes at  $z = \infty$ . This means that the function  $z \mapsto e^{(az - zr(z))x}$  belongs to  $\mathcal{D}$  for every  $x \in \mathbb{C}$ . Since the matrices  $azx$  and  $zr(z)x$  are diagonal, we have

$$e^{azx} f^{-1}(z) = e^{(az - zr(z))x} f^{-1}(z) \cdot f(z) e^{zr(z)x} f^{-1}(z)$$

for all  $x \in \mathbb{C}$  and  $|z| > R$ . The first factor on the right belongs to  $\mathcal{D}$ , and the second is equal to  $e^{(az+C)x}$ . Thus the Riemann problem with  $x_0 = 0$  and  $t = t_0$  is solved for all  $x \in \mathbb{C}$ , and its solution involves  $\gamma_+(x, t_0, z) = e^{(az+C)x}$ . It follows that  $q_f(x, t_0) \equiv C$ .  $\square$

### C. Blaschke factors and addition of a soliton.

For any  $\alpha, \beta \in \mathbb{C}$  and any projection  $P : \mathbb{C}^n \rightarrow \mathbb{C}^n$  (i.e. a linear operator with  $P^2 = P$ ) we put

$$B_{\alpha\beta P}(z) := I + \frac{\beta - \alpha}{z - \beta} P = \mu P + (I - P), \quad \mu := \mu(z) = \frac{z - \alpha}{z - \beta}.$$

For any vector subspaces  $A, B$  of  $\mathbb{C}^n$  with  $A \oplus B = \mathbb{C}^n$  there is a unique projection  $P$  such that  $A = \text{im } P$  and  $B = \text{ker } P$ . It is called the *projection onto  $A$  along  $B$* . When  $A, B$  are regarded as “coordinate axes” in  $\mathbb{C}^n$ , the operator  $B_{\alpha\beta P}(z)$  multiplies all vectors of the first axis by  $\mu(z)$  and leaves all vectors of the second axis fixed. The functions  $B_{\alpha\beta P}(z)$  are called *Blaschke factors*.

LEMMA 7. Suppose that  $E : \mathbb{C} \rightarrow \text{GL}(n, \mathbb{C})$  is an entire function,  $\alpha, \beta \in \mathbb{C}$  and  $P : \mathbb{C}^n \rightarrow \mathbb{C}^n$  is the projection onto  $A \subset \mathbb{C}^n$  along  $B \subset \mathbb{C}^n$ . Then  $E(z)B_{\alpha\beta P}^{-1}(z)$  is right-factorable  $\iff$  the subspaces  $E(\alpha)A$  and  $E(\beta)B$  are transversal:

$$E(\alpha)A \cap E(\beta)B = \{0\}.$$

If this condition holds, then the solution  $(E_1, f_1)$  of the Riemann problem  $EB_{\alpha\beta P}^{-1} = f_1^{-1}E_1$  is given by the formula

$$f_1(z) = B_{\alpha\beta Q}(z),$$

where  $Q$  is the projection to  $E(\alpha)A$  along  $E(\beta)B$ .



Let  $q_f(x, t)$  be obtained from  $f \in \mathcal{D}$  by Theorem 1. Given any  $\alpha, \beta \in \mathbb{C}$  and any transversal subspaces  $A, B \subset \mathbb{C}^n$ , we put  $h := B_{\alpha\beta} P f$ , where  $P$  is the projector to  $A$  along  $B$  and say that the solution  $q_h(x, t)$  of  $\mathbb{E}q_m$  is obtained from the solution  $q_f(x, t)$  by *adding a soliton*. We claim that

$$(AS) \quad q_h(x, t) = q_f(x, t) + (\beta - \alpha)[P_f(x, t), a],$$

where  $P_f(x, t)$  is the projector to  $\gamma_+^f(x, t, \alpha)A$  along  $\gamma_+^f(x, t, \beta)B$ . Indeed, suppose that the subspaces  $\gamma_+^f(x, t, \alpha)A$  and  $\gamma_+^f(x, t, \beta)B$  are transversal for some point  $(x, t) \in \Omega(f)$ . Put  $E_0(x, t, z) := \exp\{az(x - x_0) + (bz^j + c_1z^{j-1} + \dots + c_j)(t - t_0)\}$ . By Lemma 7,

the expression

$$\begin{aligned} E_0(x, t, z)h^{-1}(z) &= E_0(x, t, z)f^{-1}(z)B_{\alpha\beta P}^{-1}(z) = \\ &= (\gamma_-^f)^{-1}(x, t, z)\gamma_+^f(x, t, z)B_{\alpha\beta P}^{-1}(z) \end{aligned}$$

takes the form  $(\gamma_-^f)^{-1}(x, t, z)B_{\alpha\beta P_f(x,t)}^{-1}(z)E_1(x, t, z)$  for some invertible entire function  $E_1(x, t, \cdot)$ . Hence  $(x, t) \in \Omega(h)$  and

$$\gamma_-^h(x, t, z) = B_{\alpha\beta P_f(x,t)}(z)\gamma_-^f(x, t, z)$$

for all  $z$  near  $\infty$ . Comparing the Laurent coefficients for  $|z| > R_0$ , we obtain (AS).